UNIVERSITI TEKNOLOGI MALAYSIA
BORANG PENGESAHAN
LAPORAN AKHIR PENYELIDIKAN

TAJUK PROJEK: DEVELOPMENT OF A SOIL EROSION MODELING AND PREDICTION PACKAGE FOR EIA USING GIS PRIME MEREDIAN.

Saya _____TAHER BIN BUYONG______

(HURUF BESAR)

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DEVELOPMENT OF A SOIL EROSION MODELING AND PREDICTION PACKAGE FOR ENVIRONMENTAL IMPACT ASSESSMENT USING GIS PRIME MERIDIAN

(PEMBANGUNAN PAKEJ PEMODELAN DAN PERAMALAN HAKISAN TANAH UNTUK PENILAIAN KESAN ALAM SEKITAR MENGGUNAKAN PRIME MERIDIAN GIS)

TAHER BUYONG
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PUSAT PENGURAN PENYELIDIKAN
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ABSTRACT

A number of soil erosion models have been developed to predict and characterize the movement of soil. These models provide an understanding of the dynamics of soil and can be used to evaluate the effectiveness of land management practices. Nevertheless, modellers faced some major problems. They are the inability to efficiently handle, manipulate and manage large volumes of model parameters. However, recent developments in Geographic Information Systems (GIS) provide the opportunities and tools to spatially organize and effectively manage data for the modelling. Thus, this research aims to develop an interactive soil erosion modelling and prediction system within a GIS environment. Prime Meridian GIS’ Spatial Database Engine by Essential Planning System Pte. Ltd. (EPS), will be the core of the designed system. This system is designed to use the universal soil loss equation and the overlay modelling technique to generate the soil erosion risk map. The goal of developing the system is to provide a spatial decision support tool in environmental impact assessment as required by the Department of Environment, Ministry of Science Technology and Environment.
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CHAPTER ONE

BACKGROUND

1.1 Introduction

Environmental Impact Assessment (EIA) is a process to evaluate, predict and to report both the positive and negative effects of a development project. It also strives and perseveres to find ways to deal with the environmental problems. Needless to say that manual analysis of the raw data for EIA is extremely tedious and time consuming especially in analysis which involves mathematical modelling and cartographic map presentation. Consequently, the mobilizations of developmental projects will be hampered. By utilizing GIS as a tool for analysis, it is hoped that EIA analysis will be faster, efficient and more systematic.

As most EIA projects require erosion analysis, thus, the development of a Soil Erosion Modelling and Prediction Package using Prime Meridian Geographic Information System’s Spatial Database Engine is explored in this research project. The concept of modelling and prediction of soil loss at a regional scale is based on the widely known Universal Soil Loss Equation (USLE). The results of the experiment will be presented at the end of this study in a form of soil erosion risk map. This erosion analysis system will definitely improve the proficiency of EIA analysis and more importantly in generating the soil erosion risk map with minimum cost and time.
1.2 Problem Statement

Under the Environmental Quality Act, 1974 (Amendment) 1985, most developments require environmental impact assessments to be conducted and have the results presented in the form of reports. Handling environmental data manually is almost impossible, what more if analysis is needed. Thus, in the area of soil erosion assessment and analysis, there exists a few problems:

- A demand for the generation of soil erosion risk maps for Environmental Impact Assessment in view of the influx of the Malaysia’s development.
- The need for soil erosion risk maps to be produced in a very fast and yet economic manner without losing its information’s quality.
- Manually assessing and analyzing the environmental data for the production of the erosion risk map is not feasible.

Therefore, a GIS Soil Erosion Modelling and Prediction will certainly be able to solve the problems above.

1.3 Study Area

Langkawi Island, Kedah Darulaman, situated at approximately 180000.000mE to 225000.000mE and 675000.000mN to 720000.000mN in the Rectified Skew Orthomorphic coordinate system has been selected as the sample test site for experimenting this prototype erosion analysis system (see Figure 1.1). This island was chosen in view of the availability of the parametric data needed by the modelling equations.
Figure 1.1
Map showing location of the study area.
1.4 Research Objectives

The main objectives of this research are:

- To develop an application software for soil erosion loss analysis using Prime Meridian GIS’ Spatial Database Engine (SDE).
- To generate a Soil Erosion Risk Map using the prototype software.

1.5 The Scope of The Study

The scope of the research encompasses Visual Basic (VB) programming procedures to develop a soil erosion modelling and prediction software using the EPS Prime Meridian’s Spatial Database Engine. Visual Basic programming language will interface with the Spatial Structured Query language (S3QL) of the SDE to generate the soil erosion risk maps through the principle of the Universal Soil Loss Equation. Figure 1.2 illustrates the scope of the work involved.
Figure 1.2
Figure depicting the scope of work
1.6 Overview of Previous Studies

The threat from soil erosions and the importance of erosion awareness were highlighted by Olson (1981). Thus, there is a need for erosion modelling to assess and to understand the impact of erosion towards the soil. Modelling of the dynamics of soil leads to the conception of a number of modelling equations.

Morgan (1986) conveyed the details of a few techniques used to enable soil erosion to be assessed. Three methods of soil erosion modelling are introduced here. They are:

- The Universal Soil Loss Equation

This method was introduced by Wishmeier and Smith in 1962. This soil loss prediction method needs five parameters before results could be produced. The mathematical model for this method is described as:

\[ E = R \cdot L \cdot S \cdot K \cdot C \cdot P \]

with the following notation

- \( R \) : Rainfall Erosivity Index
- \( K \) : Soil Erodibility Index
- \( L \) : Length of Slope
- \( S \) : Slope Steepness
- \( C \) : Conservation Practice
- \( P \) : Crop Management

This model is the most common model used in many regions of the world.
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- The Stehlik Method

This method was developed by Stehlik in 1975 for predicting the annual rate of soil erosion in Czechoslovakia. It uses the equation:

$$X = D.G.P.L.S.O$$

where the notation of each factor represents:

D: The climatic factor

G: The petrologic factor and assesses the rock type according to the permeability of its weathered debris.

P: Erodibility of the soil based on the percentage of particles smaller than 0.1mm in size and the organic content.

S: Slope steepness ($S = 0.24 + 0.106s + 0.0028s^2$) where $s$ is the slope in percent.

L: Slope length factor.

O: Vegetation factor.

This equation is most sensitive to changes in slope steepness.
• The Morgan and Finney Method

This is also another model developed to predict annual soil loss from field-sized areas to hill slopes. The founders of this equation were Morgan and Finney in 1984. This model separates the soil erosion process into water phase and sediment phase. It requires 15 input parameters and six operating functions. Due to the complexity of the equation, the mathematical model of this method is not described here. For further information, please refer to The Fundamental of Soil Science by Foth, 1984.

The method of predicting soil erosion and sediment loss using the Universal Soil Loss Equation in a computer environment was presented in the work of Foth (1984), Miller and Donahue (1990). A detailed methodology to calculate the values for each of the parameters employed by the Universal Soil Loss Equation was also discussed in length.

With the existence of soil loss mathematical models, Chakroun (1992) proposed a methodology for mapping and monitoring soil loss at a regional scale using GIS systems. The concept used was based on interfacing a hydrological model to a modified version of the widely known Universal Soil Loss Equation and the product of the research was a soil erosion loss map.

With the soil risk map or rather soil loss map, interpretation of the behaviour of soil movement can be assessed. Bergsma (1983) played a vital role in the area of soil dynamics by stressing the importance and the personification of soil risk maps. He described that there were three major groups of erosion maps. The first group showed
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the present erosion features and the indication of the on-going erosion processes. The second group indicated past erosion and the third group identified the erosion hazard factors. With the risk maps produced, how the past and the present data (risk maps) could contribute to the erosion hazard surveys which were necessary for conservation planning can be shown.

As for conservation planning, a literature about an interactive water quality modelling system developed within the GIS environment was presented by Liao (1994). As soil erosion is one of the factors affecting water quality, thus modelling of soil erosion was discussed in this paper too. Finally, a simulation of the soil erosion rates in an agriculture landscape based on the Universal Soil Loss Equation was done.

1.7 Methodology

Firstly, the mathematical model used for the analysis is the Universal Soil Loss Equation (USLE) of Wischmeier and Smith (1965) is used for the analysis. In the software, the parameters are represented in the form of digital layers.
Secondly, a software for soil erosion modelling and prediction will be developed through the Prime Meridian GIS’ Spatial Database Engine using Visual Basic as the programming language. Figure 1.3 shows the schematic diagram depicting the software system.

Thirdly, trial runs using the developed application software will be conducted on a sample test site. Langkawi Island has been selected for this test. The data for the respective layers (parameters) will be obtained from various sources.
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Once all the layers have been integrated into the developed GIS application software, the various factors represented by the layers are multiplied according to the USLE expression. The overlay modelling technique will be used in this multiplication before the cartographic presentation of the erosion risk map.
CHAPTER TWO

THEORIES RELATED TO THE SOFTWARE DEVELOPMENT

2.1 Universal Soil Loss Equation

In 1965, the Universal Soil Loss Equation (USLE) was first proposed and used for estimating sheet and rill erosion sediment losses from cultivated fields in the eastern flank of the Rocky Mountains in the United States of America. Besides that, this equation can also enable:

- The prediction of average annual soil loss from a given field slope under specified land use and management conditions.
- The guidance to the selection of conservation practices.
- The estimation of the reduction of soil loss attainable from various changes in farm management, cropping systems and cultural practices.
- The provision of localized data on soil erosion rates to conservation agencies and resource managers when discussing erosion control (conservation) plans with farmers.

The equation has since been adapted for use in other cultivated areas of USA, in Europe, in tropical Hawaii, Western Africa and Asia with little or no modifications to the equation. (Wischmeier et al, 1982)
The expected soil loss is determined from the product of five factors: rainfall (R factor), erodibility of the selected soil (K factor), the length (L factor), steepness of slope (S factor), the types of Crop (P factor) and Conservation practices (C factor).

Wishmeier and Smith (1978) defined the USLE as:

\[ E = R \cdot L \cdot S \cdot K \cdot C \cdot P \]

- **E**: Erosion soil loss in tons per acre per year
- **R**: Rainfall erosivity index
- **L**: Length of slope
- **S**: Steepness of slope
- **K**: Soil erodibility factor
- **C**: Conservation practice factor
- **P**: Crop management factor

The many possible numerical values for each factor require extensive knowledge and preparation. A practicing conservationist normally works in a small area, maybe a county and often will need only one or two rainfall factors (R), values for a few soils (K), a few cropping (vegetative) systems (P), the LS factor and the conservation practice (C) factor.
2.1.1 The Rainfall Factor (R Factor)

The rainfall factor (R) is a product of the kinetic energy (falling force) of a small rainfall multiplied with its maximum 30-minute period intensity of the fall. In countries where there is snow-melt in the area of precipitation pattern, the symbol Rs is often used as the snow-melt contribution and added to rainfall to equal total R. Obviously, fluctuations in duration and intensities of storms from year to year complicate getting the "average" R value for any location.

2.1.2 The Soil Erodibility Factor (K Factor)

Soil erodibility (K) is the case of which a soil can be eroded. Values are ranged from 1.0 (most easily eroded) to 0.01 (almost non-erosive). Soil high in silt and very fine sand are more easily eroded than other soils. Organic matter, larger structural aggregates, and rapid soil permeability will reduce the soil K factor. Figure 2.1 illustrates an example of the calculation of the K factor.
The soil erodibility factor (K) is estimated from four soil properties: texture, organic matter content, soil structure and permeability data. When compared with measured K values, about 95 percent of tested soils varied less than 0.04 K value from calculated values by this technique. To calculate a soil K value, in this example of a soil with 65 percent silt plus very fine sand, 5 percent other sands, 2.8 percent organic matter, structure 2 and permeability 4, follow the dashed line on the graph starting at the left at 65 percent (silt + very fine sand). The obtained K value is 0.3f.

Figure 2.1
Calculation of the Soil Erodibility Factor (K)
2.1.3 The Length of Slope Factor (LS Factor)

The length-slope value (LS) is the ratio of soil loss from the slope in question to the soil loss from the reference, which is a slope 22.1 metres (72.6 feet) long and a uniform 9 percent grade. The reference slope has an LS factor of 1.00. The LS factor could be determined through the following equation by McGuire (1995):

\[
LS = (L/22)^{0.5} \times (0.065 + 0.0458 + 0.0065S^2)
\]

where \( L \) is the length of the slope in metres and \( S \) is the steepness in percent.

Longer slopes increase erosion because water accumulates and increases in speed, collecting more cutting sediment and doing proportionally more damages. Doubling slope steepness (percentage grade) will double the erosion rate while on long slopes it may triple the erosion. Doubling slope length (with the same grade) increases erosion from about 20-40 percent. Convex slopes (dome-shaped) have more erosion than indicated by calculations using the average slopes concave (saucer-shaped) slopes have less erosion than calculations using average slopes. Changes in plant cover between the comparative slopes complicate these calculations and recognition must be made from the differences. Table 2.1 shows the combined LS factor for the soil erosion equation when compared to the standard reference of a slope 72.6 feet long with steepness of 9 percent.
Table 2.1: Combined LS factor (slope length and steepness) for the soil erosion equation when compared to the standard reference of a slope 72.6 ft. long with steepness of 9 percent.

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<th>Slope %</th>
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<tr>
<td>16.0</td>
<td>1.42</td>
<td>2.01</td>
<td>2.84</td>
<td>4.01</td>
<td>5.68</td>
<td>6.95</td>
<td>8.03</td>
<td>8.98</td>
</tr>
<tr>
<td>20.0</td>
<td>2.04</td>
<td>2.88</td>
<td>4.08</td>
<td>5.77</td>
<td>8.16</td>
<td>10.0</td>
<td>11.5</td>
<td>12.9</td>
</tr>
</tbody>
</table>

(Source: Wimmeir, 1965)

2.1.4 The Vegetation Cover Factor (P Factor)

The vegetation cover factor or better known as crop management factor considers the type and density of vegetation cover on the soil and all related management practices, such as time between operations (delay in planting after plowing and so forth). The C factor is very complicated because of the wide range of possibilities in cover material, management and the manner in which the crop residues can be left soil. A case to be kept in mind is that if a region comprises of several areas needs evaluation, then the C factor can be dropped as it is a constant in the USLE equation. (Olson, 1981)
2.1.5 Conservation Practice Factor (C Factor)

The conservation practice factor (C) recognizes the influence of contour planting, strip cropping, terracing and combinations. Table 2.2 lists several of these practices and their effects on erosion. The total benefit of terracing is not evident in the table because, after terracing, each terrace is treated as a separate slope less steep than the original slope and the terrace width is used as the slope length. These factors are put into the LS factor. The greatest erosion control by optimum choice of practice would be on level terraces (zero slope) having excellent protective cover on connecting slopes.

Table 2.2: The P Factor, which is the ratio of the erosion resultant from the practice described to that which occur with up-and-down-slope cultivation.

<table>
<thead>
<tr>
<th>Vegetative Condition</th>
<th>P Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>1-2 % slope, contoured, in 400 ft lengths</td>
<td>0.60</td>
</tr>
<tr>
<td>3-5 % slope, contoured, in 300 ft lengths</td>
<td>0.50</td>
</tr>
<tr>
<td>6-8 % slope, contoured, in 200 ft lengths</td>
<td>0.50</td>
</tr>
<tr>
<td>9-12 % slope, contoured, in 120 ft lengths</td>
<td>0.60</td>
</tr>
<tr>
<td>21-25 % slope, contoured, in 50 ft lengths</td>
<td>0.90</td>
</tr>
<tr>
<td>1-2 % slope, contour strip cropping, 130 ft strip width, 800 ft slope length (along the direction of the strip)</td>
<td>0.60</td>
</tr>
<tr>
<td>6-8 % slope, contour strip cropping, 100 ft strip width, 400 ft slope length</td>
<td>0.50</td>
</tr>
<tr>
<td>13-16 % slope, contour strip cropping, 80 ft strip width, 160 ft slope length</td>
<td>0.70</td>
</tr>
<tr>
<td>21-25 % slope, contour strip cropping, 50 ft strip width, 100 ft slope length</td>
<td>0.90</td>
</tr>
</tbody>
</table>

(Source: Wishmeier, 1965)
2.2 Overlay Modelling Technique

The power of GIS is her ability to combine data from many sources using different scales, projections and data models are her major strengths. An overlay operation can be characterized as "light-table gymnastics". These involved the creation of a new map on which the value assigned to every point, or a set of points, is a function of the independent values associated with that location on two or more existing overlays. (Berry, 1993)

2.2.1 Overlay Operations

Arithmetic and logical overlay operations are part and parcel of all GIS systems. Arithmetic overlay includes operations such as addition, subtraction, division and multiplication of each value in a data layer by the value in the corresponding location in a second data layer. A logical overlay involves finding those area where a specified set of condition occurs or do not occur together. All in all, there are two types of overlays, namely the vector-based and the raster-based overlays.

2.2.1.1 The Vector-Based Overlay

Figure 2.3 gives a simple example for two categorical data layers with vector-based structures. The data layers here are represented in polygons. These polygons differ from each other in size and shape. The attributes of the polygons are stored in a separate attribute table. Overlaying the two polygons will create a new polygon with a new set of attribute value.
Figure 2.3
Vector-based overlay operations

2.2.1.2 Raster-Based Overlay

Basically, in the raster-based overlay, data files consist of an ordered list of values. The spatial location of these values are determined by the position of the value within the file itself. Therefore, the overlay process between two files involves retrieving and registering the data from one layer to another data layer of interest. There is no need to calculate the intersections of boundaries or make any modifications to the boundary feature because each spatial element is a single cell with a standard size. Figure 2.4 illustrates the raster-based overlay operations.
Figure 2.4
Raster-based overlay operation
3.1 Overview

EPS/Prime Meridian from Essential Planning Systems Ltd. Canada is a powerful spatial database comprising a spatial database builder, spatial database engine and a comprehensive set of modular API. It brings a new generation of benefits to the traditional geographic information applications (GIAs) and as well as to an emerging universe of commercial applications.

EPS/Prime Meridian frees the application developer from purchasing and customizing standard GIS or from constructing proprietary technology. With EPS/Prime Meridian, systems development team can seamlessly integrate the benefits of sophisticated spatial data analysis in any geographical application rapidly, easily and economically. This results in fast, flexible embedding of the appropriate GIS functionality optimal to any application. Thus, time and cost can be reduced. EPS/Prime Meridian can be either in a client/server, standalone or distributed environment.
3.2 Components of Prime Meridian

EPS/Prime Meridian has five main components. They include:

- a spatial database and its associated linkages to user-selected third party attribute databases.
- a spatial database builder that gives application developers a robust full-featured facility for the design, construction, maintenance and analysis of the spatial database.
- an access engine that, via a high level query language, implements a powerful and flexible gateway to the spatial database.
- a high-level spatial standard query language (S\(^2\)QL), modelled on industry-standard SQL that embeds full-function GIS in the target application.
- a comprehensive suite of APIs that, for mission-critical application requiring extremely compact code, enable direct access to the spatial database.

3.2.1 Spatial Database

EPS/Prime Meridian geographic information system database consists of two primary database components, namely the spatial and the attribute component.
3.2.1.1 Spatial Database Component

The spatial database component of EPS/Prime Meridian stores a collection of spatial data systematically organized into discrete and logically related sets. This structure helps users to make sense out of the spatial data and provides a framework for spatial database operations such as terrain modelling or map analysis.

This system is a horizontal seamless and fully contiguous. Due to the advanced algorithms for indexing spatial data, there exists no artificial partitions such as tiles, map sheets or facets to hamper a realistic presentation of the real world. The primary spatial elements such as line, arc, point and text are stored within the spatial structure and are registered to a common coordinate system which facilitates comparison of spatial data from different sources.

3.2.1.2 Attribute Database Component

As for the attribute database component, EPS/Prime Meridian require neither user or the developer to store attribute data in the spatial database. Rather, it integrates spatial data and relationships with attribute data stored separately in a third-party database. Oracle, Dbase, Excel and Access are examples of third-party databases. Close coupling by powerful, transparent and dynamic links preserves performance and in fact enhance portability.
3.2.2 Spatial Database Builder

The spatial database builder (SDB) in EPS/Prime Meridian is a full-featured GIS. The database architect or designer is provided with a complete set of tools to design, construct, load, maintain and analyze the spatial database in terms of features, themes and maps.

The SDB also supports the creation and management of relationships and linkages with the attribute database. It grants the spatial database developer to digitize, input, view and draw maps. These tools for topological creation offer exceptional features such as automatic error detection and correction within user-defined tolerances. Design and construction of the attribute database component is simplified through familiar functionality within the third-party database itself.

3.2.3 Spatial Access Engine

The spatial access engine which is the key module in the EPS/Prime Meridian system is dedicated to: managing database traffic, performing high order graphics and spatial analysis, handling raster/vector intermodality and map production. It processes the $SQL$ commands and delivers access to the database for the application programmer. Via the access engine, application developers can access within their own application, a full range of GIS functionality. The engine and its operation are totally transparent to the application end-user.
3.2.4 High Spatial Query Language

To facilitate access to the spatial database from the application programs, EPS has developed a high-level spatial standard query language, S^3QL. These spatial query commands let application builders - in the development environment of their choice - embed any level of GIS functionality desired in their application. The access engine then simply processes these S^3QL calls to the spatial database. To ensure optimal performance and function, the engine supports powerful baseline S^3QL as internal calls. An additional, extensive library of external calls can be made directly and transparently via the engine.

3.2.3 Application Program Interfaces (APIs)

The spatial access engine in EPS/Prime Meridian achieves a high level of GIS, spatial mapping, spatial database functionality and flexibility. In addition to that, a comprehensive state-of-art application program interfaces permit advanced developers to code their own external executable S^3QL commands. EPS/Prime Meridian API’s are especially valuable for vastly simplifying the fulfillment of unusual GIS needs, development within extremely high performance mission-critical environments, or the writing of sophisticated speciality applications such as custom spatial data translators. A measure of the flexibility and power of this suite is evidenced in the fact that EPS used these APIs to code EPS/Prime Meridian itself.
3.3 Benefits of Prime Meridian

There are a number of benefits using this system. They are:

- Seamless integration
- Modularity
- Compliance

3.3.1 Seamless Integration

The spatial database provides a horizontal “seamless” coverage, as it contains no arbitrary partitioning according to map sheet or tile boundaries. A horizontal seamless coverage is an accurate representation of the real world. Therefore, there exists no discontinuous features at arbitrary boundaries and all features can be stored as an unbroken series of coordinates. In addition to that, topological relationships can be maintained across a complete mapping or management area. The spatial extents of a Prime Meridian database can cover an entire area conventionally covered by several map sheets. Figure 3.1 shows that a single line can be represented both a waterway and a municipal boundary; only one set of coordinates are actually stored in the database. Thus, this allows the normalization of spatial data and avoids data duplication.
3.3.2 Modularity

With EPS/Prime Meridian application developers can deploy mission-critical GIS functionality in the application by incorporating the appropriate selection of Application Program Interface (API) - incrementally, as needed. Therefore, one can build function as needed. There is no need to settle for too much or too little. Thus, the value of cost-effectiveness is seen here.
3.3.3 Compliance

EPS/Prime Meridian allows third party interfaces such as attribute database, network, graphics, I/O and so forth. This will permit more headroom for performance which brings about lower overall solution cost.
4.1 Overview of Eromap

The prototype software developed under this research was called the Erosion Mapper or better known as Eromap. This software was developed using Visual Basic Version 3.0 (VB) and the Spatial Structure Query Language (S²QL). The main purpose of this system is to perform soil erosion analysis based on a mathematical model. The mathematical model used in this prototype software is the well Universal Soil Loss Equation or better known as USLE.

The spatial access engine which is a powerful graphics server acting as an intermediary between the Eromap and the Prime Meridian spatial database. Visual Basic Control (VBX) of the Visual Basic programming language through Dynamic Data Exchange (DDE) communicates with the Spatial Structured Query Language (S²QL) commands. It is with these interactions that the Geographic Information System (GIS) functionality managed to embed itself into Eromap.

4.2 System Development

Prior to the development of the soil erosion modelling system, three things were taken seriously into account. They are:-

- System Design Flow
- Application Flow
- System’s Directory Structure
4.2.1 System Design Flow

As with any other project, may it be large or small scale, a project work flow has to be prepare, to allow the smooth transition of the project from one phase to the other. Thus, in the development of the soil erosion modelling system (Eromap), a work flow of the system design was drawn out too. This is to facilitate the smooth system design. Figure 4.1 outlines the system design work flow:

![Diagram]

Figure 4.1
System design work flow
4.2.2 Application Flow

Before the design of any system, it is inevitable that the application flow has got to be designed. The application flow or better known as the algorithm is shown in Figure 4.2.
4.2.3 System’s Directory Structure

The Prime Meridian’s spatial data manager manages both spatial and attribute files using a directory and subdirectory layout as illustrated in figure 4.3.

```
>C:\.....\eps_pm
  \eps_pm\ pm1.x
  \eps_pm\ pm1.x\ app
  \eps_pm\ pm1.x\ app\ lam
  \eps_pm\ pm1.x\ sae
  \eps_pm\ pm1.x\ sae\ font
  \eps_pm\ sdb
  \eps_pm\ sdb\ exchange
  \eps_pm\ vbxdll
  \eps_pm\ userdata

>C:\windows95
```

Figure 4.3
Directory hierarchy of the spatial data manager

4.2.3.1 APP Directory

The APP subdirectory is used to store the Address Matching applications and its associated files.
4.2.3.2 SAE Directory

The SAE directory contains the Prime Meridian program files, the user account data file (ACCOUNT.DAT) the error message file (TSF_ERR.DAT) and the reserved keywords file (KEYWORDS.TXT).

4.2.3.3 Font Directory

The FONT subdirectory contains the systems default font (CHAR1.FNT), custom font (FANCY??.FNT), custom line type (LINETYPE.DAT) and line thickness (TSF_LINES.DAT) files. The DISPSYM.DAT file contains colour mapping and Windows True Type fonts / Prime Meridian font associations.

4.2.3.4 SDB Directory

The executable files for the Spatial Data Manager are stored in the SDB subdirectory.

4.2.3.5 Exchange Directory

This directory contain program files for spatial data translation. There are two type of data translation operations: import and export. An import operation translates a Prime Meridian data exchange format file (TDEF) or a third party data format file into the Prime Meridian map file. An export operation translates data from Prime Meridian’s format (TSF) into a TDEF or a third-party data format file.
4.2.3.6 VBXDLL

The VBXDLL subdirectory contains the dynamic link library files as well as additional VBX controls and DLLs required by the Spatial Data Manager. VBXDLL\INCLUDE contains interface files and modules for C and Visual Basic applications using some of the supplied DLLs. VBXDLL\LIB contains status libraries that must be linked into C programs calling DLL access functions.

4.2.3.7 Userdata Directory

This directory consists of blank user files which can be used as a starting point for building a Prime Meridian database. User account and the directory path can be established by choosing Utilities | Accounts from the Spatial Data Manager.

4.3 Program Organization

The prototype software was developed in the 32-bit Windows Programming environment. The prototype soil erosion modelling system is characterized by two major features. First, the complexity of the integrated models and geographic database is completely hidden from the user, who is only exposed to several pull-down menus and graphics-oriented user interfaces. The second feature is the most important where the system is highly modular and built with an open architecture. All of the modules, particularly the modelling components, are functional entities that can be easily replaced, extended or modified through the use of Visual Basic programming language. Thus, while being an operational Prime Meridian-based soil erosion modelling system, modifications and adjustments can easily be made.
In general, the interactive modelling environment consists of 13 sub-modules written in Visual Basic-SQL programming language. A graphical user interface (GUI) facilitates visualization and display of the modelling results in a form of an interactive map window. Please refer to Figure 4.4.

![Program Manager](image)

**Figure 4.4.**
An interactive modelling environment

Only three modules of the Eromap will be used for the soil erosion analysis. They are:

- Layer Interrogator
- Database Builder
- Erosion Analyzer
The following sections will describe the general structure of each of the three modules of the integrated soil erosion modelling system.

4.3.1 Module 1: Layer Interrogator

This is the first module to be executed prior to any soil erosion analysis. Module 1 was created to interrogate if the user has all the USLE factors at his dispose. On top of that, it also makes sure that all the polygons representing the layers have all the values for the respective USLE factors.

Should there be a case of an incompleteness of the layers, this module will notify the user and execute Module 2 which is the Database Builder. The Database Builder is executed to perform data entries of the layers into the prototype soil erosion modelling system. Otherwise this module will execute Module 3, the Erosion Analyzer module to obtain the result. The organization chart of this module is shown in Figure 4.5 while their pseudocodes depicting this module can be seen in Figure 4.6.
Figure 4.5.
Organization chart of Module 1
```cpp
#include <iostream.h>
#include <graphics.h>

main()
{

   // initialize graphics with auto detection of
   // graphics driver and mode
   initgraph (&g_driver, &g_mode, " ");

display graphics form;

cout << "USLE Layers Analyzer";
cout << "Inquire user if all USLE factors are available"
cin >> answer;
   if ( answer == "Y")
      { Run Erosion_Analyzer.Exe }
   else
      { cout << "What factor is not available ?"
cin>> factor ;

switch (factor)
{
   case 'R' : cout << "Import ready made layers into system"
   {run Database_Builder.Exe }
   break;
   case 'LS': cout << "Import ready made layers into system"
   {run Database_Builder.Exe }
   break;
   case 'K' : cout << "Import ready made layer into system"
   {run Database_Builder.Exe }
   break;
   case 'C' : cout << "Delineate layer using Database Builder"
   {run Database_Builder.Exe }
   break;
   case 'P' : cout << "Delineate layer using Database Builder"
   {run Database_Builder.Exe }
   break;
   }
return 0;
}
```

Figure 4.6.
Pseudocodes of Module 1

39
4.3.2 Module 2: Database Builder

Module 2 is a database builder which provides spatial data input and manipulation. This Database Builder has the capability to allow the user to create custom symbols, dynamic labels and display symbologies. Thus, should the user have yet to create or delineate the layer with the polygons representing various values, this module has the option which allows one to do so. The user would need this option to create the Crop Management (P) and the Conservation Practice (C) layers. On top of that, this Database Builder can also be used to import the layers representing various USLE factors. This is especially important to import layers such as the Rainfall (R), Soil Erodibility (K) and the Length of Slope (LS) factors.

Upon the creation of these layers, the user would also use this module for data cleaning and value designation before it can be used for further soil erosion analysis.

The organizational chart for this Database Module is illustrated in Figure 4.7.

![Database Builder Organizational Chart](image)

**Figure 4.7.**
Organization chart for Module 2
4.3.3 Module 3: Erosion Analyzer

Module 3, Erosion Analyzer, plays a vital role in the erosion modelling system. It is the core of the soil erosion modelling and prediction system. This module performs the overlay modelling technique and consequently displays the results in a form of the soil erosion risk map on the visual display unit. The organization chart of this module is depicted in Figure 4.8.

![Organization chart of Module 3](image)

Figure 4.8.
Organization chart of Module 3
Figure 4.9 illustrates the stages involved in performing the soil erosion modelling in a form of pseudocodes.

```cpp
#include <iostream.h>
#include <graphics.h>

main ()
{
    // initialize graphics with auto detection of graphics driver
    initgraph (&g_driver, &g_mode, " ");
    display graphics form;
    display map window;
    set display limits

    // Establish connections with Prime Meridian Engine (PME)
    // using Dynamic Data Exchange (DDE) technique
    Link_Item = "PMEEngine";
    Link_Topic = "PMEEngine | S2QL";
    Link_Execute S2QL_Command

    // Check Connections
    if ( Link Xxx == "Error")
    {
        Cout << "Prime Meridian Engine Connection Failure !"
        Cout << " Please check the systems' connections"
    }
    else
    {
        Extract R_layer;
        Extract LS_layer;
        Extract K_layer;
        Extract P_layer;
        Extract C_layer;

        if ( Extract Xxx == "Error")
        {
            cout << "Layer extraction error";
            cout << "Check USLE layers again !";
        }
        else
        {
            //initialize overlay modelling of layers
            result = R * LS * K * C * P
            cout << "Display of Erosion Risk Map"<< result;
        }
        return 0;
    }
```

Figure 4.9.
Pseudocode of Module 3.
4.4 Software Evaluation

A typical session using Eromap is presented in this section.

All the layers representing the various factors, namely the Rainfall (R), Soil Erodibility (K), Length of Slope (LS), Crop Management (P) and Conservation Practice (C) factors were used in this evaluation session. The following steps show the process of soil erosion analysis using Eromap.

1. C: \ WIN

A window display of Eromap will be shown as in Figure 4.10.

2. Select Layer Interrogator
   [Click the Layer Interrogator icon]
   The system will initiate the Layer Interrogator module.

![Figure 4.10](image)
Window display of Eromap
Enter Password
[See Figure 4.11]
This is for the purpose of system’s security clearance.

Answer all the System Interrogator’s inquiries.
[See Figure 4.12.]
Should there be any incomplete layers, the system will summon the Database Builder module as in Figure 4.13.

[Image of the Database Builder module with a warning to initiate the module]

Figure 4.13

Call up the base map from the system. [Click File from the menu bar as in Figure 4.14.]

Figure 4.14
Delineate the polygon representing the USLE factor. [Use the tools from the Tool Bar as in Figure 4.15.]

Clean under-shoot and over-shoot polylines. [Use the Edit command from the menu bar as in Figure 4.16.]
Assign the polygons in the layer with respective values. [Use the Themes command from the menu bar as in Figure 4.17.]

Initiate the Erosion Analyzer module. [Click the Erosion Analyzer icon from the window]

[Clear the security system with the password as in Figure 4.18.]
Display map window
[Click the Display Map command from the menu bar as in Figure 4.19.]

Check for Rainfall Factor through display
[Click Display R Factor command as in Figure 4.20.]
Check for Length of Slope (LS) Factor
[Click Display LS Factor command as in Figure 4.21.]

Check for Soil Erodibility (K) Factor
[Click Display K Factor command as in Figure 4.22.]
Check for Crop Management (P) Factor
[Click Display P Factor command as in Figure 4.23.]

Check for Conservation Practice (C) Factor
[Click Display C Factor command as in Figure 4.24.]
Figure 4.25

- **Initiate Erosion Analysis from the menu bar**
  [Click Erosion Analysis command as in Figure 4.25.]

The output from this stage is the output of the Soil Erosion Risk Map.
CHAPTER FIVE
THE RESULTS AND ANALYSIS

5.1 Introduction

It is undeniable that this prototype software was developed successfully. Nevertheless, as with any products, tests had to be conducted and results had to be generated for the purpose of software evaluation. Sample test data of Langkawi Island was used in this evaluation. The layers involved were:

- Rainfall (R) Factor
- Soil Erodibility (K) Factor
- LS Factor (LS)
- Crop management (P) Factor
- Conservation Practice (C) Factor

The test data was supplied by the Malaysian Agriculture Department (Jabatan Pertanian Malaysia) in a hardcopy form. The data was converted into the digital format by digitizing it into the Autocad platform. The Autocad system then exported it into the DXF format. The Database Builder was used to import the DXF format into the TSF format of the Eromap system.
Chapter 5: The Results And Analysis

The evaluation will be centred on four questions, namely:

- Is the modelling system efficient and reliable?
- Is the system performing the procedures properly?
- Is the system presenting the results in an acceptable and effective cartographic fashion?
- What are the limitations?

5.2 Efficiency and Reliability of Eromap

Eromap has an interactive and menu-driven interface that guides the user with prompt and explain messages through the application. There is no need for any command language of other special format of interaction. Eromap assists the user in its proper use and consequently increases the system’s user-friendliness.

The system has no human interventions in its processing except for the layer development stage if there is a need. This fact reduces the introduction of errors in the layers which will have a significant effect over the results of the overlay modelling operations. Minimum or no errors introduced in the data layers will preserve the accuracy of the data. Consequently, accurate results of the soil erosion risk map will be generated.
5.3 The Performance of Eromap

Eromap was developed in a 32-bit programming platform. The minimum requirements for Eromap to run well are as follows:

- An 80486-based IBM-compatible PC.
- DOS Version 3.22 or a later version.
- A mouse or digitizing tablet.
- A display system that can display graphics. A monitor with the resolution of at least 800 X 600 pixels that displays at least 16 colours is recommended for production CAD work. In most cases, even higher resolution and a 19-inch or larger monitor is desirable.
- Sufficient RAM. The recommended size is 12 MB.
- At least 50 MB free space on a hard drive after installation.

Erosion analysis of the Langkawi Island test data took less than 1 second on such a system configuration.

This prototype soil erosion modelling system can perform two different types of overlays. They are the vector overlay and the raster overlay. The overlay modelling technique used in this project was the vector overlay. This is mainly due to the fact that the supplied data was in a vector form.
5.4 The Presentation Capabilities of Eromap

In this soil erosion modelling and prediction project, Isopoles maps of the Isarithmic categories were generated in both the digital and analogue format.

In the digital format, dynamic colour graphics for the model output and symbolic representation of the results of the erosion analysis allow easy and immediate understanding of basic patterns and relationships for the user.

In order to examine the system’s cartographic production capabilities from a closer point of view, a few hardcopies were plotted using the Hewlett Packard Design Jet III. The hardcopies of the Rainfall (R) Factor, Length of Slope (LS) Factor, Soil Erodibility (K) Factor and the resultant Soil Erosion Risk Map can be viewed from Appendices I through IV respectively.

The results from the hardcopies were very encouraging and these provide the user with full-confidence of the system. On top of that, this would also mean that this system has a very good cartographic capabilities.

5.5 Limitations of Eromap

As with other designs and inventions, all products have their strengths and weaknesses. In Eromap, there exists a predicament associated with the mathematical overlay modelling of one of the layers.
For Eromap to be able to perform the erosion analysis, the LS factor has to be of a single layer. That means this system can only perform overlay modelling using the LS factor which is the resultant of the product between the length of slope \((L)\) layer and the slope angle \((S)\) produced by some other platforms. It must be noted that the inability to break the LS factor will cause a lost of accuracy. Heuvelink, Burrough and Stein (1989) have studied that the products of length of slope \((L)\) and the slope angle \((S)\) will always be greater than the actual values. This is due to the error propagation of \(L\) and \(S\) values of the equation below:

\[
LS = (L/22)^{0.5} \times (0.065 + 0.0458 + 0.00655S^2)
\]

There are two techniques to overcome this perplexity. They are:

- Separation of The LS Factor
- Increment of The Display Resolution

5.5.1 Separation of The LS Factor

This error can be minimized by separating the LS factor into the Slope Angle and the Length of Slope respectively. The separation of LS factor will definately increase the accuracy of the system. Nevertheless, field studies need to be conducted before the \(L\) and \(S\) factors can be obtained.
5.5.2 Increment of The Display Resolution

Another method to overcome the problem of inaccuracy is to increase the resolution of the display system. As the resolution gets higher, the soil erosion can be accurately modelled. The erosion estimates will approach actual values. The method proves to be practical in cases where field studies are impractical. On top of that, this method offers the best solution with the available (LS Factor) data.
CHAPTER SIX

REVIEWS, CONCLUSION AND RECOMMENDATIONS

Geographic information systems technology is spreading rapidly, largely due to the continuing revolution in computer hardware. In the next decade, it will definitely become the backcloth on which most environmental assessment, planning and management will take place. Thus, GIS technology must now be seen as providing the basic framework for processing large volumes of spatial data and describing spatial environmental processes. This implies the need to begin to integrate both traditional and new tools for environmental analysis and modelling.

It is undeniable that Geographic Information System (GIS) has been in the arena of erosion analysis not less than fifteen years. The recent development of GIS is not limited to soil profile data. Developments in mapping technology, interpolation methods, remote sensing and modelling have provided environmental agencies with useful tools that are used for standard productions of maps and environmental impact assessment reports. The purpose of this study is to develop such a system which can model and predict soil erosions.

The system developed in this project is the Eromap, a soil erosion modelling and prediction system which utilizes the Universal Soil Loss Equation (USLE) developed by Wischmeier and Smith in 1962.
The two main objectives of this research have been successfully achieved through Eromap. With Eromap, one is able to analyze soil erosion loss using Prime Meridian GIS' Spatial Database Engine (SDE). In addition to that, Eromap permits the user to generate soil erosion risk maps. This system also provides the user with a high level of confidence with the capability and applicability for erosion analysis of environmental impact assessments. As a result of Eromap being able to handle much larger volumes of data, one has come to grip with the difficult problems of describing the spatial variation of soil erosions.

Though Eromap has successfully being developed, nevertheless, this prototype software can further be improved in the area of mathematical modelling. At the time of this writing, the resultant LS factor has yet to be broken up into Slope Angle (S) and Length of Slope (L) respectively. The author recommends that there should be a further research into the separation of LS factor in order to achieve a better accuracy of the resultant soil erosion risk map.

In general, this developed prototype system in its present form achieves the research objectives and is a sufficiently realistic demonstration of the flexibility of GIS technology. It also shows that ability to interactively model water quality problems within the GIS environment.
References


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APPENDICES

- APPENDIX 1 : RAIN EROSIVITY FACTOR (R)
- APPENDIX 2 : SOIL ERODIBILITY FACTOR (K)
- APPENDIX 3 : LENGTH OF SLOPE FACTOR (LS)
- APPENDIX 4 : SOIL EROSION RISK MAP
- APPENDIX 5 : EROMAP PROTOTYPE SOURCE CODE
Appendix 1
Rain Erosivity Factor (R)
Appendix 2
Soil Erodibility Factor (K)
SOIL EROSION MODELLING AND PREDICTION
MAP OF LANGKAWI ISLAND
SCALE 1 : 100 000

LENGTH OF SLOPE (LS FACTOR) OF LANGKAWI ISLAND

LEGEND

□ LESS THAN 1'
□ BETWEEN 1' AND 2'
□ BETWEEN 2' AND 5'
□ BETWEEN 5' AND 10'
□ BETWEEN 10' AND 20'
□ BETWEEN 20' AND 30'
□ GREATER THAN 30'

Note:
All coordinates are based on the Rectified Skew Orthomorphic Projection

Designed & Constructed:
Michael Teng Chee Chon
Final Year Project
Bachelor of Surveying (Land)

Supervisor:
Assoc Prof Dr Taner Buyung
Centre for Geographic Information & Analysis

Date:
January 1996

Source:
This map is generated by using the prototype EROMAP Soil Erosion Modelling System through the Prime Meridian Spatial Database Engine.

Appendix 3
Length of Slope Factor (LS)
SOIL EROSION MODELLING AND PREDICTION
MAP OF LANGKAWI ISLAND
SCALE 1 : 100 000

EROSION RISK MAP OF LANGKAWI ISLAND

LEGEND
TONS/HA/YEAR
- LESS THAN 10
- BETWEEN 10 AND 50
- BETWEEN 50 AND 100
- BETWEEN 100 AND 150
- ABOVE 150

DESIGNED & CONSTRUCTED
Michael Tong Choon Bun
Final year Project
Bachelor of Surveying (Land)

SUPERVISOR
Assoc Prof Dr Taller Bayong
Centre for Geographic Information & Analysis

DATE
January 1996

SOURCE
This map is generated by using the prototype EROMAP
Soil Erosion Modelling System through the Prime Meridian
Spatial Database Engine.

Note:
All coordinates are based on the Rectified Skew Orthomorphic Projection

Appendix 4
Soil Erosion Risk Map
Appendix 5
Eromap Prototype Source Code
VERSION 2.00
Begin Form Credits
BackColor = &H00E0FFFF&
BorderStyle = 1 'Fixed Single
Caption = "Credits"
ClientHeight = 4185
ClientLeft = 1920
ClientTop = 1575
ClientWidth = 6255
ControlBox = 0 'False
FillStyle = 2 'Horizontal Line
FontBold = -1 'True
FontItalic = 0 'False
FontName = "Courier"
FontSize = 9.75
FontStrikethru = 0 'False
FontUnderline = 0 'False
Height = 4590
Left = 1860
LinkTopic = "Form1"
MaxButton = 0 'False
MinButton = 0 'False
ScaleHeight = 4185
ScaleWidth = 6255
Top = 1230
Width = 6375

Begin CommandButton Command1
BackColor = &H00FF0000&
Caption = "Close"
FontBold = -1 'True
FontItalic = 0 'False
FontName = "Arial"
FontSize = 9
FontStrikethru = 0 'False
FontUnderline = 0 'False
Height = 375
Left = 4680
TabIndex = 0
Top = 3600
Width = 975
End

Begin Image Image1
Height = 480
Left = 2760
Picture = (Icon)
Top = 120
Width = 480
End

Begin Label Label1
Height = 480
Left = 2760
Picture = (Icon)
Top = 120
Width = 480

Alignment = 2 'Center
BackColor = &H00E0FFFF&
Caption = "The author would like to thank"
FontBold = -1 'True
FontItalic = -1 'True
FontName = "Times New Roman"
FontSize = 13.5
FontStrikethru = 0 'False
FontUnderline = 0 'False
CREDITS.FRM - 2

ForeColor = &H0FF0000&
Height = 2655
Left = 240
TabIndex = 1
Top = 720
Width = 5775
End
End

CREDITS.FRM - 1

Sub Command1_Click ()
Credits.Hide
Unload Credits
GismaIN.Show
End Sub
HELP.FRM - 1

VERSION 2.00
Begin Form Help
 BackColor = &H00E0E0E0&
 BorderStyle = 1 'Fixed Single
 Caption = "HELP"
 ClientHeight = 3525
 ClientLeft = 1425
 ClientTop = 1815
 ClientWidth = 6990
  ControlBox = 0 'False
  ForeColor = &H00E0E0E0&
  Height = 3930
  Left = 1365
  LinkTopic = "Form1"
  MaxButton = 0 'False
  MinButton = 0 'False
  ScaleHeight = 3525
  ScaleWidth = 6990
  Top = 1470
  Width = 7110
Begin CommandButton Command1
  BackColor = &H00808080&
  Caption = "Close"
  Height = 375
  Left = 5400
  TabIndex = 1
  Top = 2880
  Width = 1095
End
Begin Label Label1
  Alignment = 2 'Center
  BackColor = &H00808080&
 BorderStyle = 1 'Fixed Single
  Caption = "Please refer to the accompany
  FontBold = -1 'True
  FontItalic = -1 'True
  FontName = "Times New Roman"
  FontSize = 13.5
  FontStrikethru = 0 'False
  FontUnderline = 0 'False
  ForeColor = &H00FF0000&
  Height = 2055
  Left = 240
  TabIndex = 0
  Top = 720
  Width = 6495
End
Begin Image Image1
  Height = 480
  Left = 3120
  Picture = (Icon)
  Top = 120
  Width = 480
End
End
Sub Command1_Click ()
Help.Hide
Unload Help
GISMAIN.Show
End Sub
VERSION 2.00
Begin Form PURPOSE

BackColor = &H0080C000&
BorderStyle = 3 'Fixed Double
Caption = "Purpose of Ero-Map"
ClientHeight = 4305
ClientLeft = 1290
ClientTop = 1710
ClientWidth = 7080
ControlBox = 0 'False
FillColor = &H00FF0000&
Height = 4710
Left = 1230
LinkTopic = "Form1"
MaxButton = 0 'False
MinButton = 0 'False
ScaleHeight = 4305
ScaleWidth = 7080
Top = 1365
Width = 7200

Begin CommandButton Command1

Caption = "CLOSE"
Height = 375
Left = 5520
TabIndex = 2
Top = 3840
Width = 1095

End

Begin Image Image1

Height = 480
Left = 3120
Picture = (Icon)
Top = 240
Width = 480

End

Begin Label Label2

Alignment = 2 'Center
BackColor = &H00CC00FF&
Caption = "This project is initiated to fulfil
FontBold = -1 'True
FontItalic = 0 'False
FontName = "MS Sans Serif"
FontSize = 9.75
FontStrikethru = 0 'False
FontUnderline = 0 'False
Height = 615
Left = 240
TabIndex = 0
Top = 3120
Width = 6615

End

Begin Label Label1

Alignment = 2 'Center
BackColor = &H00FFFFFF80&
Caption = "Ero-Map was designed to conduct Soi
FontBold = -1 'True
FontItalic = 0 'False
FontName = "MS Sans Serif"
 PURPOSE.FRM - 2

 FontSize = 12
 FontStrikethru = 0 'False
 FontUnderline = 0 'False
 ForeColor = &H000000CO&
 Height = 2295
 Left = 240
 TabIndex = 1
 Top = 840
 Width = 6615

End
End

 PURPOSE.FRM - 1

 Sub Timer1_Timer ()
 PURPOSE.Hide
 Unload PURPOSE
 End Sub

 Sub Command1_Click ()
 PURPOSE.Hide
 Unload PURPOSE
 GISMAIN.Show
 End Sub
VERSION 2.00
Begin Form Rights
  BackColor = &H00C0E0FF&
  BorderStyle = 1 'Fixed Single
  Caption = "Copyright © CGIA1996"
  ClientHeight = 4020
  ClientLeft = 1725
  ClientTop = 1860
  ClientWidth = 6540
  ControlBox = 0 'False
  Height = 4425
  Left = 1665
  LinkTopic = "Form1"
  ScaleHeight = 4020
  ScaleWidth = 6540
  Top = 1515
  Width = 6660
End
Begin CommandButton Command1
  Caption = "Close"
  Height = 375
  Left = 4200
  TabIndex = 2
  Top = 3400
  Width = 975
End
Begin Image Image1
  Height = 480
  Left = 2760
  Picture = (Icon)
  Top = 120
  Width = 480
End
Begin Label Label2
  BackColor = &H00C0E0FF&
  Caption = "Michael Tang Chuoon Mun"
  FontBold = -1 'True
  FontItalic = -1 'True
  FontName = "Times New Roman"
  FontSize = 9.75
  FontStrikethru = 0 'False
  FontUnderline = 0 'False
  ForeColor = &H00FF0000&
  Height = 375
  Left = 3600
  TabIndex = 1
  Top = 3000
  Width = 2415
End
Begin Label Label1
  BackColor = &H00C0E0FF&
  Caption = "Copyright © 1996 by MIKETCM-CGI"
  FontBold = -1 'True
  FontItalic = 0 'False
  FontName = "MS Sans Serif"
  FontSize = 9.75
  FontStrikethru = 0 'False
  FontUnderline = 0 'False
  ForeColor = &H000000C0&
End
RIGHTS.FRM - 2

    Height = 2415
    Left = 120
    TabIndex = 0
    Top = 720
    Width = 6255
    End
End

RIGHTS.FRM - 1

Sub Command1_Click ()
Rights.Hide
Unload Rights
GISMMAIN.Show
End Sub
VERSION 2.00
Begin Form PWForm
  BackColor = &H00C0E0FF&
  BorderStyle = 3 'Fixed Double
  Caption = "ERD-MAP SECURITY CHECK"
  ClientHeight = 3900
  ClientLeft = 2250
  ClientTop = 1845
  ClientWidth = 5655
  ControlBox = 0 'False
  Height = 4305
  Left = 2190
  LinkTopic = "Form2"
  MaxButton = 0 'False
  MinButton = 0 'False
  ScaleHeight = 3900
  ScaleWidth = 5655
  Top = 1500
  Width = 5775

Begin CommandButton Command1
  Caption = "OK"
  FontBold = -1 'True
  FontItalic = 0 'False
  FontName = "MS Sans Serif"
  FontSize = 9.75
  FontStrikethru = 0 'False
  FontUnderline = 0 'False
  Height = 375
  Left = 3960
  TabIndex = 6
  Top = 3360
  Width = 1335
End

Begin TextBox pass
  Alignment = 2 'Center
  FontBold = -1 'True
  FontItalic = 0 'False
  FontName = "MS Sans Serif"
  FontSize = 9.75
  FontStrikethru = 0 'False
  FontUnderline = 0 'False
  ForeColor = &H0000FF00&
  Height = 360
  Left = 2040
  PasswordChar = "X"
  Tabindex = 5
  Top = 3000
  Width = 1455
End

Begin PictureBox IconPic
  AutoSize = -1 'True
  BackColor = &H0080C0FF&
  BorderStyle = 0 'None
  Height = 480
  Left = 5040
  Picture = (Icon)
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  ScaleWidth = 480
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<td>0 'False</td>
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<td>2160</td>
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</tr>
<tr>
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<tr>
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<td>0 'False</td>
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<td>FontName</td>
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<td>FontSize</td>
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<tr>
<td>FontStrikeThru</td>
<td>0 'False</td>
</tr>
</tbody>
</table>
FontUnderline = 0 'False
ForeColor = &H0000000FF&
Height = 495
Left = 840
TabIndex = 3
Top = 1440
Width = 3975

End

Begin Label Label1
Alignment = 2 'Center
BackColor = &H00C0E0FF&
Caption = "Ero-Map Soil Erosion Modelling And
FontBold = -1 'True
FontItalic = 0 'False
FontName = "MS Sans Serif"
FontSize = 13.5
FontStrikethru = 0 'False
FontUnderline = 0 'False
ForeColor = &H00C00000&
Height = 855
Left = 360
TabIndex = 2
Top = 240
Width = 4935

End

End
Sub Command1_Click ()
    'change from string to numeric by using Val
    Code = Val(pass.Text)

    If Code = 2543969 Then
        Beep
        Beep
        MsgBox "Welcome To Ero-Map Version 1.0", 48, "ACCESS"
        PWFORM.Hide
        Unload PWFORM
       Cls
        Load GISMMain
        Beep
        Beep
        GISMMain.Show
        Else
        Beep
        Beep
        Beep
        MsgBox "INVALID USER : ACCESS DENIED", 16, "WARNING"
    End If

End Sub
Sub MnuLvl2Bound_Click()
    Call PMEXECUTE("ADD FEATURECLASS BLK_BDREY TO PM_DISPLAY_LIST INMAP")
End Sub

Sub MnuLvl2Geo_Click()
    Call PMEXECUTE("ADD FEATURECLASS GEOLOGY TO PM_DISPLAY_LIST INMAP")
End Sub

Sub MnuLvl2Water_Click()
    Call PMEXECUTE("ADD FEATURECLASS SING_WATER TO PM_DISPLAY_LIST INMAP")
End Sub

Sub Form_Load()
    'Declarations
    Dim SL1, SL2, SL3, SL4, SL5, SL6, SL7 As String

    'Center the form
    Left = (Screen.Width - Width) / 2
    Top = (Screen.Height - Height) / 2

    'Pre-startup procedure
    bRTN = Shell("C:\EPS_PM\SAE\PMENGINE.EXE")
    Call PMEXECUTE("LOGIN MAPKAWI")
    Call PMEXECUTE("OPEN INSTANCE WINMAP")
    Call PMSETUP(""")
    MAPNAME = "C:\EROMAP\MAPKAWI\LKAWI.TSF"

    SL1 = ("SET WINMAP!MAP_FILEANME TO ")
    SL2 = DBLEQUOTE & MAPNAME & DBLEQUOTE

    Call PMEXECUTE(SL1 & SL2)

    SHANDLE = Hex(GISMAIN.Picture1.hWnd)

    SL3 = ("SET WINMAP!WINDOW.OWNER TO ")
    SL4 = DBLEQUOTE & SHANDLE & DBLEQUOTE
    Call PMEXECUTE(SL3 & SL4)

End Sub

Sub MnuLvl2Clear_Click()
    Call PMEXECUTE("REMOVE * FROM PM_DISPLAY_LIST IN INSTANCE WINMAP")
    Call PMEXECUTE("DRAW * IN INSTANCE WINMAP")
End Sub

Sub MnuLvl2Cre_Click()
    'DISPLAY CREDITS FORM
    GISMAIN.Hide
    Load CREDITS
    Beep

GISMAIN.FRM - 2

CREDITS.Show
End Sub

Sub MnuLvl2Right_Click ()
'DISPLAY RIGHTS FORM
GISMAIN.Hide
Load RIGHTS
Beep
RIGHTS.Show
End Sub

Sub MnuLvl2Disp_Click ()
Call PMEXECUTE("SET WINMAP!WINDOW.VISIBLE TO TRUE")
Call PMEXECUTE("SET WINMAP!WINDOW.BACKGROUNDCOLOR TO 7")
Call PMEXECUTE("ZOOM UP 50 IN INSTANCE WINMAP")
Call PMEXECUTE("ZOOM AREA 1821.54 639.15 482578 IN INSTANCE WINMAP")
End Sub

Sub MnuLvl2Ero_Click ()
Call PMEXECUTE("REMOVE + FROM PM_DISPLAY_LIST IN INSTANCE WINMAP")
Call PMEXECUTE("ADD FEATURECLASS E0010 TO PM_DISPLAY_LIST AT ENNMAP")
Call PMEXECUTE("ADD FEATURECLASS E100150 TO PM_DISPLAY_LIST AT ENNMAP")
Call PMEXECUTE("ADD FEATURECLASS E1050 TO PM_DISPLAY_LIST AT ENNMAP")
Call PMEXECUTE("ADD FEATURECLASS E15000 TO PM_DISPLAY_LIST AT ENNMAP")
Call PMEXECUTE("ADD FEATURECLASS E50100 TO PM_DISPLAY_LIST AT ENNMAP")
End Sub

Sub MnuLvl2Exit_Click ()
Call PMEXECUTE("CLOSE INSTANCE WINMAP")
Call PMEXECUTE("LOGOUT")
'Call PMEXECUTE("DOWN")
Unload GISMAIN
GISMAIN.Hide
End Sub

Sub MnuLvl2Fresh_Click ()
Call PMEXECUTE("DRAW + IN INSTANCE WINMAP")
End Sub

Sub MnuLvl2Inst_Click ()
GISMAIN.Hide
Load HELP
HELP.Show
End Sub

Sub MnuLvl2Pur_Click ()
'DISPLAY PURPOSE FORM
GISMAIN.Hide
Load PURPOSE
Beep
PURPOSE.Show
End Sub

Sub MnuLv12SysDev_Click ()
' DISPLAY SYSDEV FORM
GISMAIN.Hide
Load SYSDEV
Beep
SYSDEV.Show
End Sub

Sub MnuLv12Zoomin_Click ()
Call PMEXECUTE("ZOOM IN INSTANCE WINMAP")
End Sub

Sub MnuLv12ZoomOut_Click ()
Call PMEXECUTE("ZOOM OUT IN INSTANCE WINMAP")
End Sub

Sub MnuLv13C_Click ()
Call PMEXECUTE("REMOVE * FROM PM_DISPLAY_LIST IN INSTANCE WIN"
Call PMEXECUTE("ADD FEATURECLASS C_085 TO PM_DISPLAY_LIST AT MAP")
Call PMEXECUTE("ADD FEATURECLASS C_095 TO PM_DISPLAY_LIST AT MAP")
Call PMEXECUTE("ADD FEATURECLASS C_100 TO PM_DISPLAY_LIST AT MAP")
Call PMEXECUTE("ADD FEATURECLASS C_115 TO PM_DISPLAY_LIST AT MAP")
End Sub

Sub MnuLv13Coast_Click ()
Call PMEXECUTE("REMOVE * FROM PM_DISPLAY_LIST IN INSTANCE WIN"
Call PMEXECUTE("ADD FEATURECLASS COAST TO PM_DISPLAY_LIST AT MAP")
End Sub

Sub MnuLv13Down_Click ()
Call PMEXECUTE("ZOOM DOWN 25 IN INSTANCE WINMAP")
End Sub

Sub MnuLv13K_Click ()
Call PMEXECUTE("REMOVE * FROM PM_DISPLAY_LIST IN INSTANCE WIN"
Call PMEXECUTE("ADD FEATURECLASS K50 TO PM_DISPLAY_LIST AT EI P")
Call PMEXECUTE("ADD FEATURECLASS K36 TO PM_DISPLAY_LIST AT EI P")
Call PMEXECUTE("ADD FEATURECLASS K37 TO PM_DISPLAY_LIST AT EI P")
Call PMEXECUTE("ADD FEATURECLASS K38 TO PM_DISPLAY_LIST AT EI P")
Call PMEXECUTE("ADD FEATURECLASS K39 TO PM_DISPLAY_LIST AT EI P")
Call PMEXECUTE("ADD FEATURECLASS K42 TO PM_DISPLAY_LIST AT EI P")
Call PMEXECUTE("ADD FEATURECLASS K47 TO PM_DISPLAY_LIST AT EI P")
Call PMEXECUTE("ADD FEATURECLASS K35 TO PM_DISPLAY_LIST AT EI P")

Call PMEXECUTE("ADD FEATURECLASS K54 TO PM_DISPLAY_LIST AT END IN P")
Call PMEXECUTE("ADD FEATURECLASS K57 TO PM_DISPLAY_LIST AT END IN P")
Call PMEXECUTE("ADD FEATURECLASS K72 TO PM_DISPLAY_LIST AT END IN P")
End Sub

Sub MnuLv13Left_Click()
Call PMEXECUTE("ZOOM LEFT 25 IN INSTANCE WINMAP")
End Sub

Sub MnuLv13LS_Click()
Call PMEXECUTE("REMOVE * FROM PM_DISPLAY_LIST IN INSTANCE WINMAP")
Call PMEXECUTE("ADD FEATURECLASS LS0001 TO PM_DISPLAY_LIST AT END NMAP")
Call PMEXECUTE("ADD FEATURECLASS LS0102 TO PM_DISPLAY_LIST AT END NMAP")
Call PMEXECUTE("ADD FEATURECLASS LS0205 TO PM_DISPLAY_LIST AT END NMAP")
Call PMEXECUTE("ADD FEATURECLASS LS0510 TO PM_DISPLAY_LIST AT END NMAP")
Call PMEXECUTE("ADD FEATURECLASS LS1020 TO PM_DISPLAY_LIST AT END NMAP")
Call PMEXECUTE("ADD FEATURECLASS LS2030 TO PM_DISPLAY_LIST AT END NMAP")
Call PMEXECUTE("ADD FEATURECLASS LS3000 TO PM_DISPLAY_LIST AT END NMAP")
End Sub

Sub MnuLv13P_Click()
Call PMEXECUTE("REMOVE * FROM PM_DISPLAY_LIST IN INSTANCE WINMAP")
Call PMEXECUTE("ADD FEATURECLASS P_07 TO PM_DISPLAY_LIST AT END IN AP")
Call PMEXECUTE("ADD FEATURECLASS P_08 TO PM_DISPLAY_LIST AT END IN AP")
Call PMEXECUTE("ADD FEATURECLASS P_09 TO PM_DISPLAY_LIST AT END IN AP")
Call PMEXECUTE("ADD FEATURECLASS P_10 TO PM_DISPLAY_LIST AT END IN AP")
End Sub

Sub MnuLv13Rain_Click()
Call PMEXECUTE("REMOVE * FROM PM_DISPLAY_LIST IN INSTANCE WINMAP")
Call PMEXECUTE("ADD FEATURECLASS R2185 TO PM_DISPLAY_LIST AT END MAP")
Call PMEXECUTE("ADD FEATURECLASS R2250 TO PM_DISPLAY_LIST AT END MAP")
Call PMEXECUTE("ADD FEATURECLASS R2350 TO PM_DISPLAY_LIST AT END MAP")
Call PMEXECUTE("ADD FEATURECLASS R2450 TO PM_DISPLAY_LIST AT END MAP")
Call PMEXECUTE("ADD FEATURECLASS R2550 TO PM_DISPLAY_LIST AT END MAP")
Call PMEXECUTE("ADD FEATURECLASS R2650 TO PM_DISPLAY_LIST AT END MAP")
Call PMEXECUTE("ADD FEATURECLASS R2750 TO PM_DISPLAY_LIST AT END MAP")
GISMAIN.FRM - 5

Call PMEXECUTE("ADD FEATURECLASS R2850 TO PM_DISPLAY_LIST AT END MAP")
End Sub

Sub MnuLvl3Right_Click()
Call PMEXECUTE("ZOOM RIGHT 25 IN INSTANCE WINMAP")
End Sub

Sub MnuLvl3Up_Click()
Call PMEXECUTE("ZOOM UP 25 IN INSTANCE WINMAP")
End Sub

EROEXEC.BAS - 1

Sub PMEXECUTE (S2QL_COMMAND As String)
GISMAIN.Text1.LinkItem = "PMENGINE"
GISMAIN.Text1.LinkTopic = "PMENGINE|S2QL"
GISMAIN.Text1.LinkMode = 2
GISMAIN.Text1.LINKTIMEOUT = 25000
GISMAIN.Text1.LinkExecute S2QL_COMMAND
Exit Sub
End Sub

EROSETUP.BAS - 1

Sub PMSETUP (SVALUE As String)
Call PMEXECUTE("SET WINMAP!WINDOW.BUTTONBAR TO FALSE")
End Sub
Sub Command1_Click()
    CODE = Val(TEXT1.Text)
    If CODE = 1 Then
        Beep
        Beep
        MsgBox "C FACTOR SECURED", 48, "LAYER INTERROGATOR"
        CROP.Hide
        Unload CROP
        Cls
        Load PCONS
        Beep
        Beep
        PCONS.Show
    Else
        Beep
        MsgBox "INITIATE DATABASE BUILDER", 16, "WARNING"
        CROP.Hide
        Unload CROP
    End If
End Sub

Sub Command1_Click()
    CODE = Val(SCRCHK.Text)
    If CODE = 2543969 Then
        Beep
        Beep
        MsgBox "WELCOME LAYER-INTERROGATOR", 48, "ACCESS"
        LAYER.Hide
        Unload LAYER
        Cls
        Load Rain
        Beep
        Beep
        Rain.Show
    Else
        Beep
        Beep
        MsgBox "INVALID USER", 16, "WARNING"
        Cls
        LAYER.Hide
        LAYER.Show
    End If
End Sub
KSOIL.FRM - 1

Sub Command1_Click ()
CODE = Val(TEXT1.Text)
If CODE = 1 Then
Beep
Beep
MsgBox "K FACTOR SECURED", 48, "LAYER INTERROGATOR"
Beep
Beep
Beep
MsgBox "PROCEED TO EROMAP LAYER ANALYZER", 48, "ACCESS"
KSOIL.Hide
Unload KSOIL
Cls
' Load P reform

Else
Beep
MsgBox "INITIATE DATABASE BUILDER", 16, "WARNING"
KSOIL.Hide
Unload KSOIL
End If
End Sub

PCONS.FRM - 1

Sub Command1_Click ()
CODE = Val(TEXT1.Text)
If CODE = 1 Then
Beep
Beep
Beep
MsgBox "P FACTOR SECURED", 48, "LAYER INTERROGATOR"
PCONS.Hide
Unload PCONS
Cls
' Load KSOIL
Beep
Beep
KSOIL.Show
Else
Else
Beep
MsgBox "INITIATE DATABASE BUILDER", 16, "WARNING"
PCONS.Hide
Unload PCONS
End If
End Sub
LS.FRM - 1

Sub Command1_Click ()
CODE = Val(TEXT1.Text)
If CODE = 1 Then
Beep
Beep
MsgBox "LS FACTOR SECURED", 48, "LAYER INTERROGATOR"
LS.Hide
Unload LS
Cls
Load CROP
Beep
Beep
CROP.Show
Else
MsgBox "INITIATE DATABASE BUILDER", 16, "WARNING"
LS.Hide
Unload LS
End If
End Sub

RAIN.FRM - 1

Sub Command1_Click ()
CODE = Val(TEXT1.Text)
If CODE = 1 Then
Beep
Beep
MsgBox "RAINFALL FACTOR SECURED", 48, "LAYER INTERROGATOR"
RAIN.Hide
Unload RAIN
Cls
Load LS
Beep
Beep
LS.Show
Else
Beep
Beep
MsgBox "INITIATE DATABASE BUILDER", 16, "WARNING"
RAIN.Hide
Unload RAIN
End If
End Sub
VERSION 2.00
Begin Form Sysdev
  BackColor = &H00C0E0FF&
  BorderStyle = 1 'Fixed Single
  Caption = "Ero-Map System Developer"
  ClientHeight = 3540
  ClientLeft = 1425
  ClientTop = 1785
  ClientWidth = 6840
  ControlBox = 0 'False
  ForeColor = &H00000000&
  Height = 3945
  Left = 1365
  LinkTopic = "Form2"
  MaxButton = 0 'False
  MinButton = 0 'False
  ScaleHeight = 3540
  ScaleWidth = 6840
  Top = 1440
  Width = 6960
End

Begin CommandButton Command1
  Caption = "Close"
  FontBold = -1 'True
  FontItalic = 0 'False
  FontName = "Times New Roman"
  FontSize = 12
  FontStrikethru = 0 'False
  FontUnderline = 0 'False
  Height = 375
  Left = 5400
  TabIndex = 5
  Top = 3000
  Width = 1095
End

Begin Line Line2
  BorderColor = &H0000FF00&
  BorderWidth = 2
  X1 = 360
  X2 = 6360
  Y1 = 360
  Y2 = 360
End

Begin Line Linel
  BorderColor = &H0000C000&
  BorderWidth = 2
  X1 = 360
  X2 = 6360
  Y1 = 720
  Y2 = 720
End

Begin Image Image2
  Height = 480
  Left = 3120
  Picture = (Icon)
  Top = 1200
  Width = 480
End

Begin Image Image1
Height = 480
Left = 2880
Picture = (Icon)
Top = 840
Width = 480

End

Begin Label Label5
BackColor = &H00C0E0FF&
Caption = "Associate Professor Dr. Taher Buyong"
FontBold = -1 'True
FontItalic = -1 'True
FontName = "Times New Roman"
FontSize = 13.5
FontStrikethru = 0 'False
FontUnderline = 0 'False
ForeColor = &H00000000&
Height = 495
Left = 2280
TabIndex = 4
Top = 2400
Width = 4455

End

Begin Label Label4
BackColor = &H00C0E0FF&
Caption = "Advisor"
FontBold = -1 'True
FontItalic = -1 'True
FontName = "Times New Roman"
FontSize = 13.5
FontStrikethru = 0 'False
FontUnderline = 0 'False
ForeColor = &H00FF0000&
Height = 375
Left = 600
TabIndex = 3
Top = 2400
Width = 1215

End

Begin Label Label3
BackColor = &H00C0E0FF&
Caption = "Michael Tang Chuoon Mun"
FontBold = -1 'True
FontItalic = -1 'True
FontName = "Times New Roman"
FontSize = 13.5
FontStrikethru = 0 'False
FontUnderline = 0 'False
Height = 495
Left = 2280
TabIndex = 2
Top = 1920
Width = 4215

End

Begin Label Label2
Alignment = 2 'Center
BackColor = &H00C0E0FF&
Caption = "Developer"
FontBold = -1 'True
CROP.FRM - 1

VERSION 2.00
Begin Form CROP
  BackColor = &H00C0E0FF&
  BorderStyle = 1 'Fixed Single
  Caption = "LAYER INTERROGATOR (CROP FACTOR)"
  ClientHeight = 3045
  ClientLeft = 1995
  ClientTop = 1950
  ClientWidth = 5850
  Height = 3450
  Left = 1935
  LinkTopic = "Form2"
  MaxButton = 0 'False
  MinButton = 0 'False
  MousePointer = 2 'Cross
  ScaleHeight = 3045
  ScaleWidth = 5850
  Top = 1605
  Width = 5970
Begin CommandButton Command1
  Caption = "OK"
  Height = 375
  Left = 4200
  TabIndex = 3
  Top = 2520
  Width = 975
End
Begin TextBox Text1
  Alignment = 2 'Center
  FontBold = -1 'True
  FontItalic = 0 'False
  FontName = "MS Sans Serif"
  FontSize = 12
  FontStrikethru = 0 'False
  FontUnderline = 0 'False
  Height = 420
  Left = 2280
  TabIndex = 2
  Top = 2280
  Width = 735
End
Begin Label Label2
  Alignment = 2 'Center
  BackColor = &H000000FF&
  Caption = "YES(1) / NO(2)"
  FontBold = -1 'True
  FontItalic = 0 'False
  FontName = "MS Sans Serif"
  FontSize = 12
  FontStrikethru = 0 'False
  FontUnderline = 0 'False
  ForeColor = &H00FF0000&
  Height = 375
  Left = 1680
  TabIndex = 1
  Top = 1680
  Width = 2175
End
CROP.FRM – 2

Begin Label Labell
  Alignment = 2 'Center
  BackColor = &H00000000&
  Caption = "DO YOU HAVE THE C FACTOR ?"
  FontBold = -1 'True
  FontItalic = 0 'False
  FontName = "MS Sans Serif"
  FontSize = 18
  FontStrikethru = 0 'False
  FontUnderline = 0 'False
  ForeColor = &H00FFFF00&
  Height = 975
  Left = 840
  TabIndex = 0
  Top = 600
  Width = 4095
End

Begin Image Imagel
  Height = 480
  Left = 2640
  Picture = (Icon)
  Top = 120
  Width = 480
End
End

SYSDEV.FRM – 1

Sub Command1_Click ()
'End display
Sysdev.Hide
Unload Sysdev
GISMAIN.Show
End Sub