# STATISTICAL PROPERTIES OF LINES DISTRIBUTION FOR TROPICAL WOOD RECOGNITION SYSTEM

### HAFIZZA BINTI ABDUL GHAPAR

A thesis submitted in fulfilment of the requirements for the award of the degree of Master of Philosophy

Malaysia-Japan International Institute of Technology Universiti Teknologi Malaysia

JANUARY 2022

### DEDICATION

This thesis is dedicated to my family, who have been my source of inspiration and gave strength and provide financial support to finish this study. To my lab mates who shared their word of advice and encouragement. Thank you for all your support along the way.

#### ACKNOWLEDGEMENT

Foremost, I would like to express my sincere gratitude to my supervisor, Dr Uswah Binti Khairuddin and Prof Datin Dr Rubiyah Yusof, for her patience, encouragement, guidance, critics, and immense knowledge. Without her guidance, this thesis would not have been the same as presented here.

My sincere thanks also went to my fellow labmates in Centre for Artificial Intelligence and Robotics (CAIRO) for their invaluable help throughout my study and for all the fun we had in the last two years. Their keen interest, encouragement and valuable advice were a great help in preparing this thesis.

Finally, I would like to express my very profound gratitude to my family member for supporting me throughout my years of study. This accomplishment would not have been possible without them. Thank you.

#### ABSTRACT

An automated tropical wood recognition system has been developed by Centre for Artificial Intelligence & Robotics (CAIRO), Universiti Teknologi Malaysia (UTM) based on machine vision to emulate the experts known as KenalKayu. The system used Statistical Properties of Pores Distribution (SPPD) feature extractor and K-Nearest Neighbor (KNN) classifier which have been proven to increase the system's accuracy. Unfortunately, when more wood species were added to the system's database, it reduces the accuracy of the system. Therefore, providing additional features that are representation of each species is one way to improve this issue. As the wood surface pattern is not only defined by pores but lines as well, this thesis presents additional new feature extraction method based on Statistical Properties of Line Distribution (SPLD) to capture the discriminant line features of each species and K-Nearest Neighbor (KNN) is used as classifier. The results of experiments showed that when used by itself as a feature extractor, the SPLD managed to achieve 88% accuracy, and the accuracy increased to 99.5% when combined with SPPD features and 100% accuracy was achieved when SPPD and Basic Grey Level Aura Matrix (BGLAM) features were used in combination. In conclusion, the SPLD method is an essential customized feature extractor and could be used as an alternative to adequately identify wood species. Hence, in the future, other discriminant features can also be added for wood identification purposes.

#### ABSTRAK

Sistem pengecaman kayu tropika automatik telah dibangunkan oleh Pusat Kecerdasan Buatan & Robotik (CAIRO), Universiti Teknologi Malaysia (UTM) berdasarkan visi mesin untuk mencontohi pakar yang dikenali sebagai KenalKayu. Sistem ini menggunakan pengekstrak ciri Sifat Statistik Taburan Liang (SPPD) dan pengelas Kejiranan Terdekat-K (KNN) yang telah terbukti meningkatkan ketepatan sistem. Malangnya, apabila lebih banyak spesies kayu ditambahkan pada pangkalan data sistem, ia mengurangkan ketepatan sistem. Oleh itu, menyediakan ciri tambahan yang mewakili setiap spesies adalah satu cara untuk memperbaiki isu ini. Memandangkan corak permukaan kayu bukan sahaja ditakrifkan oleh liang tetapi garisan juga, tesis ini membentangkan kaedah pengekstrakan ciri baharu tambahan berdasarkan Sifat Statistik Taburan Garis (SPLD) untuk mengenal pasti ciri garis diskriminasi setiap spesies dan Kejiranan Terdekat-K (KNN) digunakan sebagai pengelas. Keputusan eksperimen menunjukkan bahawa jika ianya digunakan dengan sendiri sebagai pengekstrak ciri, SPLD berjaya mencapai ketepatan 88%, dan ketepatan tersebut meningkat kepada 99.5% apabila digabungkan dengan ciri SPPD manakala ketepatan 100% dicapai apabila SPPD dan Matrik Aura Aras Kelabu Asas (BGLAM) digunakan secara gabungan. Kesimpulannya, kaedah SPLD adalah pengekstrak ciri khas yang penting dan boleh digunakan sebagai alternatif untuk mengenal pasti spesies kayu. Oleh itu, pada masa hadapan, ciri-ciri diskriminasi lain juga boleh ditambah untuk tujuan pengecaman kayu.

## TABLE OF CONTENTS

# TITLE

D	DECLA	RATION	iii
D	DEDIC	ATION	iv
А	CKNC	DWLEDGEMENT	v
Α	BSTR	ACT	vi
Α	BSTR	AK	vii
Т	ABLE	OF CONTENTS	viii
L	JIST O	F TABLES	xii
L	<b>IST O</b>	F FIGURES	xiii
L	<b>IST O</b>	F ABBREVIATIONS	xvii
L	JIST O	F SYMBOLS	xviii
L	IST O	F APPENDICES	xix
CHAPTER 1	1 I	NTRODUCTION	1
1.	.1 P	Problem Background	1
1.	.2 P	Problem Statement	4
1.	.3 R	Research Objective	5
1.	.4 R	Research Scope	6
1.	.5 T	Thesis Contribution	6
1.	.6 T	Thesis Outline	7
CHAPTER 2	2 I	LITERATURE REVIEW	9
2.	.1 Iı	ntroduction	9
2.	.2 V	Wood Identification	9
	2	2.2.1 Wood Identification Procedure	10
	2	2.2.2 Wood identification via Comparison	12
	2	2.2.3 Wood Dichotomous Keys	13
2.	.3 C	Classification of Wood	15

	2.4	Struct	tructure of Wood				16		
	2.5 Machine Vision Software for Wood Identification				21				
	2.6	Previo Recog	ous Reseat inition Ken	rch on Au alKayu	itomated W	/ood	Specie	28	25
	2.7	Overv	iew of Lin	e Detection	Technique				30
	2.8	Gestal	lt Theory						32
		2.8.1	Proximity	4					32
		2.8.2	Similarity	7					33
		2.8.3	Continuit	У					33
2.8.4 Closure					34				
		2.8.5	Connecte	dness					34
	2.9	Gestal	tic Groupi	ng of Line S	legment Dete	ectior	1		35
	2.10 Research Gap				37				
	2.11	Chapt	er Summar	У					37
CHAPTE	R 3	RESE	CARCH M	ETHODOI	LOGY				39
	3.1	Introd	uction						39
	3.2	2 Overview of Proposed Framework				40			
		3.2.1	Image Ac	equisition					40
		3.2.2	Feature E	xtraction					45
			3.2.2.1	Grey Level	l Co-Occurre	ence l	Matrix	(GLCM)	45
			3.2.2.2	Basic Grey	Level Aura	Matr	rix (BG	LAM)	46
			3.2.2.3	Statistical (SPPD)	Properties	of	Pores	Distribu	tion 47
	3.3	Line E	Extraction I	Method					48
		3.3.1	Canny Ec	lge					49
		3.3.2	Hough Ti	ransform					50
		3.3.3	Prewitt						52
		3.3.4	Sobel						53
		3.3.5	Roberts c	ross					54
		3.3.6	Laplacian	ı					55
		3.3.7	Histogran	n equalizatio	on				57
		3.3.8	Contours	, Corners an	d T-Junctior	15			58

		3.3.9	Line Seg	ment Detector (LSD)	59
	3.4	Gestal	tic Groupi	ng of Line Segments (GG)	60
		3.4.1	A Contra	rio Model	61
3.5		3.4.2 Algorithm			64
		Statist	ical Proper	rties of Line Distribution (SPLD)	65
	3.6	Classi	fier		69
		3.6.1	K-Neares	t Neighbor (KNN) classifier	69
		3.6.2	Performation	nce metrics for classification	70
			3.6.2.1	Confusion Matrix	70
			3.6.2.2	Cohen's Kappa	72
	3.7	Chapte	er Summar	у	73
CHAPTER	<b>X</b> 4	RESU	LTS AND	DISCUSSION	74
	4.1	Introd	uction		74
	4.2	Results of Experimental Data		imental Data	74
		4.2.1	Database	A1	75
			4.2.1.1	Evaluation of Statistical Properties of L Distribution (SPLD) as Feature Extraction	Lines 76
			4.2.1.2	Fusion of SPLD and BGLAM as Fea Extract ion	ature 79
			4.2.1.3	Fusion of SPLD and SPPD as Feature Exion	tract 82
			4.2.1.4	Fusion of SPLD, SPPD and BGLAM as Fea Extract ion	ature 84
		4.2.2	Database	A2	85
			4.2.2.1	Evaluation of Statistical Properties of L Distribution (SPLD) as Feature Extraction	Lines 85
			4.2.2.2	Fusion of SPLD and BGLAM as Fea Extract ion	ature 88
			4.2.2.3	Fusion of SPLD and SPPD as Feature Exion	tract 90
			4.2.2.4	Fusion of SPLD, SPPD and BGLAM as Fea Extract ion	ature 93
		4.2.3	Summary	v of Combine Method	95
	4.3	SPLD	Features A	Analysis	96

4.4	Result Analysis	104	
4.5	Chapter Summary	106	
CHAPTER 5	CONCLUSION	107	
5.1	Conclusion	107	
5.2	Contribution to Knowledge	108	
5.3	Limitation	109	
5.4	Future Works	110	
REFERENCES		111	
LIST OF PUBLI	LIST OF PUBLICATIONS		

### LIST OF TABLES

TABLE NO.	TITLE	PAGE
Table 2.1	Summary of Wood Identification on Machine Vision	23
Table 2.2	Summary of Previous Research on KenalKayu	28
Table 3.1	Software and hardware specification	42
Table 3.2	Wood species	43
Table 3.3	A confusion matrix for binary classification	71
Table 3.4	Evaluation measures for binary class data set	71
Table 4.1	Summary Result of SPLD	77
Table 4.2	Detailed accuracy of SPLD by class	77
Table 4.3	Summary Result of SPLD and BGLAM	80
Table 4.4	Detailed accuracy of SPLD and BGLAM by class	80
Table 4.5	Summary Result of SPLD and SPPD	82
Table 4.6	Detailed accuracy of SPLD and SPPD by class	83
Table 4.7	Summary Result of SPLD, SPPD and BGLAM	85
Table 4.8	Summary Result of SPLD	86
Table 4.9	Detailed accuracy of SPLD by class	86
Table 4.10	Summary Result of SPLD and BGLAM	89
Table 4.11	Detailed accuracy of SPLD and BGLAM by class	89
Table 4.12	Summary Result of SPLD and SPPD	91
Table 4.13	Detailed accuracy of SPLD and SPPD by class	91
Table 4.14	Summary Result of SPLD, SPPD and BGLAM	93
Table 4.15	Detailed accuracy of SPLD, SPPD and BGLAM by class	94
Table 4.16	Classification Accuracy of Wood Species	95

### LIST OF FIGURES

FIGURE NO	. TITLE				
Figure 2.1	The three wood surfaces; (X) cross section surface, (T) tangential surface and (R) radial surface. [11]	10			
Figure 2.2	Wood block secured in vise	11			
Figure 2.3	Wood block hold by hand	11			
Figure 2.4	Viewing wood anatomy image using hand lens	12			
Figure 2.5	Part of dichotomous key [7]	14			
Figure 2.6	Example of macroscopic anatomy image	16			
Figure 2.7	A cut-through of a tree trunk [19]	17			
Figure 2.8	Characteristic of cell structure	18			
Figure 2.9	The sample of hard maple (left) and silver maple (right) [20]	19			
Figure 2.10	The sample of hackberry (left) and katalox (right) [20]	19			
Figure 2.11	The sample of Sheoak [20]	20			
Figure 2.12	The sample of Yellow Poplar [20]	20			
Figure 2.13	The sample of persimmon [20]	21			
Figure 2.14	Proximity [54]	33			
Figure 2.15	Similarity [54]	33			
Figure 2.16	Continuity [54]	34			
Figure 2.17	Closure [54]	34			
Figure 2.18	Connectedness [54]	35			
Figure 2.19	Original image, LSD line segments, good continuation and bars (from left to right) [59]	36			
Figure 3.1	Process flow for the wood recognition system	39			
Figure 3.2	Wood sample	40			
Figure 3.3	CCD camera	41			
Figure 3.4	MAXGear Digital Microscope HD USB Camera	41			
Figure 3.5	Example of Wood Anatomy	44			

Figure 3.6	Data collection process					
Figure 3.7	Four directions for generation of GLCM					
Figure 3.8	An example of BGLAM	46				
Figure 3.9	Homomorphic image (left) black and white image showing the black pores (right) and black and white image showing the "white pores" (below)	48				
Figure 3.10	Example of Canny Edge					
Figure 3.11	Line Polar Coordinates	50				
Figure 3.12	Original image	50				
Figure 3.13	Peak in the HT of the wood image	51				
Figure 3.14	Line detected by HT	51				
Figure 3.15	Mask for detection of vertical edges (left) and horizontal edges (right)	52				
Figure 3.16	Example of Prewitt	52				
Figure 3.17	Mask for detection of vertical edges (left) and horizontal edges (right)					
Figure 3.18	Example of Sobel	53				
Figure 3.19	Mask for detection of vertical edges (left) and horizontal edges (right)					
Figure 3.20	Example of Roberts	54				
Figure 3.21	Positive Laplacian Operator (left) and Negative Laplacian Operator (right)	55				
Figure 3.22	Original Image	55				
Figure 3.23	Laplacian 3x3	56				
Figure 3.24	Laplacian 5x5	56				
Figure 3.25	Example of a wood anatomy image before and after histogram equalization	57				
Figure 3.26	Block diagram of the algorithm	58				
Figure 3.27	Original image (left) and Contours image (right)	58				
Figure 3.28	Mask for detection of image gradient	59				
Figure 3.29	Original image (left) and LSD image (right)	59				
Figure 3.30	Instances of a non-local alignment (1), a bar (2) and a good continuation (3) Gestalts [59]					

Figure 3.31	Example of search space [59]			
Figure 3.32	Original image			
Figure 3.33	LSD (initial line segment)			
Figure 3.34	Good Continuation			
Figure 3.35	Bars (parallelism)	67		
Figure 3.36	Non-Local Alignment	67		
Figure 3.37	Residual	68		
Figure 4.1	Confusion Matrix of SPLD	78		
Figure 4.2	Bintangor (left) misclassified as Terentang (right)	79		
Figure 4.3	Sepetir (left) misclassified as Penarahan (right)	79		
Figure 4.4	Confusion Matrix of SPLD and BGLAM	81		
Figure 4.5	Comparison graph between Penarahan and Sepetir	82		
Figure 4.6	Confusion Matrix of SPLD and SPPD	84		
Figure 4.7	Gerutu (left) misclassified as Kungkur (right)	84		
Figure 4.8	Confusion Matrix of SPLD	87		
Figure 4.9	Dissimilarity between three wood images of the same species. First column shows Bintangor, second column shows Durian and third column shows Terentang.	88		
Figure 4.10	Confusion Matrix of SPLD and BGLAM	90		
Figure 4.11	Confusion Matrix of SPLD and SPPD	92		
Figure 4.12	Bintangor (left) misclassified as Gerutu (right)	92		
Figure 4.13	Confusion Matrix of SPLD, SPPD and BGLAM	94		
Figure 4.14	Initial Line Segments	96		
Figure 4.15	Good Continuation	97		
Figure 4.16	Parallelism	97		
Figure 4.17	Non-Local Alignments	98		
Figure 4.18	Residual	98		
Figure 4.19	Original 3D scatter plot 1	99		
Figure 4.20	3D Scatter Plot 1 from different angle	99		
Figure 4.21	Original 3D scatter Plot 2	100		

Figure 4.22	3D Scatter Plot 2 from different angle			
Figure 4.23	Matrix of scatter plots by Plot 1			
Figure 4.24	Matrix of scatter plots by Plot 2			
Figure 4.25	Example of misclassified species Melunak on wood images (a) Original Image, (b) LSD line segments (initial line segments), (c) pairs of parallel line segments (bars), (d) Good Continuation, (e) Non-local alignment, (f) Residual, (g) black and white image showing the black pores and (h) black and white image showing the "white pores"	105		
	pores	105		

# LIST OF ABBREVIATIONS

AIKO	-	Automatic wood identification tool
BGLAM	-	Basic Grey Level Aura Matrix
BPNN	-	Back propagation neural network
CAIRO	-	Centre for Artificial Intelligence and Robotics
CCD	-	Charge-coupled device
FN	-	False negative
FP	-	False Positive
FRIM	-	Forest Research Institute of Malaysia
GA	-	Genetic Algorithm
GG	-	Gestaltic Grouping
GLCM	-	Grey level co-occurrence matrix
GMRF	-	Gaussian Markov random field
HT	-	Hough Transform
KDA	-	Kernel Discriminant Analysis
KNN	-	K-Nearest Neighbor
KSOM	-	Kohonen Self-Organizing Map
LBP	-	Local Binary Pattern
LDA	-	Linear Discriminant Analysis
LSD	-	Line Segment Detector
MTIB	-	Malaysia Timber Industry Board
MV	-	Machine vision
NFA	-	Number of false alarms
NLA	-	Non-local alignments
SPLD	-	Statistical Properties of Lines Distribution
SPPD	-	Statistical Properties of Pores Distribution
TN	-	True Negative
TP	-	True Positive
UTM	-	Universiti Teknologi Malaysia
VSDP	-	Vision System Development Platform

### LIST OF SYMBOLS

ρ	-	Maximum distance between the origin and the line tip
θ	-	Maximum acceptable angle
$\Delta \theta$	-	An angle threshold parameter
$\mathfrak{I}^{ ho}$	-	NFA of parallel line event
$\varsigma^{k,\rho}$	-	NFA of non - local alignment
$\wp^{k, ho, heta}$	-	NFA of good continuation
Ν	-	Total number of line segment
Κ	-	Maximum number of line segments in a good continuation

### LIST OF APPENDICES

APPENDIX		TITLE	PAGE
Appendix A	Algorithm 1		118
Appendix B	Algorithm 2		119
Appendix C	Algorithm 3		120
Appendix D	Algorithm 4		121
Appendix E	Algorithm 5		122

#### **CHAPTER 1**

#### **INTRODUCTION**

#### **1.1 Problem Background**

For a long time, tropical rainforests have been regarded as one of the world's most productive forest. In this world, the tropical rainforests can only be found in South America, Central Africa and Southeast Asia. Malaysia is located in South East Asia and a home to over 2,650 tree species, with natural forest occupying more than 55.3 percent of its land area. According to Malaysia Timber Industry Board (MTIB), since June 2019, Malaysia has 4.34 million hectares of certified forests endorsed by the Program for the Endorsement of Forest Certification scheme to fulfill the demand for certified timber products [1]. Malaysia forests provide a large variety of useful materials, ranging from medicinal plants and food to fiber and timber [2].

Furthermore, Malaysia is one of the world's top tropical timber producers and top 10 furniture producers. The timber industry is an important contributor to the Malaysian economy. In 2019, Malaysia earned RM 22.5 billion from timber exports [3]. In fact, Malaysian timber currently shipped to more than 162 countries, with India being the major importer. However, deforestation is a critical threat as the country is still developing. Some timber traders tend to mix different types of wood and even try to export an endangered wood species to increase their profit margin. Nevertheless, the remaining forests face challenges from unsustainable logging, illegal removal of forest resources and encroachment [4]. Various measures have been proposed to combat this problem including wood identification by wood experts at various checkpoints.

It is easy to identify a tree by observing its flowers, fruits and leaves. However, once the tree is cut down and become wooden logs, it becomes very difficult to identify the tree species and the expert must rely on their physical characteristics for species identification. Wood species has different appearances such as shapes, smells, odor and colors of the leaves. These characteristics are called macroscopic features and can be used to indicate whether a wood is labeled correctly, or to which species it is likely to belong to. Recent wood can often be identified by macroscopic characteristics, particularly by color, gloss, odor, weight and structure. As such characteristics are generally modified or destroyed in fossil, historic or carbonized wood, only a few species or species groups of the indigenous flora can be identified with the naked eye or only with the aid of a magnifier (5 to 20x). Macroscopic keys typically have fewer features than microscopic keys. Several species have identical macroscopic characters instead of macroscopic features [5].

The microscopic features on wood cross sectional surfaces are useful for identification and determining the wood species because different kind of wood species will have a distinctive microscopic feature. Macroscopic features are usually generic whereas microscopic features necessitate a more thorough anatomical inspection with the aid of IAWA List of Microscopic Features for Hardwood Identification [5]. The anatomical features in this list composed of growth rings, porosity, vessel arrangement, vessel groupings, outline of solitary vessels, perforation plate type, intervessel pit arrangement and size, type of fiber wall pitting, fiber wall thickness and length, axial parenchyma distribution, ray width, aggregate rays, cellular composition of rays, storied structure, intercellular canals and their cellular location.

The wood detection and classification process are currently performed manually by wood experts with handheld lens or unaided eye [6]. A dichotomous key [7] is provided as a guideline for the experts to determine the wood species. However, the conventional technique in performing wood identification can lead to difficulties in using keys due to errors in recognizing feature. In addition, lack of background or training in wood identification can lead to a feature being misinterpreted. Apart from that, a feature may also be interpreted differently from the way a key constructor intended. Fault in recognizing a feature is likely to be a cause of misidentification of the wood species. Wood recognition is mainly done by well-trained wood experts. Regrettably, it takes a long period of time to train a wood expert which is qualified to identify wood species with high accuracy because there are more than 3000 wood species in Malaysia. The process of examining every unit of wood by a human inspector can be tedious and time consuming. There will also be a problem in identifying the timber accurately especially the lesser-known species. Wood experts are not abundant in the market today to meet the demand in the industry which involves in raw wood identification.

Therefore, it may not be feasible if the customs need to check and identify the species of wood before they are exported out of the country. Manufacturers can also use the technique to check and verify whether the wood materials acquired are from the correct species, as different type of wood species will have different value, verification of the species is important to avoid unnecessary loss for the manufacturers. In view of these factors, a systematic method is essential so that the identification of wood species can be carried out quickly and accurately.

To mitigate this problem, an automated visual inspection may help users to recognize wood species in just an instant. It has been implemented to a variety of applications and has been used for century to replace humans with intelligent machines in different industries. Centre for Artificial Intelligence and Robotics (CAIRO), Universiti Teknologi Malaysia (UTM) in particular Khalid et al. [8] had developed a tropical wood recognition system based on wood macroscopic anatomy called KenalKayu. The research has been done since 2002 and it has been improved in so many ways just to ensure the system is able to recognize the wood species. This system may replace the conventional technique in performing wood identification which is exposed to human error and biasedness.

### **1.2 Problem Statement**

The main problem in wood recognition system is the lack of discriminative features of the texture image and also very discriminative features among inter class species [9] as well as noises due to illuminations, or uncontrolled environment. Some of the wood species have similar pattern with other and some have different pattern even though they are from the same species. So, there is a need on how to develop more accurate algorithm for wood species recognition based on texture analysis. Usually, the wood experts do this process manually and they used dichotomous key [10] which is the traditional way to classify the wood species by looking at the tree barks and the pattern of the wood cross-section. The wood features such as the size of pores, the density of pores, etc. depends very much on the age, weather and other factors, contributing to the irregularities of the features. Due to these factors, classification of the wood species remains a challenging task.

Many studies have been done in area of wood recognition system. Researchers like [8], [9], [11]–[14] had been working on automated tropical wood recognition to improve the system. The work includes the use of grey level cooccurrence matrix (GLCM) technique for extracting the texture features of the wood species and using back propagation neural network (BPNN) for classification. Yusof et al. [15] adopted fusion of two feature sets using multi feature extractor technique. Two feature extraction methods were used in this system is grey level co-occurrence matrix approach (GLCM) and Gabor filters. Khalid et al. [16] has developed a preclassification stage to solve the problem of nonlinearity of tropical wood species separation boundaries using K-Means Clustering and Kernel Discriminant Analysis (KDA).

In later development, Khairuddin et al. [12] introduced Genetic Algorithm (GA) as feature selection to improve the accuracy of wood species recognition, in particular to reduce the redundant features which are not considered as discriminatory enough for accurate classification. Their work showcased an improved automated tropical wood recognition system that can perform accurate wood identification for 70 wood databases in an offline mode. Unfortunately, when

more woods were added in the database, or when the testing was done online with new wood images, the accuracy of the system drops.

It is worth taking a step back and looks at how experts identify the wood in manual ways using the dichotomous keys. As features of wood rely heavily on pores characteristics, Khairuddin et al. [12] proposed a new feature extraction method specifically for tropical wood called the Statistical Properties of Pores Distribution (SPPD). The feature extraction mimics manual procedure of tropical wood species recognition which is observing the pores characteristics such as size and density of pores. The SPPD feature extractors managed to increase the system's accuracy.

However, the SPPD method ignores another very important wood microscopic feature that are used by experts in the dichotomous key, the line characteristics. As we know, the most prevailing features that were usually used by experts to examine wood species are by looking at lines thickness, lines length and whether the lines are continuous or cut into several short lines, parenchyma lines or ray lines. Some of the wood does not have any lines at all. This shows that lines feature in wood cross sectional surface may be the key or important features that should be added in the automated wood recognition system.

#### **1.3 Research Objective**

The prototype of the intelligent tropical wood recognition had successfully been developed but the system performances need to be improved for the industrial use. The objectives of this thesis are as follows:

- (a) To develop a new feature extraction method for automated tropical wood recognition system based on the line properties and distribution using Gestaltic Grouping of Line Segments detection algorithm.
- (b) To evaluate and validate the newly developed line feature extraction method for automated tropical wood species identification.

(c) To determine the most effective features extractor that provides the highest accuracy during classification in automatically recognizing the wood species.

#### **1.4** Research Scope

The scopes of this research are as follows:

- (a) The proposed method will be trained and tested using images from 20 wood species that were taken using the new microscopic camera. Two databases will be used in this research which are Database A1 and Database A2.
- (b) Several algorithms are used for development of the system such as a contrario model is used for detecting the line segment, SPLD as a feature extraction and K-Nearest Neighbor (KNN) as a classifier.
- (c) The recognition of the tropical wood species focuses on wood species in Malaysia only and based on the wood anatomy images.
- Input images are all in grayscale because the macroscopic wood classification does not rely on the wood colour.

### 1.5 Thesis Contribution

The major contributions described in this thesis are as follows:

- (a) A novel feature extraction method based on wood microscopic line features namely Statistical Properties of Line Distribution (SPLD) technique to capture the discriminant line features of each species.
- (b) Finding the best combination of feature extraction methods including the new line-based features for accurate tropical wood species identification.

### 1.6 Thesis Outline

This thesis is organized into five chapters described as follows:

- (a) Chapter 1 introduces background information and problem on the tropical wood identification. It also consists of the scopes and objectives, contributions, and outline of the thesis.
- (b) Chapter 2 provides a critical review on the specific topics of wood recognition based on anatomical features, previous research on automated wood species identification and literature review on line extraction.
- (c) Chapter 3 explains the methodologies and research flow adopted in this study starting from the data acquisition, image processing, feature extraction and classifier techniques used.
- (d) Chapter 4 presents the results and discussion of the experiments conducted using the proposed methodologies described in Chapter 3. A critical analysis of the finding is also presented.
- (e) Chapter 5 presents the conclusion of this research, the limitation of study and the recommended future works that can improve upon the findings.

#### REFERENCES

- M. K. P. P. dan Komoditi and L. P. K. Malaysia, *NATIP: National Timber Industry Policy*, 2009-2020. Ministry of Plantation Industries and Commodities, 2009.
- [2] "Malaysian Timber Council." [Online]. Available: http://www.mtc.com.my/publication-Brochures-Species.php. [Accessed: 11-Oct-2018].
- [3] "Malaysian timber companies and the pandemic Global Wood Markets Info." [Online]. Available: https://www.globalwoodmarketsinfo.com/malaysian-timber-companiespandemic/. [Accessed: 17-Feb-2021].
- [4] "Malaysia Country Overview To Aid Implementation Of The Eutr," 2020.
- [5] C. Schirarend, "Wheeler, E.; Baas, P.; Gasson, P. E. (eds.), IAWA List of Microscopic Features for Hardwood Identification. IAWA Bull. n. ser. 10 (3), S. 219 bis 332, 190 Abb., Leiden, 1989. Preis. US \$ 20,-," *Feddes Repert.*, vol. 101, no. 11–12, pp. 600–600, 2008, doi: 10.1002/fedr.19901011106.
- [6] E. Wheeler and P. Baas, "Wood Identification -A Review," *IAWA J.*, vol. 19, pp. 241–264, 1998, doi: 10.1163/22941932-90001528.
- P. K. B. Menon, Structure and identification of Malayan woods / P.K. Balan Menon; revised by Ani Sulaiman and Lim Seng Choon. Kepong, Kuala Lumpur: Forest Research Institute Malaysia, 2004.
- [8] M. Khalid, E. L. Y. Lee, R. Yusof, and M. Nadaraj, "Design of an Intelligent Wood Species Recognition System," *Int. J. Simul. Syst. Sci. Technol.*, vol. 9, no. 3, pp. 9–19, 2008.
- [9] R. Yusof, N. R. Rosli, and M. Khalid, "Tropical Wood Species Recognition Based on Gabor Filter," 2009 2nd Int. Congr. Image Signal Process., pp. 1–5, 2009, doi: 10.1109/CISP.2009.5302660.
- [10] "Wood Identification." [Online]. Available: http://www4.ncsu.edu/~xylem/WPS202/ident.htm. [Accessed: 30-Mar-2018].
- [11] R. Yusof *et al.*, "A Study of Feature Extraction and Classifier Methods for Tropical Wood Recognition System," *IEEE Reg. 10 Annu. Int. Conf.*

*Proceedings/TENCON*, vol. 2018-Octob, no. October, pp. 2034–2039, 2019, doi: 10.1109/TENCON.2018.8650411.

- [12] U. Khairuddin, R. Yusof, and M. Khalid, "Optimized feature selection for improved tropical wood species recognition system," *ICIC express Lett. Part B Appl.*, vol. 2, no. 2, pp. 441–446, 2011.
- [13] A. Ahmad, R. Yusof, and Y. Mitsukura, "Pheromone-based Kohonen Self-Organizing Map (PKSOM) in clustering of tropical wood species: Performance and scalability," 2015 10th Asian Control Conf. Emerg. Control Tech. a Sustain. World, ASCC 2015, vol. 2015, no. June, pp. 2384–2388, 2015, doi: 10.1109/ASCC.2015.7244589.
- [14] R. Yusof, M. Khalid, and A. S. M. Khairuddin, "Fuzzy data management on pores arrangement for tropical wood species recognition system," in 2013 Science and Information Conference, 2013, pp. 529–535.
- [15] R. Yusof, N. R. Rosli, and M. Khalid, "Using Gabor filters as image multiplier for tropical wood species recognition system," *UKSim2010 - UKSim 12th Int. Conf. Comput. Model. Simul.*, pp. 289–294, 2010, doi: 10.1109/UKSIM.2010.61.
- [16] A. Khairuddin, M. Khalid, and R. Yusof, "Using Two Stage Classification for Improved Tropical Wood Species Recognition System," in *Smart Innovation*, *Systems and Technologies*, vol. 11, 2011, pp. 305–314.
- [17] R. J. Pankhurst, *Biological identification : the principles and practice of identification methods in biology*. Arnold London, 1978.
- [18] R. B. Hoadley, "Identifying Wood. Accurate results with simple tools," *IAWA* J., vol. 12, no. 1, p. 84, 1991, doi: https://doi.org/10.1163/22941932-90001207.
- [19] "DoITPoMS TLP Library The structure and mechanical behaviour of wood -The structure of wood (II)." [Online]. Available: https://www.doitpoms.ac.uk/tlplib/wood/structure\_wood\_pt2.php. [Accessed: 25-Feb-2021].
- [20] "Hardwood Anatomy | The Wood Database." [Online]. Available: https://www.wood-database.com/wood-articles/hardwood-anatomy/.
   [Accessed: 26-Feb-2021].
- [21] X. J. Tang, Y. H. Tay, N. A. Siam, and S. C. Lim, "MyWood-ID: Automated macroscopic wood identification system using smartphone and macro-lens,"

*ACM Int. Conf. Proceeding Ser.*, no. November, pp. 37–43, 2018, doi: 10.1145/3293475.3293493.

- [22] P. Ravindran, B. J. Thompson, R. K. Soares, and A. C. Wiedenhoeft, "The XyloTron: Flexible, Open-Source, Image-Based Macroscopic Field Identification of Wood Products," doi: 10.3389/fpls.2020.01015.
- [23] N. Rosa da Silva *et al.*, "Automated classification of wood transverse crosssection micro-imagery from 77 commercial Central-African timber species," *Ann. For. Sci.*, vol. 74, no. 2, 2017, doi: 10.1007/s13595-017-0619-0.
- [24] R. Jordan, F. Feeney, N. Nesbitt, and J. A. Evertsen, "Classification of wood species by neural network analysis of ultrasonic signals," *Ultrasonics*, vol. 36, no. 1–5, pp. 219–222, Feb. 1998, doi: 10.1016/S0041-624X(97)00148-0.
- [25] T. Brandtberg, "Individual tree-based species classification in high spatial resolution aerial images of forests using fuzzy sets," *Fuzzy Sets Syst.*, vol. 132, no. 3, pp. 371–387, 2002, doi: https://doi.org/10.1016/S0165-0114(02)00049-0.
- [26] K. Wang and X. Bai, "Research on Classification of Wood Surface Texture based on Feature Level Data Fusion," in 2007 2nd IEEE Conference on Industrial Electronics and Applications, 2007, pp. 659–663, doi: 10.1109/ICIEA.2007.4318489.
- [27] R. Damayanti *et al.*, "LignoIndo: Image database of Indonesian commercial timber," *IOP Conf. Ser. Earth Environ. Sci.*, vol. 374, no. 1, 2019, doi: 10.1088/1755-1315/374/1/012057.
- [28] M. Tuceryan and A. Jain, "Handbook of pattern recognition & computer vision," *Singapore World Sci.*, pp. 207–248, 1998.
- [29] M. Nasirzadeh, A. A. Khazael, and M. bin Khalid, "Woods Recognition System Based on Local Binary Pattern," 2010 2nd Int. Conf. Comput. Intell. Commun. Syst. Networks, no. 2, pp. 308–313, 2010, doi: 10.1109/CICSyN.2010.27.
- [30] M. Khalid, R. Yusof, and A. S. M. Khairuddin, "Tropical wood species recognition system based on multi-feature extractors and classifiers," *Proc.* 2011 2nd Int. Conf. Instrum. Control Autom. ICA 2011, no. November, pp. 6–11, 2011, doi: 10.1109/ICA.2011.6130117.
- [31] M. K. Rubiyah Yusof, Uswah Khairuddin, "New Mutation Operation For Faster Convergence In Genetic Algorithm Feature Selection," *Int. J. Innov.*

Comput. Inf. Control, vol. 8, no. 10 B, pp. 7363–7379.

- [32] A. Ahmad and R. Yusof, "Clustering the Tropical Wood Species Using Kohonen Self-Organizing Map (KSOM)," *Proc. 2nd Int. Conf. Adv. Comput. Sci. Eng.*, no. CSE, pp. 16–19, 2013, doi: 10.2991/cse.2013.5.
- [33] C. Akinlar and C. Topal, "Edlines: Real-time line segment detection by Edge Drawing (ed)," in 2011 18th IEEE International Conference on Image Processing, 2011, pp. 2837–2840, doi: 10.1109/ICIP.2011.6116138.
- [34] J. B. Burns, A. R. Hanson, and E. M. Riseman, "Extracting Straight Lines," *IEEE Trans. Pattern Anal. Mach. Intell.*, vol. PAMI-8, no. 4, pp. 425–455, 1986, doi: 10.1109/TPAMI.1986.4767808.
- [35] R. G. von Gioi, J. Jakubowicz, J. Morel, and G. Randall, "LSD: A Fast Line Segment Detector with a False Detection Control," *IEEE Trans. Pattern Anal. Mach. Intell.*, vol. 32, no. 4, pp. 722–732, 2010, doi: 10.1109/TPAMI.2008.300.
- [36] S. Kumar, M. Singh, and S. D.K., "Comparative Analysis of Various Edge Detection Techniques in Biometric Application," *Int. J. Eng. Technol.*, vol. 8, no. 6, pp. 2452–2459, 2016, doi: 10.21817/ijet/2016/v8i6/160806409.
- [37] G. T. Shrivakshan, "A Comparison of various Edge Detection Techniques used in Image Processing," *Int. J. Comput. Sci. Issues*, vol. 9, no. 5, pp. 269– 276, 2012.
- [38] C.-A. Boiangiu and B. Raducanu, "Robust Line Detection Methods," *Proc.* 9th WSEAS Int. Conf. Int. Conf. Autom. Inf., no. June 2008, pp. 464–467, 2008.
- [39] G. T. K, "A Survey on Line Detection Techniques using Different Types of Digital Images," *Int. J. Adv. Res. Comput. Eng. Technol.*, vol. 8, no. 5, pp. 2278–1323, 2019.
- [40] P. S. Rahmdel, R. Comley, D. Shi, and S. McElduff, "A review of hough transform and line segment detection approaches," *VISAPP 2015 - 10th Int. Conf. Comput. Vis. Theory Appl. VISIGRAPP, Proc.*, vol. 1, pp. 411–418, 2015, doi: 10.5220/0005268904110418.
- [41] D. H. Ballard, "Generalizing the Hough transform to detect arbitrary shapes," *Pattern Recognit.*, vol. 13, no. 2, pp. 111–122, 1981, doi: https://doi.org/10.1016/0031-3203(81)90009-1.
- [42] C. Y. Low, H. Zamzuri, and S. A. Mazlan, "Simple robust road lane detection

algorithm," in 2014 5th International Conference on Intelligent and Advanced Systems (ICIAS), 2014, pp. 1–4, doi: 10.1109/ICIAS.2014.6869550.

- [43] M. Aly, "Real time detection of lane markers in urban streets," in 2008 IEEE Intelligent Vehicles Symposium, 2008, pp. 7–12, doi: 10.1109/IVS.2008.4621152.
- [44] Y. Li, A. Iqbal, and N. R. Gans, "Multiple lane boundary detection using a combination of low-level image features," in *17th International IEEE Conference on Intelligent Transportation Systems (ITSC)*, 2014, pp. 1682–1687, doi: 10.1109/ITSC.2014.6957935.
- [45] Y. Leng and C. Chen, "Vision-based lane departure detection system in urban traffic scenes," in 2010 11th International Conference on Control Automation Robotics & Vision, 2010, pp. 1875–1880, doi: 10.1109/ICARCV.2010.5707817.
- [46] H. Tan, Y. Zhou, Y. Zhu, D. Yao, and K. Li, "A novel curve lane detection based on Improved River Flow and RANSA," in *17th International IEEE Conference on Intelligent Transportation Systems (ITSC)*, 2014, pp. 133–138, doi: 10.1109/ITSC.2014.6957679.
- [47] Y. Lin *et al.*, "Line segment extraction for large scale unorganized point clouds," *ISPRS J. Photogramm. Remote Sens.*, vol. 102, pp. 172–183, 2015, doi: https://doi.org/10.1016/j.isprsjprs.2014.12.027.
- [48] X. Lu, Y. Liu, and K. Li, "Fast 3D line segment detection from unorganized point cloud," *arXiv*, 2019.
- [49] I. Stamos and P. E. Allen, "3-D model construction using range and image data," in *Proceedings IEEE Conference on Computer Vision and Pattern Recognition. CVPR 2000 (Cat. No.PR00662)*, 2000, vol. 1, pp. 531–536 vol.1, doi: 10.1109/CVPR.2000.855865.
- [50] T. T. Nguyen, X. D. Pham, and J. W. Jeon, "Rectangular object tracking based on standard hough transform," 2008 IEEE Int. Conf. Robot. Biomimetics, *ROBIO 2008*, no. March 2009, pp. 2098–2103, 2009, doi: 10.1109/ROBIO.2009.4913326.
- [51] A. M. Sallam and M. Abdallah, "Proposed Multi-object Tracking Algorithm Using Sobel Edge Detection operator," vol. 3, no. 5, pp. 14–23, 2017.
- [52] Y. Ramadevi, T. Sridevi, B. Poornima, and B. Kalyani, "Segmentation And Object Recognition Using Edge Detection Techniques," *Int. J. Comput. Sci.*

Inf. Technol., vol. 2, pp. 153–161, 2010.

- [53] M. Wertheimer, "Gestalt theory.," in *A source book of Gestalt psychology*.,London, England: Kegan Paul, Trench, Trubner & Company, 1938, pp. 1–11.
- [54] K. Mullet and D. Sano, *Designing Visual Interfaces: Communication Oriented Techniques*. USA: Prentice-Hall, Inc., 1995.
- [55] B. Rajaei, R. G. von Gioi, and J. Morel, "From line segments to more organized gestalts," in 2016 IEEE Southwest Symposium on Image Analysis and Interpretation (SSIAI), 2016, pp. 137–140, doi: 10.1109/SSIAI.2016.7459194.
- [56] A. Desolneux, L. Moisan, and J.-M. Morel, From Gestalt Theory to Image Analysis: A Probabilistic Approach, 1st ed. Springer Publishing Company, Incorporated, 2007.
- [57] A. Desolneux, L. Moisan, and J.-M. Morel, "Meaningful Alignments," *Int. J. Comput. Vis.*, vol. 40, no. 1, pp. 7–23, 2000, doi: 10.1023/A:1026593302236.
- [58] J. Lezama, J. M. Morel, G. Randall, and R. Grompone Von Gioi, "A contrario 2D point alignment detection," *IEEE Trans. Pattern Anal. Mach. Intell.*, vol. 37, no. 3, pp. 499–512, 2015, doi: 10.1109/TPAMI.2014.2345389.
- [59] B. Rajaei and R. G. Von Gioi, "Gestaltic grouping of line segments," *Image Process. Line*, vol. 8, pp. 37–50, 2018, doi: 10.5201/ipol.2018.194.
- [60] H. Zhang, W. Yang, H. Yu, H. Zhang, and G. S. Xia, "Detecting power lines in UAV images with convolutional features and structured constraints," *Remote Sens.*, vol. 11, no. 11, pp. 1–17, 2019, doi: 10.3390/rs11111342.
- [61] Q. Xuejie and Y.-H. Yang, "Basic gray level aura matrices: theory and its application to texture synthesis," *Comput. Vision, 2005. ICCV 2005. Tenth IEEE Int. Conf. on, 1*, vol. 121, pp. 128–135, 2005.
- [62] J. Canny, "A Computational Approach to Edge Detection," *IEEE Trans. Pattern Anal. Mach. Intell.*, vol. PAMI-8, no. 6, pp. 679–698, 1986, doi: 10.1109/TPAMI.1986.4767851.
- [63] HOUGH and P. V. C., "Method and means for recognizing complex patterns," U.S. Patent, no.3069654, 1962.
- [64] J. Prewitt, "Object enhancement and extraction," *Picture processing and Psychopictorics*, vol. 10, no. 1. pp. 15–19, 1970.
- [65] I. Sobel, "An Isotropic 3x3 Image Gradient Operator," *Present. Stanford A.I. Proj. 1968*, Feb. 2014.

- [66] L. Roberts, Machine Perception of Three-Dimensional Solids. 1963.
- [67] A. Buades and R. G. von Gioi, "Visual system inspired algorithm for contours, corner and T-junction detection," in 2016 6th European Workshop on Visual Information Processing (EUVIP), 2016, pp. 1–6, doi: 10.1109/EUVIP.2016.7764586.
- [68] S. Blusseau, "On salience and non-accidentalness : comparing human vision to a contrario algorithms," École Normale Supérieure de Cachan, 2016.
- [69] N. M. Seel, Ed., "Gestalt Theory," in *Encyclopedia of the Sciences of Learning*, Boston, MA: Springer US, 2012, p. 1371.
- [70] A. Delsolneux, L. Moisan, and J.-M. Morel, *From Gestalt Theory to Image Analysis: A Probabilistic Approach*, vol. 34. 2008.
- [71] I. W. BAILEY, "The Evolutionary History of the Foliar Ray in the Wood of the Dicotyledons: and its Phylogenetic Significance1: With Plates LXIII and LXIII," *Ann. Bot.*, vol. os-26, no. 3, pp. 647–662, Jul. 1912, doi: 10.1093/oxfordjournals.aob.a089409.
- [72] D. A. Kribs, "Salient Lines of Structural Specialization in the Wood Rays of Dicotyledons," *Bot. Gaz.*, vol. 96, no. 3, pp. 547–557, Mar. 1935, doi: 10.1086/334500.
- [73] U. Khairuddin, R. Yusof, and N. R. Rosli, "A Comparative Study of k-NN and MLP-NN Classifiers Using GA-kNN Based Feature Selection Method for Wood Recognition System," vol. 17, no. 4, pp. 2695–2699, 2015.
- [74] N. Ali, D. Neagu, and P. Trundle, "Evaluation of k-nearest neighbour classifier performance for heterogeneous data sets," *SN Appl. Sci.*, vol. 1, no. 12, pp. 1–15, 2019, doi: 10.1007/s42452-019-1356-9.
- S. M. Vieira, S. Member, and U. Kaymak, "Cohen's Kappa Coefficient as a Performance Measure for Feature Selection," no. July, 2010, doi: 10.1109/FUZZY.2010.5584447.
- [76] "Cohen's kappa Wikipedia." [Online]. Available: https://en.wikipedia.org/wiki/Cohen%27s\_kappa. [Accessed: 25-Aug-2021].
- [77] "Mean absolute error Wikipedia." [Online]. Available: https://en.wikipedia.org/wiki/Mean\_absolute\_error. [Accessed: 25-Aug-2021].
- [78] "Root-mean-square deviation Wikipedia." [Online]. Available: https://en.wikipedia.org/wiki/Root-mean-square\_deviation. [Accessed: 25-Aug-2021].