

TOMATO RIPENESS DETECTION USING DEEP LEARNING

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DEDICATION

This thesis is dedicated to my father, who taught me that the best kind of knowledge to have is that which is learned for its own sake. It is also dedicated to my mother, who taught me that even the largest task can be accomplished if it is done one step at a time.

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ABSTRACT

Tomatoes are fruits with high nutrition and high in fibre; packed with vitamin C, vitamin K1, vitamin B9 and minerals. The global tomato processing market has reached 43.4 million tons in 2021. It is important to determine maturity level of the crops before harvesting to optimize yield. However, manual inspection of ripe tomatoes required huge labour resources and is time consuming. The amount of labour force for fruit harvesting has increased over the years due to increasing demand. Recently, some studies have attempted to evaluate the feasibility of smart agriculture involving machine learning for harvest ripeness detection. However, these works typically used smaller data size, simple dataset with no background or leaves or explored limited machine learning model. Hence, this thesis aimed to identify tomato ripeness detection using two machine learning networks such as Mask RCNN and YOLOv5. Both models were compared based on minimum average precision. The results of these algorithms were benchmarked with previous works in terms of precision and recall. The dataset for this work consisted of 1000 high resolution images (3024 x 4032) with a total of 9063 tomatoes consisting of unripe, half ripe and ripe tomatoes with leafy background to emulate actual environment in a tomato field. The images were annotated with bounding box in VGG image annotator prior to training and testing with the Mask R-CNN, YOLOv5 networks. After that, these images were divided to training, validation and testing set with 80:10:10 ratio and trained using TensorFlow. Parameters such as epochs, step per epochs, learning rate, batch size were tuned to improve training accuracy and reduce training loss. Minimum average precision achieved for Mask R-CNN was 0.903 and YOLOv5 was 0.927. Precision and recall for Mask RCNN was 89.94% and 87.14% respectively. YOLOv5 achieved better precision and recall of 92.72% and 90.87% respectively, which were better compared to Mask RCNN.

ABSTRAK

Tomato merupakan sejenis buah-buahan yang berkhasiat tinggi. Tomato mengandungi nutrisi yang tinggi dalam serat, vitamin C, vitamin K1, vitamin B9 dan mineral. Pada tahun 2021, pasaran pemprosesan global tomato telah mencecah 43.4 juta ton. Oleh itu, penentuan tahap kematangan tomato sebelum menuai adalah sangat penting bagi mengoptimumkan hasil. Kini, ramai yang menggunakan mata kasar dan membuat pemeriksaan secara manual dalam proses penuaian. Keadaan ini memerlukan sumber tenaga manusia yang besar dan amat makan masa. Sejak kebelakangan tahun ini, jumlah tenaga buruh telah bertambah kerana pasaran tomato semakin meningkat. Beberapa kajian yang melibatkan pertanian pintar dalam sektor penuaian tomato telah cuba dilaksanakan dengan menggunakan pembelajaran mesin baru-baru ini. Walau bagaimanapun, kajian-kajian tersebut biasanya menggunakan saiz data yang kecil, ringkas tanpa latar belakang atau daun. Kajian-kajian tersebut juga meneroka rangkaian pembelajaran mesin yang terhad. Justeru, tesis ini bertujuan untuk mengenal pasti pengesanan kematangan tomato menggunakan beberapa seni bina rangkaian pembelajaran mesin seperti Mask RCNN dan YOLOv5. Prestasi rangkaian ini dibandingkan dengan kajian-kajian terdahulu dari segi kejituan purata minimum, kejituan dan perolehan kembali. Set data untuk tesis ini terdiri daripada 1000 imej resolusi tinggi (3024 x 4032) yang melibatkan 9063 biji tomato belum masak, separuh masak dan masak. Imej-imej ini mempunyai latar belakang berdaun. Imej-imej diberi anotasi secara manual dalam menggunakan VGG image annotator. Set data tersebut dibahagikan kepada Latihan, ujian dan pengesahan dalam nisbah 80:10:10. Kejituan purata minimum untuk Mask RCNN mencapai 0.903 dan YOLOv5 mencapai 0.927. YOLOv5 mempunyai kejituan dan perolehan kembali yang lebih tinggi iaitu 92.72% dan 90.87% berbanding dengan Mask RCNN iaitu 89.94% dan 87.14%.

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LIST OF ABBREVIATIONS

CIELAB	-	Commission Internationale Lab Colour Space
CNN	-	Convolutional Neural Network
FC	-	Fully Connected
FP	-	False Positive
FPN	-	Feature Pyramid Network
FN	-	False Negative
GLCM	-	Gray Level Cooccurrence Matrix
IoU	-	Intersection of Union
JSON	-	JavaScript Object Notations
MRE	-	Mean Relative Error
PAnet	-	Path Aggregation Network
RCNN	-	Region-based Convolutional Neural Network
RGB	-	Red Green Blue
ROI	-	Region Of Interest
RPN	-	Region Proposal Network
SPP	-	Spatial Pyramid Pooling Layer
SSD	-	Single Shot Multibox Detector
SVM	-	Support Vector Machine
TP	-	True Positive
TN	-	True Negative
VGG	-	Visual Geometry Group
YOLO	-	You Only Look Once
mAP	-	Minimum Average Precision

CHAPTER 1

INTRODUCTION

1.1 Research Background

Tomato processing is one of the most internationally diversified agricultural sectors. This is because tomatoes are nutritious and beneficial to human health. Tomatoes are consumed worldwide due to this factor. Tomato production quantities are much higher compared to other crops grown worldwide. It is six times higher than rice and three times more than potatoes [1].

Tomato are common fruits that have high nutrition in fibre, vitamin C, vitamin K1, vitamin B9 and minerals. Usually, tomatoes can come in different maturity and colours such as red, yellow and green. Red represents ripe, yellow represents half ripe and green represents unripe [2]. The global tomato processing market has reached 43.4 million tons in 2021. It is important to determine maturity level of the crops before harvesting to optimize yield. However, manual inspection of ripe tomatoes required huge labour resources and is time consuming. The amount of labour force for tomato harvesting has increased over the years due to increasing demand. The global tomato processing market expects to reach 54.5 million tons in 2027 [3]. As a result, tomato farming is crucial in rural and suburban areas of emerging nations since it can boost the local economy.

When immature or unripe fruits are harvested, the quality of these fruits are poor. Usually, they are incapable of ripening. Immature fruits are susceptible to internal deterioration and decay. Similarly, if fruits are harvested late, the chances of getting rotten fruits are very high. Thus, improper harvest timing will result in drastic postharvest loss. In order to reduce the losses of preharvest and postharvest fruits qualitatively and quantitatively, it is important to understand the maturity condition of fruit. The loss of quality of tomatoes is one of the major challenges faced in tomato

agriculture sector [4]. Typically, farmers use their personal experience to detect type of disease and maturity level of tomatoes. Manual inspection is used to determine the tomato crop's level of maturity. This in turn leads to a dependency on manual labour, which is inconsistent. To overcome these problems, smart harvesting is being promoted in recent years.

1.2 Problem Statement

Recently, some studies have attempted to evaluate the feasibility of smart agriculture involving machine learning for harvest ripeness detection. However, these works typically used smaller data size, simple dataset with no background or leaves or explored limited machine learning networks. From the literature review, most works focused on single method to detect tomato ripeness such as SVM, CNN, decision tree, GLCM, Mask RCNN, Faster RCNN and YOLOv3. Also, some of the studies detect tomatoes without background. It is less effective during harvesting process because the tomatoes are actually hanging on tomato trees in actual environment, and typically surrounded by leaves.

1.3 Objectives

The aims of this project are:

- (a) To configure two machine learning networks to detect tomato ripeness.
- (b) To evaluate the performance of the two types of machine learning architecture in tomato ripeness detection.
- (c) To validate the algorithm with bigger dataset - 1000 images depicting a total of 9063 unripe, half ripe and ripe tomatoes with leafy background within the images.

1.4 Scope of Work

The project's scopes are as follows:

- (a) To use publicly accessible database and to work only on tomatoes.
- (b) Dataset would be labelled manually using VGG annotator tool.
- (c) Two different object detection networks, which are Mask RCNN and YOLOv5, would be implemented and compared.
- (d) The performance of these two different architectures would be evaluated based on performance accuracy and mAP of tomato ripeness classification.
- (e) Mask RCNN and YOLOv5 would be trained using TensorFlow.
- (f) Intel Tiger Lake core i7-11800H and 6GB RTX 3060 GPU would be used as computational platform to train the network.

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