

MODELLING OF A DC FAST CHARGING STATION FOR ELECTRIC VEHICLES

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DEDICATION

This thesis is dedicated to my father, who is the reason I was able to persue my Master's degree and who supported me through my journey thus far. It is also dedicated to my mother, who taught me that even the largest task can be accomplished if it is done one step at a time.

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ABSTRACT

The trend of the energy sectors around the globe is to lean more towards alternative and renewable sources of energy due to the increase in carbon emissions and inevitable shortage of fossil fuel-based sources. Among those technologies are Electric Vehicles (EVs), which are a green emission free replacement for the traditional Internal Combustion Engine (ICE) vehicle. The charging infrastructure is a major concern among potential EV customers, with emphasis on fast charging ability, especially for highways and long-distance commutations. In this project, modelling of a DC Fast Charging (DCFC) EV Station is designed and modelled using Matlab/Simulink software. The developed DCFC model comprises 2 main conversion stages which are the AC/DC stage as well as the DC/DC stage for regulating and charging the EVs. The control method used for the AC/DC convertor is the synchronous frame reference voltage & reactive current control, while the charging control is a Constant Current/Constant Voltage (CCCV) control. An LCL filter was designed for the harmonic mitigation as it shows superior performance to traditional L and LC filters. The DCFC station was simulated for the case of 2 EVs charging and 4 EVs charging. The results obtained show the state of charge (SoC) of the EV battery has been successfully charged from 35% to 85% SoC in 16.6 minutes, in which considered as an acceptable fast charging time according to the market standards. Also, the AC grid current in both cases of simulation had a THD of lower than 8%. Finally, the DC bus voltage was successfully maintained at a constant voltage level, 600V. The presented simulation results proved that the developed model with its applied control strategies demonstrated the principle work of a DCFC EV system.

ABSTRAK

Trend sektor tenaga di seluruh dunia adalah lebih cenderung ke arah sumber tenaga alternatif dan boleh diperbaharui kerana peningkatan pelepasan karbon dan kekurangan sumber bahan bakar fosil yang tidak dapat dielakkan. Di antara teknologi tersebut adalah Kenderaan Elektrik (EV), yang merupakan pengganti bebas pelepasan hijau untuk kenderaan Mesin Pembakaran Dalam (ICE) tradisional. Infrastruktur pengecasan yang menjadi perhatian utama di kalangan calon pengguna EV adalah penekanan terhadap kemampuan pengecasan pantas, terutama untuk lebuhraya dan perjalanan jarak jauh. Dalam projek ini, pemodelan Stesen EV Pengecasan Pantas DC (DCFC) dirancang dan dimodelkan menggunakan perisian Matlab/Simulink. Model DCFC yang dimodelkan merangkumi 2 peringkat penukaran utama iaitu penukar AC/DC dan penukar DC/DC untuk mengawal dan mengecas EV. Kaedah kawalan yang digunakan untuk penukar AC/DC adalah voltan rujukan kerangka segerak & kawalan arus reaktif, sementara pengawal pengecasan adalah kawalan Arus Tetap/Voltan Tetap (CCCV). Penapis LCL direka untuk mengurangkan kesan harmonik kerana ia menunjukkan prestasi lebih baik berbanding penapis tradisional L dan LC. Stesen DCFC disimulasikan untuk kes pengisian 2 EV dan pengecasan 4 EV. Hasil yang diperoleh menunjukkan keadaan pengecasan (SoC) bateri EV telah berjaya dicas dari SoC 35% hingga 85% dalam masa 16.6 minit, di mana ia boleh dianggap sebagai masa pengecasan pantas yang dapat diterima sesuai dengan standard pasaran. Juga, arus grid AC dalam kedua-dua kes simulasi mempunyai THD yang lebih rendah daripada 8%. Akhirnya, voltan bas DC berjaya dikekalkan pada tahap voltan malar, 600V. Hasil simulasi yang dibentangkan membuktikan bahawa model yang dibina dengan strategi pengawal yang digunakan telah menunjukkan prinsip kerja sistem DCFC EV yang sebenar.

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CHAPTER 1

INTRODUCTION

1.1 Background Study

The trend of the energy sectors around the globe is to lean more towards alternative and renewable sources of energy due to the increase in carbon emissions and inevitable shortage of fossil fuel-based sources. Among those technologies are electric vehicles (EVs), which are a green emission free replacement for the traditional internal combustion engine (ICE) vehicle. EVs are either battery electric vehicles (BEV), plug in electric vehicles (PHEV) and hybrid electric vehicles (HEV). HEV and PHEV are both hybrid electric vehicles, which reduce the carbon emissions of traditional ICE vehicles by decreasing the ICE vehicle fuel consumption and hence decreasing its emissions. The main difference between PHEV's and HEV's is the ability to externally charge the EV battery which is available in PHEV's. HEV's however, cannot be charged externally, Instead, the battery is charged through regenerative braking and by the internal combustion engine. Both PHEV and HEV are not emission free vehicles but an improvement to the ICE vehicle. BEV's however or pure electric vehicles as they are also known are solely dependant on the EV battery with no combustion engine, hence achieving zero emissions [1].

With the increase in EV demands, there are still several obstacles against EV adoption, for instance high in cost, mileage coverage, and also charging station infrastructures. Charging stations can be a home charger for single EV use or a public station.

1.2 Problem Statement

The electric vehicles (EVs) revolution has become a popular empowering subject in recent years as many believe it will transform the imminent of transportation market. However, there are still several barriers to the widespread adoption of EVs. For instance, as claimed in [2], 56% of EVs' customers placed high importance on fast charging ability, while 62% has stated that the availability of charging infrastructure was their primary concern regarding EVs. According to the three main Fast Charging Standards: Combined Charging System (CCS), CHAdeMO, and Tesla Supercharger, the charging time for fast DC chargers is anywhere from 15 to 45 minutes depending on the charger output and vehicle voltage capacity [3]. To solve these issues, DC fast charging (DCFC) has been introduced by EV manufacturers. More EV stations also have been developed from time to time. Thus, more capacity of EVs can be fueled faster. However, DCFC has poses a burden on the grid when bulky and unpredict charging occurs in simultaneous time. The high loading of the DCFC station on the grid may cause negative impacts on the grid as it will be described in detail in **Chapter-2**. Mitigating these effects requires the suitable control and filter implementation to maintain system stability between the DCFC station and the utility grid.

1.3 Research Objectives

The objectives of this research are:

1. Designing and modelling the EV Charging station with 4 EV slots.
2. Modelling a fast battery charging which SoC of 80% can be achieved around 20 minutes.
3. Controlling the DC bus voltage with low THD level of the grid AC current using DQ-Frame Reference Control with implementing an LCL Filter.

1.4 Scope of the Project

- A. Only DC Bus Architecture for the DCFC is considered.
- B. IEEE 519-2014 standard for DC Fast charging is the standard considered. 5% voltage harmonic distortion limit and an 8% THD limit should be maintained
- C. Converter control will be implementing DQ-reference frame voltage and current control.
- D. Charging Control is using a constant current constant voltage (CCCV) control.
- E. Simulation will be done in MATLAB/Simulink.

1.5 Report Outline

The work begins with a brief introduction on Fast Charging necessity the challenges facing such implementation. Then, **Chapter-2** will discuss a few elements from the literature regarding charging levels and standards, implications on the grid due to the DCFC station as well as the architectures. **Chapter-3** describes the various components as well as control methods used in designing the station. Each power conversion stage is described with its dedicated converter control. The simulation results will be analysed and discussed in **Chapter-4**. The report ends with some conclusions and recommendation for future works in **Chapter-5**

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