

LEAST SQUARES VARIANCE COMPONENT ESTIMATION FOR
SURVEYING NETWORK ADJUSTMENT

NUR KHALILAH BINTI BIDI

A thesis submitted in fulfilment of the
requirements for the award of the degree of
Master of Philosophy

Faculty of Built Environment and Surveying
Universiti Teknologi Malaysia

MAY 2019

DEDICATION

Special dedication to...

To my beloved father and mother...

Bidi b Mat Nor

Normah bt Sulong

My dear families...

To all my siblings

My supportive lab mates...

My supportive friend...

Muhammad Khairil Adzhar b Radzali

For finding me the light

Only Allah S.W.T will return your kindness... I am really appreciated it

ACKNOWLEDGEMENT

Praise to Lord of Universe, Allah S.W.T for the guidance and His overflow, I can complete and finish my Master study. May peace and blessings to Prophet Muhammad S.A.W, His last messenger.

Firstly, I would like to express my deep and sincere gratitude to my supervisor, Dr. Ami Hassan because of his insightful guidance helped me in all the time of research and writing this thesis. Without his help and encouragement, the thesis would not have reached its completion. His constructive comments and advice have always played a significant role in improving the content of my thesis and publications.

Special thanks go to Mr Zainal Abidin as my co-supervisor for his efficient supervision and kindness to guide and helpful advice during my study. His understanding, encouragement and personal guidance make me struggle to finish this research. He is also very much acknowledged for the scientific discussions we have had afterward.

A much appreciate to Department of Surveying and Mapping Johor Bahru (DSMM) for providing me cadastral data in order to realise this research. Thanks also to Dr. Dudy Wijaya for helping me to understand LS-VCE concept, algorithm and software.

Besides my supervisors, special thanks to all my friends in GIG, UTM especially Anim Zanariah, Suraya, Astina, Fadilah, Najihah, Adilla and Jehan for helping me and useful discussion over the last four semesters. Above all, my heartfelt gratitude goes to my beloved parents and siblings for their unconditional love, spiritual support, and continuous encouragement all the way through these years since 2016.

ABSTRACT

The stochastic model of least squares adjustment plays an essential role in geodetic network data processing because the model describes the accuracy of the measurements and their correlation with each other. Knowledge of weights of the observables is necessary to provide a better understanding of the sources of errors and to model the error, hence the weights need to be determined correctly. For geodetic applications, it is crucial to have knowledge about covariance matrix of the observables since variance components are most commonly used to determine a realistic precision. This study focuses on the estimation of variance components from different types of data for geodetic applications, which include deformation survey and cadastral survey. Least Squares Variance Component Estimation (LS-VCE) method was used in this study because the method is simple, flexible and attractive due to the precision of variance estimators that can be directly obtained. For deformation monitoring network, simulations of geodetic and Kenyir dam networks data were performed. Meanwhile, for cadastral observation data from several types of instruments such as chain measurement, Electronic Distance Measurement and total station were utilized. The results revealed that the estimated variance components for distance scale error σ_p seem to become unrealistic for each data tested as the baseline of the networks was not long enough. In addition, it was found that the traverse network which included chain survey, showed insignificant result to the precision of station coordinates when the measurements were combined. The distance-dependent model was selected as the best model for Kenyir dam network since W-test values of Epoch 1 and 2 were 0.30 and 0.50, where the expectation and the variance of W-test values were 0 and 1, respectively. The findings showed that LS-VCE method was very reliable in various geodetic applications. In conclusion, the program developed is valuable for professional groups which include surveyors and engineers, as well as geophysics and geologists.

ABSTRAK

Model stokastik bagi pelarasan kuasa dua terkecil memainkan peranan penting dalam pemprosesan data jaringan geodesi, kerana ia menerangkan ketepatan pengukuran dan kolerasi antara satu sama lain. Pengetahuan tentang pemberat dalam cerapan adalah perlu untuk memberikan pemahaman yang lebih baik tentang sumber-sumber selisih dan pemodelan selisih tersebut, oleh itu ia perlu ditentukan dengan betul. Bagi aplikasi geodesi, adalah penting untuk mempunyai pengetahuan mengenai matriks kovarians yang paling biasa digunakan untuk menentukan ketepatan yang realistik. Kajian ini memberi tumpuan kepada penganggaran komponen varians dari pelbagai jenis data untuk aplikasi geodesi termasuk ukur deformasi dan ukur kadaster. Kaedah Penganggaran Komponen Kuasa Dua Varians (PKKV) digunakan dalam kajian ini kerana kaedah ini lebih mudah, fleksibel dan menarik disebabkan ketepatan varians anggaran boleh diperolehi secara langsung. Bagi jaringan deformasi, data jaringan simulasi dan jaringan empangan Kenyir telah dijalankan. Sementara itu, data cerapan kadaster dari beberapa jenis peralatan seperti pengukuran rantai, pengukuran jarak elektronik dan total station telah digunakan. Keputusan menunjukkan bahawa komponen-komponen varians yang dianggarkan untuk selisih skala jarak σ_p tidak realistik bagi setiap data yang diuji kerana garis dasar jaringan tidak cukup panjang. Di samping itu, didapati bahawa jaringan terabas yang melibatkan ukur rantai menunjukkan hasil yang tidak signifikan kepada kejituan koordinat stesen apabila pengukuran digabungkan. Model jarak bersandar dipilih sebagai model terbaik bagi jaringan empangan Kenyir kerana nilai ujian W bagi epok 1 dan 2 adalah 0.30 dan 0.50, di mana jangkaan dan varians nilai ujian W masing-masing adalah 0 dan 1. Keputusan menunjukkan bahawa kaedah PKKV sangat dipercayai dalam pelbagai aplikasi geodesi. Kesimpulannya, program yang dibangunkan adalah sangat berguna kepada kumpulan profesional termasuk juru ukur dan jurutera, serta ahli geofizik dan geologi.

TABLE OF CONTENTS

	TITLE	PAGE
	DECLARATION	ii
	DEDICATION	iii
	ACKNOWLEDGEMENT	iv
	ABSTRACT	v
	ABSTRAK	vi
	TABLE OF CONTENTS	vii
	LIST OF TABLES	xi
	LIST OF FIGURES	xvi
	LIST OF ABBREVIATIONS	xviii
	LIST OF SYMBOLS	xix
	LIST OF APPENDICES	xxi
CHAPTER 1	INTRODUCTION	1
	1.1 Background of the Research	1
	1.2 Problem Statement	4
	1.3 Research Question	7
	1.4 Aim and Objectives of the Research	7
	1.5 Scope of the Research	8
	1.6 Significance of the Research	10
	1.7 General Research Methodology	11
	1.8 The Structure of The Thesis	14
CHAPTER 2	LITERATURE REVIEW	17
	2.1 Introduction	17
	2.2 Introduction of Variance Components Estimation	17
	2.3 Variance Component Model	21
	2.3.1 Models of additive effects	21
	2.3.2 Models of group effects	22

2.3.3	Models of mixed effects	23
2.4	Methods Available for Variance Components Estimation	23
2.4.1	Minimum Norm Quadratic Unbiased Estimator (MINQUE) Method	25
2.4.2	Maximum Likelihood Estimation (MLE) Method	26
2.4.3	Helmert Method	27
2.5	Principle of Least Squares Variance Component Estimation	28
2.6	Geodetic Application: Deformation Monitoring and Cadastral Network	33
2.6.1	Deformation Monitoring Network	33
2.6.2	Cadastral Network	35
	2.6.2.1 Chain Survey Principle	36
	2.6.2.2 Electronic Distance Measurement (EDM) and Total Station Instruments	37
2.7	Previous Research on the use of VCE Method for Geodetic Applications	38
2.8	Chapter Summary	39
CHAPTER 3	RESEARCH METHODOLOGY	42
3.1	Introduction	42
3.2	Data Acquisition	44
3.2.1	Deformation Monitoring Network Survey	44
3.2.2	Cadastral Network Survey	49
3.3	LSA and VCE Program Development	56
3.3.1	LSA Computation Procedure	56
3.3.2	VCE Computation Procedure	60
3.4	Evaluation of Variance Component Estimation: W-test Statistic	63
3.5	Development of Computational Package using MATLAB Programming	65
3.5.1	Deformation Network Analysis Computation (DNAC)	66
3.5.2	Cadastral Network Computation (CNC)	67

3.6	Chapter Summary	68
CHAPTER 4	RESULT AND DISCUSSION OF DEFORMATION MONITORING NETWORK	70
4.1	Introduction	70
4.2	Deformation Monitoring Network Results	70
4.2.1	Simulation Network of Dataset 1	71
4.2.2	Kenyir Dam Monitoring Network	76
4.3	Deformation Monitoring Network Analysis	82
4.3.1	Simulation Network of Dataset 1	82
4.3.2	Kenyir Dam Monitoring Network	84
4.4	Validation of Deformation Network Analysis Computational (DNAC) Package	88
4.5	Chapter Summary	90
CHAPTER 5	RESULT AND DISCUSSION OF CADASTRAL NETWORK	93
5.1	Introduction	93
5.2	Cadastral Network Results	93
5.2.1	Dataset 1 – Chain, Theodolite and Total Station	94
5.2.2	Dataset 2 – EDM, Theodolite and Total Station	98
5.2.3	Dataset 3 – Chain, EDM, Theodolite and Total Station	103
5.3	Cadastral Network Analysis	108
5.3.1	Dataset 1 – Chain, Theodolite and Total Station	108
5.3.2	Dataset 2 – EDM, Theodolite and Total Station	110
5.3.3	Dataset 3 – Chain, EDM, Theodolite and Total Station	113
5.4	Validation of Cadastral Network Computation (CNC) Package	116
5.5	Chapter Summary	119

CHAPTER 6	CONCLUSION AND RECOMMENDATIONS	120
6.1	Conclusion	120
6.2	Recommendations	122
REFERENCES		124
Appendix A		132
Appendix B		136
Appendix C		147
Appendix D		157
Appendix E		165
LIST OF PUBLICATIONS		168
RESEARCH ACTIVITIES		169

LIST OF TABLES

TABLE NO.	TITLE	PAGE
Table 2.1	Summary of the previous research regarding the estimation of variance components and this study	40
Table 3.1	Approximate coordinates of Dataset 1 with fixed station	44
Table 3.2	Data observation of deformation network for Dataset 1	45
Table 3.3	Approximate coordinates of Dataset 2 with fixed station	46
Table 3.4	Data observation of deformation network for Dataset 2	46
Table 3.5	Approximate coordinates of Kenyir dam network	47
Table 3.6	Data observation of Kenyir dam network	47
Table 3.7	Combination of the instruments used for datasets in cadastral network	50
Table 3.8	Approximate coordinates of cadastral network for Dataset 1	50
Table 3.9	Data observation of network include chain and total station instrument	51
Table 3.10	Approximate coordinates of cadastral network for Dataset 2	51
Table 3.11	Data observation of network include EDM and total station instrument	52
Table 3.12	Approximate coordinates of cadastral network for Dataset 3	52
Table 3.13	Data observation of network include chain, EDM and total station instrument	53
Table 4.1	Initial variance components and standard deviation of Model 1 for Dataset 1	72
Table 4.2	Estimated variance components and standard deviation of Model 1 for Dataset 1	72
Table 4.3	Standard deviation of station of Model 1 for Dataset 1 (Epoch 1)	73
Table 4.4	Standard deviation of station Model 1 for Dataset 1 (Epoch 2)	73

Table 4.5	Initial variance components and standard deviation of Model 2 for Dataset 1	74
Table 4.6	Estimated variance components and standard deviation of Model 2 for Dataset 1	74
Table 4.7	Standard deviation of station of Model 2 for Dataset 1 (Epoch 1)	75
Table 4.8	Standard deviation of station of Model 2 for Dataset 1 (Epoch 2)	75
Table 4.9	Initial variance components and standard deviation of Model 1 for Dataset 2	76
Table 4.10	Estimated variance components and standard deviation of Model 1 for Dataset 2	77
Table 4.11	Standard deviation of station of Model 1 for Dataset 2 (Epoch 1)	77
Table 4.12	Standard deviation of station of Model 1 for Dataset 2 (Epoch 2)	77
Table 4.13	Initial variance components and standard deviation of Model 2 for Dataset 2	78
Table 4.14	Estimated variance components and standard deviation of Model 2 for Dataset 2	78
Table 4.15	Standard deviation of station of Model 2 for Dataset 2 (Epoch 1)	79
Table 4.16	Standard deviation of station of Model 2 for Dataset 2 (Epoch 2)	79
Table 4.17	Initial variance components and standard deviation of Model 3 for Dataset 2	80
Table 4.18	Estimated variance components and standard deviation of Model 3 for Dataset 2	80
Table 4.19	Standard deviation of station of Model 3 for Dataset 2 (Epoch 1)	81
Table 4.20	Standard deviation of station of Model 3 for Dataset 2 (Epoch 2)	81
Table 4.21	Results of estimated variance component for Dataset 1 using LS-VCE method	82
Table 4.22	The W-test statistic values of each variance components model for simulation network of Dataset 1	84

Table 4.23	Estimated variance components for Kenyir dam network using LS-VCE method	85
Table 4.24	The W-test statistic values of each variance components model for Kenyir dam network	85
Table 4.25	Comparison results of adjusted coordinates between StarNet software and MATLAB package for Dataset 1 – Epoch 1	88
Table 4.26	Comparison results of adjusted coordinates between StarNet software and MATLAB package for Dataset 1 – Epoch 2	89
Table 4.27	Comparison results of adjusted coordinates between StarNet software and MATLAB package for Kenyir dam – Epoch 1	89
Table 4.28	Comparison results of adjusted coordinates between StarNet software and MATLAB package for Kenyir dam – Epoch 2	90
Table 5.1	Combination of the instruments used for datasets in cadastral network	94
Table 5.2	Initial variance components and standard deviation of Model 1 (Dataset 1)	95
Table 5.3	Estimated variance components and standard deviation of Model 1 (Dataset 1)	95
Table 5.4	Standard deviation of station coordinate after adjustment of Model 1 (Dataset 1)	96
Table 5.5	Initial variance components and standard deviation of Model 2 (Dataset 1)	97
Table 5.6	Estimated variance components and standard deviation of Model 2 (Dataset 1)	97
Table 5.7	Standard deviation of station coordinate after adjustment of Model 2 (Dataset 1)	97
Table 5.8	Initial variance components and standard deviation of Model 1 (Dataset 2)	98
Table 5.9	Estimated variance components and standard deviation of Model 1 (Dataset 2)	99
Table 5.10	Standard deviation of station coordinate after adjustment of Model 1 (Dataset 2)	99
Table 5.11	Initial variance components and standard deviation of Model 2 (Dataset 2)	100

Table 5.12	Estimated variance components and standard deviation of Model 2 (Dataset 2)	100
Table 5.13	Standard deviation of station coordinate after adjustment of Model 2 (Dataset 2)	101
Table 5.14	Initial variance components and standard deviation of Model 3 (Dataset 2)	101
Table 5.15	Estimated variance components and standard deviation of Model 3 (Dataset 2)	102
Table 5.16	Standard deviation of station coordinate after adjustment of Model 3 (Dataset 2)	102
Table 5.17	Initial variance components and standard deviation of Model 1 (Dataset 3)	103
Table 5.18	Estimated variance components and standard deviation of Model 1 (Dataset 3)	103
Table 5.19	Standard deviation of station coordinate after adjustment of Model 1 (Dataset 3)	104
Table 5.20	Initial variance components and standard deviation of Model 2 (Dataset 3)	105
Table 5.21	Estimated variance components and standard deviation of Model 2 (Dataset 3)	105
Table 5.22	Standard deviation of station coordinate after adjustment of Model 2 (Dataset 3)	106
Table 5.23	Initial variance components and standard deviation of Model 3 (Dataset 3)	107
Table 5.24	Estimated variance components and standard deviation of Model 3 (Dataset 3)	107
Table 5.25	Standard deviation of station coordinate after adjustment of Model 3 (Dataset 3)	107
Table 5.26	Results of VCE for traverse network Dataset 1 using LS-VCE	108
Table 5.27	Results of W-test for Dataset 1 using LS-VCE method	110
Table 5.28	Results of VCE for traverse network Dataset 2 using LS-VCE	111
Table 5.29	Results of W-test for Dataset 2 using LS-VCE method	111
Table 5.30	Results of VCE for traverse network Dataset 3 using LS-VCE	113
Table 5.31	Results of W-test for Dataset 3 using LS-VCE method	115

Table 5.32	Comparison of adjusted coordinates between StarNet software and CNC package for Dataset 1	116
Table 5.33	Comparison of adjusted coordinates between StarNet software and CNC package for Dataset 2	117
Table 5.34	Comparison of adjusted coordinates between StarNet software and CNC package for Dataset 3	118

LIST OF FIGURES

FIGURE NO.	TITLE	PAGE
Figure 1.1	Example of a set of measurement data have failed Chi-Square test in StarNet software.	5
Figure 1.2	The study area for cadastral network data	9
Figure 1.3	Overview of general research methodology	11
Figure 2.1	The quadrilateral of ABCD divided into triangles (Civil Seek, 2018)	36
Figure 3.1	The framework of the research methodology	43
Figure 3.2	Dataset 1: Simulation of deformation monitoring network	48
Figure 3.3	Dataset 2: Simulation of deformation monitoring network	48
Figure 3.4	Kenyir dam monitoring control network	49
Figure 3.5	Dataset 1: Lot combination from chain measurement and total station	54
Figure 3.6	Data 2: Lot combination from electronic distance measurement (EDM) and total station (TS)	54
Figure 3.7	Dataset 3: Lot combination from chain measurement, EDM and total station	55
Figure 3.8	The procedure of least squares adjustment computation	59
Figure 3.9	The computation procedure of variance covariance components using LS-VCE method.	62
Figure 3.10	Main window of the geodetic computational package	65
Figure 3.11	Interface of deformation network analysis computation generated from MATLAB (GUIDE)	66
Figure 3.12	Interface of cadastral network computation generated from MATLAB (GUIDE)	68
Figure 4.1	Estimated standard deviation of each control station for Dataset 1	83
Figure 4.2	Estimated standard deviation of control station for Kenyir dam network	87
Figure 5.1	Estimated standard deviation of each station for Dataset 1 (chain, theodolite and total station)	109

Figure 5.2	Estimated standard deviation of each station for Dataset 2 (EDM, theodolite and total station)	112
Figure 5.3	Estimated standard deviation of each station for Dataset 3 (chain, EDM, theodolite and total station)	114

LIST OF ABBREVIATIONS

1D	-	One-Dimensional
2D	-	Two-Dimensional
3D	-	Three-Dimensional
BIQUE	-	Best Invariant Quadratic Unbiased Estimator
BLUE	-	Best Linear Unbiased Estimation
CNC	-	Cadastral Network Computation
DNAC	-	Deformation Network Analysis Computation
EDM	-	Electronic Distance Measurement
GNSS	-	Global Navigation Satellite System
GPS	-	Global Positioning System
GUIDE	-	Graphical User Interface Development Environment
DSMM	-	Department of Survey and Mapping Johor Bahru
MATLAB	-	Matrix Laboratory
MLE	-	Maximum Likelihood Estimation
MINQUE	-	Minimum Norm Quadratic Unbiased Estimator
NDCDB		National Digital Cadastral Database
LSA	-	Least Squares Adjustment
LS-VCE	-	Least Squares Variance Component Estimation
REML	-	Restricted Maximum Likelihood Estimator
TLS	-	Terrestrial Laser Scanning
TS	-	Total Station
UAV	-	Unmanned Aerial Vehicle
UTM	-	Universiti Teknologi Malaysia
VCE	-	Variance Component Estimation

LIST OF SYMBOLS

b	-	Degrees of freedom in functional model
df	-	Degrees of freedom in stochastic model
d	-	Distance measurement
e	-	Residual vector in stochastic model
k	-	Number of distance measurement
l	-	Observation vector in functional model
\mathcal{L}	-	Likelihood function
m	-	Number of observations
n	-	Number of unknown parameters
p	-	Number of variance component
s	-	Number of directions
t	-	Redundant observation
v	-	Residual vector in functional model
w	-	W-test in stochastic model
x	-	Unknown parameter vector
y	-	Observation vector in stochastic model
A	-	Design matrix
B	-	Null space of A^T
P	-	Weight matrix in functional model
N	-	Normal matrix
W	-	Weight matrix in stochastic model
χ^2	-	Chi-Squares test
ε	-	Total errors
σ_k	-	Variance components
σ_d		Distance-dependent component
σ_p		Distance scale component
σ_b		Horizontal angle/bearing azimuth component
σ_o^2	-	A priori variance factor
$\hat{\sigma}_o^2$		A posteriori variance factor

σ_k	-	Initial variance component
$\hat{\sigma}_k$	-	Estimated variance component
σ_d^2	-	Variance of distance-dependent
σ_p^2	-	Variance of distance scale
σ_b^2	-	Variance of bearing/horizontal angle
θ_m	-	Variance covariance component
Σ_x	-	Covariance matrix in functional model
C_y	-	An $m \times m$ symmetric matrix
\hat{L}^a	-	Adjusted observation in functional model
Q_o	-	Known part of covariance matrix
K, Q_y	-	Covariance matrix in stochastic model
Q_k	-	Cofactor matrix in stochastic model
P_A^1	-	Orthogonal projector in stochastic model
T_m	-	Coefficient matrices

LIST OF APPENDICES

APPENDIX	TITLE	PAGE
Appendix A	Result of Simulation Deformation Network of Dataset 2	132
Appendix B	Result of Control Stations for Deformation Monitoring Network	136
Appendix C	Results of Control Stations for Cadastral Network	147
Appendix D	LSA Computation MATLAB Routine	157
Appendix E	VCE Computation MATLAB Routine	165

CHAPTER 1

INTRODUCTION

1.1 Background of the Research

Least squares adjustment (LSA) of a geodetic application is always an important topic in surveying. In general, principle of least squares is to minimize the sum of squares of the weighted residuals (Caspary, 2000). Back in the early 18th century, Gauss and Legendre introduced the concept of least squares estimation mostly for the purpose of reducing physical and astronomical data (Olyazadeh *et al.*, 2011). In geodetic data processing, principle of least squares method deals with these two types of models, which are ‘functional model’ and ‘stochastic model’. The functional model contains the geometrical relationship between measurements and parameters to be estimated, while the stochastic model gives information about the precision of measurements.

Data processing in geodetic network often count on the least squares method, thus an appropriate stochastic model of the observables is constantly required (Amiri-Simkooei, 2007). In addition, information of weight of the observables is important to estimate the correct least squares solution (Wentworth, 1965). According to Ghilani and Wolf (2006):

“The weight of an observation is a measure of its relative worth compared to other measurements. Weights are used to control the sizes of corrections applied to measurements in an adjustment. The more precise an observation, the higher its weight; in other words, the smaller the variance, the higher the weight.”

(Ghilani and Wolf, 2006, pp. 159)

Based on these sentences, it can be stated automatically that weights are inversely proportional to variances. Hence, it also follows that correction sizes

should be inversely proportional to the weights. Inappropriate weight (variance component) can affect the LSA results, which is significant in geodetic network. The input data of the geodetic network representing the measurement accuracy is also referred to as the variance components of the measurement data. Therefore, the estimation of the unknown variance components is called variance component estimation (VCE).

For many applications, information available on the covariance matrix of the observation is crucial. This is because every measurement data or observation data of geodetic network are necessary to know their level of accuracy in the form of a standard deviation or variance. Thus, the standard deviation of the measurement has supposedly become one of the important elements in LSA. A realistic covariance matrix allows us to determine a correct precision description of the unknown parameters. According to Amiri-Simkooei (2007), the information that we can obtain through covariance matrix allows us, first, to study the different contributing errors factors in observation, second, to acquire minimum variance estimators of the parameters in a linear model and third, to perform hypothesis testing correctly and to evaluate other quality control measures such as reliability.

However, the covariance matrix is only partially known in most of the modern geodetic applications, as a result, the unknown part needs to be estimated from the redundant observation. For example, our knowledge of stochastic model is still at an elementary level in the field of Global Navigation Satellite System (GNSS). This is different with a functional model (i.e. observation equations), which is common in many GNSS textbooks available (Amiri-Simkooei, 2007). In recent years, the geodetic community has become increasingly interested in the method of estimating variance components. The interest in VCE in geodetic applications is more relevant within the context of the least squares adjustment. Variance component estimation brings geodetic perspective, which refers to the technique of estimating the variance or the variance factors for individual groups of observation from an adjustment.

Nowadays, variance component estimation method has become one of the familiar topics in statistical geodetic literatures. There are various available methods for computing variance components. However, these methods employ different principles of estimation. Moghtased-Azar *et al.* (2014), Eshagh & Sjöberg (2008) and Teunissen & Amiri-Simkooei (2008) have listed many pioneer studies on VCE work published in several statistic related journals. One of the most popular methods, presented by Rao (1970), is the Minimum Norm Quadratic Unbiased Estimator (MINQUE) to avoid any distributional assumption. Then in 1983, the MINQUE method was extended to the general Gauss-Helmert model by Sjöberg, namely condition adjustment with unknowns (Moghtased-Azar *et al.*, 2014).

Maximum Likelihood Estimation (MLE) method was first presented for geodetic applications by Kubik (1970) to estimate ratios of weight in a network direction. Another approach is Helmert's method presented by Kelm (1978), followed by Least Squares Variance Component Estimation (LS-VCE) method by Amiri-Simkooei (2007), which explored a new kind of least squares estimator to the VCE in GPS application. The VCE approach is being proposed to be implemented in the attempt to develop more realistic weighting factors for geodetic network adjustment. The principle of VCE method generally is based on the 'unconstrained' estimation (Amiri-Simkooei, 2016). Least squares variance component estimation (LS-VCE) method is used in this study, which was first proposed by Teunissen (1988). Even though the method is rarely used in VCE methods, Amri-Simkooei (2007) found that LS-VCE is a more simple, flexible and attractive method for the estimation of unknown variance and covariance components. Therefore, this study is aimed to investigate whether the least squares estimation method can be used to solve the problem of variance component estimation in geodetic applications which include deformation survey and cadastral survey.

1.2 Problem Statement

The weight matrix is computed by using variance of the observations that were initially provided as input data in the form of standard deviation for each observation data accordingly. Grodecki (1997) showed that the weights assigned to the observations can directly influence the LSA results. The solution of LSA computation is dependent on the weight of the observations. Furthermore, the weight matrix is then used again for the computation of LSA global test (or χ^2 test) to determine whether the LSA solution passed or failed. Failure in global test renders the LSA solution as questionable, and as the result, the weight matrix used in such computation has become the possible element that needs to be examined.

Currently, there is a limitation on the information of the covariance matrix of the observables in many modern geodetic applications. For geodetic applications, it is crucial to have knowledge about the covariance matrix of the observables since that variance component is the most commonly used to determine a realistic precision. In addition, it allows us to investigate the various contributing error factors in the observations (Amiri-Simkooei, 2007). Such an example in Figure 1.1, what if a set of measurement data is computed by using StarNet software have failed the Global test (Chi-Square test). However, by removing blunders in observations or use trial and error method by changing the standard deviation values seem not practical to be done in bundles of data. Thus, determination of variance component in more systematic ways are crucially needed. This shows the importance of variance component estimation methods.

Adjustment Statistical Summary			
=====			
Iterations	=	2	
Number of Stations	=	6	
Number of Observations	=	27	
Number of Unknowns	=	8	
Number of Redundant Obs	=	19	
Observation	Count	Sum Squares of StdRes	Error Factor
Angles	15	63.833	2.459
Distances	12	900.016	10.324
Total	27	963.848	7.122
Warning: The Chi-Square Test at 5.00% Level Exceeded Upper Bound Lower/Upper Bounds (0.685/1.315)			

Figure 1.1 Example of a set of measurement data have failed Chi-Square test in StarNet software.

In recent years, conventional approaches have been used to estimate the variance component. Such methods that used include employing a rigorous computation, adopting the accuracy of specification given by the manufacturer, based on analysis of previous works, using individual groups of the observations for separating adjustments of the network, and last but not least, trial and error method, in which different combinations of the suspected variances of the observations are entered into the adjustment (Dennler, 1980; Chen, 1983). Obviously, the conventional methods are too rigid and need rigorous computation. Also, they are not suitable for current practice and with current needs such as new technologies like GPS, UAV, datum unification, photogrammetry, etc.

Since the conventional methods have their own weakness, the geodetic community has been trying to explore a better alternative. As a result, several approaches based on statistical methods have shown the potential to be more convincing. At present, many different methods exist for estimating the variance component (VCE). One of the well-known methods is the Minimum Norm Quadratic Unbiased Estimator (MINQUE). The other methods are the Best Invariant Quadratic

Unbiased Estimator (BIQUE), the Restricted Maximum Likelihood Estimator (REML), the Bayesian method, and Least Squares Variance Component Estimator (LS-VCE) to the VCE.

Regarding the previously stated scenario, the conventional methods are not challenged enough and cannot be achieved by the following problem statement. The determination of standard deviation (or the estimation of variance component) is required for geodetic networks. The present practice of determining the variance component through conventional means is faced with difficulties. Thus, the geodetic community is actively seeking an alternative method for the determination of VCE.

To address this challenge, Amiri-Simkooei (2007) come out with a new method called LS-VCE, where using the principle of least square and weight matrix is defined by the user. The main idea of this method is to identify whether it is possible to apply the least squares estimation method and solve VCE problems. LS-VCE method also sustains all the basic properties of a least squares estimator. The advantages of these methods are that the existing knowledge of least squares theory can be applied for various aspects of VCE and the precision of variance components can directly be achieved (Teunissen and Amiri-Simkooei, 2008). Therefore, this research will highlight and focus on the estimation of variance components from different types of data by using LS-VCE method for the geodetic applications which includes deformation monitoring survey and cadastral survey. Finally, the LSA and VCE computational package will be developed to estimate the variance components of the geodetic observation data.

1.3 Research Question

The research question is expected to be the key and the important indicator that will highlight the main idea for this research and to solve the issue that is needed to be encountered. Thus, the following questions need to be properly addressed:

- i) How to estimate the variance components for geodetic applications; deformation monitoring network and cadastral network?
- ii) How to determine the optimum variance of geodetic observation network using W-test statistic?

1.4 Aim and Objectives of the Research

The aim of this research is to estimate variance components from the different types of data for geodetic applications which include deformation survey and cadastral survey. Therefore, the following specific objectives were set towards achieving this aim:

- i) To perform least square adjustment and variance component estimation using LS-VCE method for geodetic surveying network.
- ii) To evaluate the optimum variance components of the geodetic network for selecting the best stochastic model using W-test statistic.

1.5 Scope of the Research

i) Two-dimensional (2D) Geodetic Network Application

This study focuses mainly on two types of geodetic networks, which include applications on deformation monitoring network and cadastral network. This research is concentrated only on the geodetic analysis in two-dimensional (2D) network for simplicity and ease of understanding. The types of observation data involved consist of distances, horizontal angles, and bearing azimuth.

ii) Data Acquisition

Deformation Monitoring Network

For deformation monitoring network, there are three types of data tested. The first dataset based on the simulation deformation geodetic network was carried out at the field of Universiti Teknologi Malaysia (UTM). The second dataset was obtained from the existing data through FREDY04 software. Then, the last data was based on the real work at Kenyir dam acquired from the supervisor's past project. All sets of data are made in the two epochs measurement.

Cadastral Network

Cadastral network utilized observation data from several types of instrument used, such as chain measurement, electronic distance measurement (EDM), and total station (TS). Scope of the area is focused on the small area of Johor, Malaysia, where Mukim Tebrau region is selected (refer to Figure 1.2). These data are provided from the Department of Survey and Mapping Johor Bahru (JUPEM). Year of data is selected randomly from 1966 to 2014 to differentiate the advancement of instruments used by the surveyors.



Figure 1.2 The study area for cadastral network data

iii) Software Used

The geodetic observation data is processed using MATLAB programming. A package was developed by using MATLAB GUIDE to solve least square adjustment computation and to estimate the optimum variance component from different type geodetic network data. Then, the package is compared with commercial software MicroSurvey StarNet (a powerful adjustment commercial software) for validation process.

iv) VCE Method Used

As mentioned in Section 1.2, LS-VCE method is used for VCE computation after network adjustment is done since it is based on the least squares principle. The simple routine is developed by using MATLAB programming in order to solve LSA and VCE computational problem. Thus, it is hoped that it will become a user-friendly package and easy to understand for educational purpose only.

1.6 Significance of the Research

The significance of this study was triggered to estimate standard deviation (variance component) in geodetic network applications from covariance matrix elements particularly on deformation monitoring network and cadastral network. In Malaysia, surveyors and practitioners usually depend on commercial software, such as MicroSurvey StarNet and GeoLab. However, a limited number of this commercial software is available, especially for deformation monitoring. Therefore, in order to encounter this limitation, this study has developed a program which able to perform LSA and VCE computation directly.

An additional aim of this study is to develop a computational LSA and VCE package by using the simple, flexible and attractive method, which is LS-VCE method, in order to gain interest and draw attention to the important of variance components in the field of geodetic network applications. Implementing the VCE method after the least square adjustment or LSA can be used as comprehensive way of estimating a proper weighting component in different type of observables corresponding to different characteristics.

Lastly, this research hopes that development of computational LSA and VCE package can be useful for attracting practicing surveyors in Malaysia as well as Geomatics Engineering students in local universities to become interested in estimation of variance component in integrated manner.

1.7 General Research Methodology

The general research methodology in this study is shown in Figure 1.3. This thesis highlighted literature review, data acquisition, data processing and data analysis.

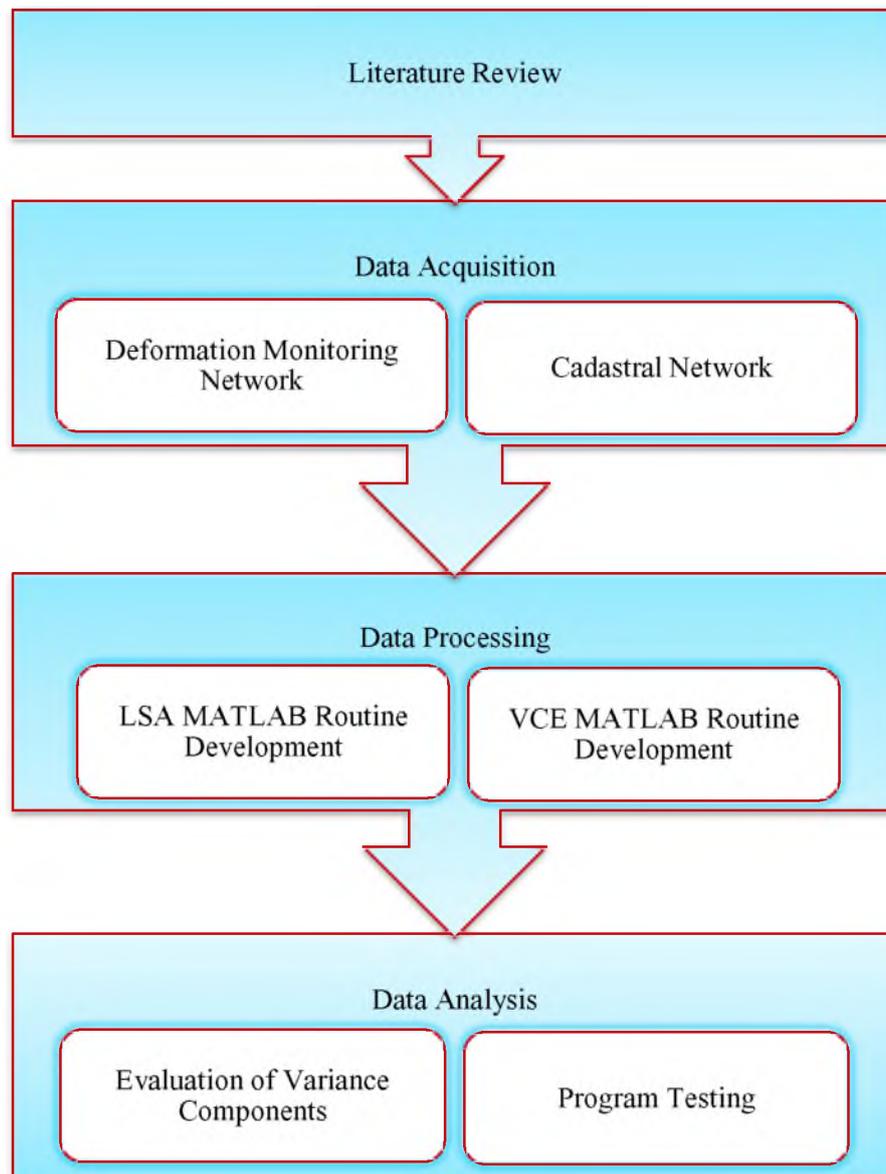


Figure 1.3 Overview of general research methodology

Literature Review

The literature review stage is required as a reference and guidance in executing this study. The topics discussed are focused on:

- i) An overview of variance component estimation, errors in the measurement, and VCE applications.
- ii) Types of variance component models
- iii) Methods available for variance component estimation
- iv) The principle of Least Squares Variance Component Estimation (LS-VCE) method which is applied in this study.
- v) Applying the VCE to the geodetic applications, where this study focused on deformation monitoring network and cadastral network.

Data Acquisition

The data acquisition of this study is gathered as follows:

- i) Deformation monitoring network
There are three sets of data, which consist of 2 sets of simulation data and real work data at Kenyir dam. All the data are measured in the 2D network which includes measurement of distances, horizontal angle and bearing azimuth. Every deformation network is made up of two epochs measurement.
- ii) Cadastral Network
In this study, cadastral data are requested from the Department of Survey and Mapping Johor Bahru (DSMM) where the data come with various type of instruments used. These instruments include observation by chain measurement, electronic distance measurement (EDM), theodolite and total station (TS). The study area is in Johor state at Mukim Tebrau region. The data are chosen randomly from the year 1966 to 2014. This is because, with the advancement of technology, various modern instruments are developed.

Data Processing and Programming

The geodetic observation data is processed using MATLAB programming. This stage involved the development of the least square adjustment (LSA) routine and followed by variance component estimation (VCE) computation. The developed package is divided into two part, which is deformation monitoring survey and cadastral survey. Each geodetic application will create their own MATLAB computation routine. This is because the format of the input data for each application is different. The data are processed by the least squares adjustment of the network and proceeded with VCE computation in order to acquire the realistic precision of measurement.

Data Analysis

As for data analysis, the result of the stochastic model from VCE computation, which is the case here, variance components need to be evaluated. The W-test statistic is practiced in order to find misspecifications in the stochastic model, to enhance an existing covariance matrix, and to test the general validity of the stochastic model. Subsequently, the developed package is compared with MicroSurvey StarNet for validation of the program developed.

1.8 The Structure of The Thesis

This thesis is organised into six chapters. The introduction to the study and research explanation has been detailed in **Chapter 1**. It starts with the background of the study followed by the problem statement, the aims and objectives of this study, the scope of this study and lastly the significance of this study.

Chapter 2 reviewed literature on several topics and begins with an overview of the principle of variance component estimation. In addition, a simple review of the available methods for VCE that includes minimum norm quadratic unbiased estimator (MINQUE), the best invariant quadratic unbiased estimator (BIQUE), maximum likelihood estimation (MLE), the Helmert method to VCE, and lastly, a detailed on least squares variance component estimation (LS-VCE) is presented since this study employed the method. This was followed by a discussion on the geodetic application, which includes deformation monitoring network and cadastral network.

Chapter 3 presents the research methodology of this study. In this chapter, data acquisition of deformation monitoring and cadastral network is explained. This chapter also included the development of least square adjustment (LSA) routine followed by variance component estimation (VCE) computation. This is to complete Objective 1 of this study. Then, a methodology to evaluate the variance component estimation was presented and discussed. The W-test was generalized for hypothesis testing to the stochastic model. This is towards achieving Objective 2 of this research.

This chapter also explained the developed computation package using MATLAB programming. The package will be divided into two choices, either deformation network computation or cadastral computation. Each geodetic application will create their own MATLAB computation routine. This is because the format of the input data of each application is different. A detailed explanation about the function of the package and how to employ it for different types of geodetic observation data was also described in this chapter.

Chapter 4 and **Chapter 5** discuss the result and analysis of deformation monitoring network and cadastral network, respectively. The purpose of this chapter was to come up with a realistic optimum variance component based on various types of geodetic observation data. The analysis was made to select the best model of variance component for each geodetic network tested in this study. Next, the developed computational package was compared with a powerful adjustment commercial software for validation process.

Chapter 6 is the last chapter of this research, where the overall study and recommendations listed for further research study and enhancements for future work are summarized.

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