## CROWD DETECTION FROM AERIAL IMAGES

### SITI ERNEE BINTI MD ZAINI

A project report submitted as partial fulfilment of the requirements for the award of the Master of Engineering (Electrical-Computer and Microelectronic System)

Faculty of Electrical Engineering
Universiti Teknologi Malaysia

JANUARY 2015

Dedicated, in thankful appreciation for support and encouragement to my beloved husband Azizal bin Adnan, my daughter Arissa El-Zahrah bt Azizal, my mother, my grandmother, families and friends.

### **ACKNOWLEDGEMENT**

Praise be to Allah S.W.T., the Most Merciful and the Most Compassionate. Peace be upon him, Muhammad S.A.W, the messenger of God.

First and foremost, I would like to express my heartily gratitude to my academic advisor and supervisor, Dr. Usman Ullah Sheikh for his proposal, insightful comments, and guidance on this project. Without his guidance, assistance, and involvement in every step throughout the process, this research would have never been published. I would like to thank you very much for your support and understanding over these past two semesters.

My appreciation also goes to my family especially my husband, Mr Azizal bin Adnan who has been so patient and supported me all these years. Thanks for their encouragement, love and emotional support that they had given to me.

Last but not least, I would like to express my appreciation to my friends especially Nor Hafizah, Wan Mohd Amir Haris and Mohd Faizi, thank you for listening to my problems. Millions of thanks also go to those who were involved directly or indirectly in this project.

### **ABSTRACT**

The detection of crowd from surveillance imagery is important to monitor public places and to ensure public safety. Hence, this work proposes crowd detection from static image captured from Unmanned Aerial Vehicle. The proposed methodology consists of three steps: FAST feature extraction, Gray Level Co-Occurrence Matrix (GLCM) feature computation and the use of Support Vector Machine (SVM) for classification. The use of FAST corner detector is to obtain regions of interest where possible existence of crowd. The application of GLCM is to extract second order statistical texture features for texture analysis. The result of GLCM then, will be classified to crowd and non-crowd using SVM. For evaluation, ten different images were used taken in various crowd formation, event and location. The accuracy of the proposed method is obtained and the classification results are shown visually.

#### **ABSTRAK**

Pengesanan orang ramai daripada imej pengawasan adalah penting untuk memantau tempat-tempat awam dan untuk memastikan keselamatan awam. Oleh itu, kerja ini mencadangkan pengesanan orang ramai daripada imej statik ditangkap dari Udara Tanpa Pemandu Kenderaan. Kaedah yang dicadangkan terdiri daripada tiga langkah: pengekstrakan ciri FAST, Gray Tahap Bersama Kejadian Matrix (GLCM) ciri pengiraan dan penggunaan Sokongan Mesin Vektor (SVM) untuk klasifikasi. Penggunaan FAST pengesan sudut adalah untuk mendapatkan kawasan-kawasan yang menarik di mana wujud kemungkinan orang ramai. Penggunaan GLCM adalah untuk mengeluarkan perintah kedua ciri tekstur statistik untuk analisis tekstur. Hasil GLCM kemudian, akan diklasifikasikan kepada orang ramai dan bukan orang ramai dengan menggunakan SVM. Untuk penilaian, sepuluh gambar yang berbeza telah diambil yang digunakan dalam pelbagai pembentukan orang ramai, majlis dan lokasi. Ketepatan kaedah yang dicadangkan diperolehi dan keputusan klasifikasi ditunjukkan secara visual.

# TABLE OF CONTENTS

CHAPTER	TITLE		PAGE	
	DECLARA	ΓΙΟΝ	ii	
	DEDICATION		iii	
	ACKNOWL	LEDGEMENT	iv	
	ABSTRACT		v	
	ABSTRAK		vi	
	TABLE OF	TABLE OF CONTENTS		
	LIST OF TA	ABLES	ix	
	LIST OF FI	GURES	X	
	LIST OF AI	BBREVIATIONS	xiv	
	LIST OF SY	MBOLS	XV	
	LIST OF AI	PPENDICES	xvi	
1	INTRODUC	CTION	1	
	1.1 Introd	luction	1	
	1.2 Backs	ground	2	
	1.3 Probl	em Statement	2	
	1.4 Object	etives	3	
	1.5 Resea	arch Scope	3	
	1.6 Thesi	s Organization	4	
2	LITERATU	RE REVIEW	5	
	2.1 Introd	luction	5	
	2.2 Key (	Challenges in crowd detection	5	
	2.3 Relate	ed Works	6	
	2.3.1	Feature Extraction	8	

		2.3.2 Support Vector Machines (SVMs)	16
		2.3.3 Crowd Density Estimation	18
		2.3.4 Crowd tracking	18
	2.4	Summary	19
3	RES	ERCH METHODOLOGY	20
	3.1	Introduction	20
	3.2	Research Design	20
	3.3	Project Methodology	21
		3.3.1 Image pre-processing	23
		3.3.2 FAST Method for feature extraction	24
		3.3.3 Grey Level Co-occurrence Matrices	25
		3.3.4 Support Vector Machine (SVM)	31
4	RES	ULTS AND DISCUSSION	32
	4.1	Introduction	32
	4.2	Training and Testing Image	32
	4.3	Accuracy Evaluation	34
	4.4	Discussion on Result	41
5	CONCLUSION AND RECOMMENDATION		43
	1.1	Conclusion	43
	1.2	Limitation	43
	1.3	Recommendation	43
REFERENCE			45
APPENDICES A-D			49

# LIST OF TABLES

TABLE NO.	TITLE	PAGE
4.1	GLCM parameters used in the project.	34
4.2	Number of testing images implemented in this project.	34
4.3	The percentage of accuracy of each of the images.	35

# LIST OF FIGURES

FIGURE NO	TITLE	PAGE
2.1	(a) Stadium1 test image from airborne image sequence	2
	including both crowded and sparse people groups, (b)	
	Closer view of a crowded region of (a) (Sirmacek &	
	Reinartz, 2011).	
2.2	A framework for crowd analysis (Zhan et al., 2008).	3
2.3	Schematic representation of the topics tackled in this	4
	survey and the proposed taxanomy for the people	
	counting and crowd behavior understanding problems	
	(Julio & Soraia, 2010).	
2.4	(a) A pyramid of image patches of increasing spatial	9
	extent is constructed at each image location. (b) The	
	obtained variation of crowd and non-crowd models can	
	be used to infer the local image content (Arandjelovic,	
	2008).	
2.5	Red boundary indicates background regions. (a) The	10
	photo represents less crowded situation and (b)	
	represents crowded environment (Hinz, 2009).	
2.6	12 point segment test corner detection in an image	12
	patch. The highlighted squares are the pixels used in	
	the corner detection. The pixel at p is the centre of a	
	candidate corner. The arc is indicated by the dashed	
	lines passes through 12 contiguous pixels which are	
	brighter that p by more than the threshold (Rosten,	
	2006).	

2.7	(a) Original airborne image including crowd and sparse people groups. (b) Detected FAST feature	13
	locations are represented with red crosses (Sirmacek &	
2.0	Reinartz, 2011).	1.4
2.8	Gabor filter bank for 3 scales and 8 orientations  (Mayrham & Wysehl 2012)	14
2.0	(Meynberg & Kuschk, 2013).	1.0
2.9	Test images with classification results of the detected	16
	interest points. green = classified as crowd, red =	
2.10	classified as non-crowd (Meynberg & Kuschk, 2013).	1.77
2.10	2 images from left are a crowd image after Gabor	17
	Filter had been applied and the next 2 images to the	
0.11	right is a non-crowd image.	
2.11	Crowd density feature vectors are extracted from the	
	input image through texture analysis GLCM method	
0.10	(Marana et al., 1997).	
2.12	(a) Raw classification result (white correspond to	
	crowd and black to non-crowd) (b) the probability of	
	crowd using a radial basis function SVM	
	(Arandjelovic, 2008).	
2.13	(a) Detected motion paths for two persons walking in	20
	opposite directions, (b) Detected motion paths for two	
	persons which are walking very close to each other	
	(Sirmacek & Reinartz, 2011).	
3.1	Research approach.	21
3.2	Crowd detection flow chart.	23
3.3	FAST Corner Detection.	25
3.4	a) Original image b) the bottom picture show the	26
	image after implementing FAST method. The entire	
	green points represented corner points that been	
	detected in the image.	
3.5	Original image of non-crowd. (b) GLCM images of	29

non-crowd image.

3.6	(a) Original image of size 64x64 crowd image. (b)	30
	GLCM images of crowd image with window size=8.	
	(c) GLCM images with window size=3.	
2.5		2.1
3.7	Training set of non-crowd images.	31
3.8	Training set of crowd images.	31
4.1	10 dataset of images that been used in this project	33
4.2	(a) Original input image of size 900x900. (b) The detected crowd region using patch size of 90x90 and GLCM feature of (b) homogeneity, (c) entropy, (c) contrast and (d) energy. Red region shows region of	36
	correctly detected non-crowd area and green as correctly detected crowd area. Accuracy for (b) is 100%, (c) 94.40% (d) 72.2% and (e) 66.67%.	
	However, there is misclassification in (d) and (e)	
4.3	(a) Original input image of size 900x900. (b) The	37
	detected crowd region using patch size of 90x90 and	
	GLCM feature of (b) entropy, (c) homogeneity, (c)	
	contrast and (d) energy. Red region shows region of	
	correctly detected non-crowd area and green as	
	correctly detected crowd area. Accuracy for (b) is	
	78.88%, (c) 92.70% (d) 78.88% and (e) 72.73%.	
	However, there is misclassification in all images.	
4.4	(a) Original input image of size 900x900. (b) The	38
	detected crowd region using patch size of 90x90 and	
	GLCM feature of (b) homogeneity, (c) entropy, (c)	
	contrast and (d) energy. Red region shows region of	
	correctly detected non-crowd area and green as	
	correctly detected crowd area. Accuracy for (b) is	
	95.24%, (c) 47.62% (d) 42.86% and (e) 66.67%.	

However, there is misclassification in all images.

- 4.5 (a) Original input image of size 900x900. (b) The 39 detected crowd region using patch size of 90x90 and GLCM feature of (b) homogeneity, (c) entropy, (c) contrast and (d) energy. Red region shows region of correctly detected non-crowd area and green as correctly detected crowd area. Accuracy for (b) is 80.00%, (c) 60.00% (d) 60.00% and (e) 40.00%. However, there is misclassification in all images.
- 4.6 (a) Original input image of size 900x900. (b) The 40 detected crowd region using patch size of 90x90 and GLCM feature of (b) homogeneity, (c) entropy, (c) contrast and (d) energy. Red region shows region of correctly detected non-crowd area and green as correctly detected crowd area. Accuracy for (b) is 100.00%, (c) 89.19% (d) 97.3% and (e) 75.68%. However, there is misclassification in all images.
- 4.7 The detected crowd region using patch size of (a) 41 180x180 (c) 90x90 (e) 60x60 and GLCM feature of homogeneity. Detected FAST feature locations are represented with green points patch size of (b) 180x180, (c) 90x90 (f) 60x60.

## LIST OF ABBREVIATIONS

FAST - Features from Accelerated Segment Test

GLCM - Gray-level co-occurrence matrix

HWT - Haar wavelet transform

RGB - Red Green Blue

SIFT - Scale Invariant Features Transform

SVM - Support Vector Machine

UAV - Unmanned Aerial Vehicle

## LIST OF SYMBOLS

p - pixel

t - threshold

σ - Bandwidth of Gaussian kernel

l - Mean of distance

 $I_p$  - Intensity

*n* - Set of contiguous pixels

*i* - Spatial coordinates - horizontal

j - Spatial coordinates – vertical

 $p_{ij}$  - The matrices

*K* - Gray tone

# LIST OF APPENDICES

APPENDIX	TITLE	PAGE
A	Matlab Coding for main function	49
В	Matlab Coding for GLCM Function	50
C	Matlab Coding for SVM	53
D	Matlab Coding on reading image	55

### **CHAPTER 1**

### INTRODUCTION

### 1.1 Introduction

Crowd has been defined as a large number of people gathered together in a disorganized or uncontrollable way (The Free Dictionary). A crowd may be described through a mutual purpose or set of reactions, such as at a sports event, political rally, or religious event, or simply be made up of many people going about their business in a busy area such as shopping mall and market. Frequently, these large gatherings of people occur without serious problems. Occasionally the combination of insufficient facilities and deficient crowd management results in disasters, injury and death.

Nowadays the crowd phenomenon has been more common due to the steady population growth along with the worldwide urbanization. Therefore it is not surprising if there are a lot of research disciplines and analysis has been made in this field. The crowd phenomenon could be applied in several applications such as crowd management, public space design, virtual environment as well as visual surveillance (Zhan et al., 2008). In order to avoid crowd related disasters and ensure the public safety, crowd analysis has been applied in developing management strategies especially for large and well-known events such as concerts and sport matches. Besides that, public space design applications practise crowd analysis to provide rules and procedures for public design. Furthermore, virtual environment application models crowd as mathematic model in virtual environment to enhance the simulation of crowd phenomena and this will lead to the improvement of human life experience

and knowledge. Visual surveillance application uses crowd analysis for automatic detection of irregularities, anomalies, alarms as well as panics. As a result, this project will focus more to visual surveillance crowd analysis application since monitoring and detecting large crowds is an important topic in this field and it can provide information for decision making by the local security forces.

### 1.2 Background

Crowd detection has been studied since many years ago and had attracted many researchers. The initial works in this field, several researchers tried to solve crowd detection problem using street or indoor cameras which are known as close-range cameras (Davis et al., 1995), (Regazzoni & Tesei, 1994). By using these types of cameras, it is not possible to monitor and detect crowd at bigger events. However, nowadays a lot of work had been done using outdoor and moving camera such as airborne camera (Sirmacek & Reinartz, 2011), (Meynberg & Kuschk, 2013), aerial camera mounted on helicopters (Hinz, 2009) as well as satellite images (Sirmacek & Reinartz, 2011). Unmanned Aerial Vehicle (UAV) is an aircraft without human pilot on board. Image from UAV can be used to monitor bigger events.

Hence using a visible image from UAV can be an effective approach for monitoring, detecting and tracking crowds in large events. This thesis focuses on using visible image from UAV to detect and track crowd as well as develop algorithms which can work on image from UAV.

### 1.3 Problem Statement

The detection of crowd from image is very important to ensure safety of people. This information is very crucial especially for police departments and crisis management teams. There are several key challenges which are, limited resolution of images, occlusion, illumination changes, and any other obstacles that could influence detection process, as well as there are some difficulties in analysing crowd event.

From previous study (Meynberg & Kuschk, 2013), there are still ~10% misclassification between crowd and non-crowd due to poorly chosen parameters of global classifier. Hence, this project will emphasize on getting the optimum crowd detection from similar images used by previous studies.

## 1.4 Objectives

This following are the objectives of this study:

- 1) To detect crowd of people from visible image.
- 2) To use an aerial image sequence derived from moving platform such as UAV.
- 3) To achieve high detection rate of crowd from aerial images.

### 1.5 Research Scope

The research scope of this project is as follows. Firstly, this project is implemented using MATLAB for offline processing.

Secondly, this project utilizes images from UAV as input crowd images. In order to evaluate the effectiveness of the proposed method, images containing crowd during day time with good weather are considered. The images used in the project were obtained from the internet.

## 1.6 Thesis Organization

This study includes five chapters. Chapter two provides a comprehensive literature review on the methods on how to detect crowd based on previous studies. Finally, based on the literature review the problems are identified.

Chapter three proposes the methodology. In this chapter the methods and steps that are proposed in order to perform crowd detection are described. The methods consist of; Features from Accelerated Segment Test (FAST) feature extraction, further features extraction using Gray Level Co-occurrence Matrices (GLCM) and Support Vector Machine (SVM) to classify between crowd and noncrowd.

In chapter four the results of the crowd detection is provided. Discussions on the results of the project are also included in this chapter.

Last but not least, chapter five concludes this work. Some comments and suggestions for future improvements are provided in this chapter.

#### REFERENCES

- Albregtsen, F. (2008). Statistical Texture Measures Computed from Gray Level Cooccurrence Matrices. *Image Processing Laboratory Department of Informatics, University Oslo*,.
- Arandjelovic, O. (2008). Crowd detection from still images. *British Machine Vision Conference (BMVC'08)*, Vol. 1, Citeseer, pp. 523–532.
- Castleman, K. (1996). Digital image processing. Englewood Cliffs: Prentice-Hall.
- Clausi, D. A., & Deng, H. (2005). Design-based Texture Feature Fusion Using Gabor Filters and Co-Occurrence Probabilities. *IEEE Transactions on Image Processing*, Vol. 14, pp. 925-936.
- Dalal, N., & Triggs, B. (2005). Histogram of oriented gradients for human detection. Computer Vision and Pattern Recognition. 25 June 2005. San Diego, CA, pp.886-893.
- Daugman, J. G. (1988). Complete discrete 2-D Gabor transforms by neural networks for image analysis and compression. *Acoustics, Speech and Signal Processing*, 1169-1179.
- Davis, A., J.Yin, & S, V. (1995). Crowd monitoring using image processing . *IEEE Electronic and Communications Engineering Journal vol* 7 (1), 37-47.

- Drucker, H., Burges, C. J., Kaufman, L., Smola, A., & Vapnik, V. (1997). Support vector regression machines. *Advances in neural information processing* systems, 155-161.
- Ghidoni, S., Cielniak, G., & Menegatti, E. (2012). Texture-based crowd detection and localisation. Advances in Intelligent Systems and Computing, Vol. 193, pp. 725-736
- Guillaume, L., & Miroslav, R. (2011). Texture segmentation: Co-occurrence matrix and Laws' texture masks methods. *Heriot-Watt University, Universitat de Girona, Universit'e de Bourgogne*.
- Haralick, R. (1979). Statistical and structural approaches to texture. *Proceedings of the IEEE*, *Vol.* 67(5), 786-804.
- Haralick, R., Shanmugan, K., & Dinstein, I. (1973). Textural Features for Image Classification. *IEEE Transactions on Systems, Man, and Cybernetics, Vol. SMC-3*, 610-621.
- Hinz, S. (2009). Density and motion estimation of people in crowded environments based on aerial image sequences . *ISPRS Hannover Workshop on High-Resolution Earth Imaging for Geospatial Information*, Vol.1
- Husni, M., & Nanna, S. (2010). Crowd Event Detection in Computer Vision.
  International Conference Signal Processing System, July 2010. Dalian, 444-447
- Jakkula, V. (2006). Tutorial on Support Vector Machine (SVM). *School of EECS*, Washington State University. Pullman 99164.
- Julio, S., & Soraia, M. (2010). Crowd Analysis using Computer Vision Techniques. *IEEE Signal Processing Magazine*. Vol. 27(5), pp. 66.77.

- Kadir, A. (2014). A Model of Plant Identification System Using GLCM, Lacunarity And Shen Features. *Research Journal of Pharmaceutical, Biological and Chemical Sciences Vol.* 5(2), 1-10.
- Kalman, R. (1960). A new approach to linear filtering and prediction problems. *Journal of basic Engineering 82 (1)*, 35-45.
- Lin, S.-F., Chen, J.-Y., & Chao, H.-X. (2001). Estimation of number of people in crowded scenes using perspective transformation. *Systems, Man and Cybernetics, Part A: Systems and Humans*, 645-654.
- Lowe, D. G. (1999). Object Recognition from Local Scale-Invariant features.

  \*Proceedings of the International Conference on Computer Vision. 20-27 Sep 1999. Kerkyra, 1150-1157.
- Marana, A., Velastin, S., Costa, L., & Lotufo, R. (1997). Estimation of crowd density using image processing. *IEE Colloquium on Image Processing for Security Applications*, 10 Mar 1997. London, 1-8.
- Meynberg, O., & Kuschk, G. (2013). Airborne Crowd Density Estimation. *ISPRS*Annals of the Photogrammetry, Remote Sensing and Spatial Information

  Sciences,.
- Nello, C., & John, S.-T. (2000). "An Introduction to Support Vector Machines and Other Kernel-based Learning Methods. Cambridge University Press.
- Nitish, Z., & Vrushsen, P. (2012). GLCM Textural Features for Brain Tumor Classification. *International Journal of Computer Science Issues*, Vol. 9, 354-359.
- Regazzoni, C., & Tesei, A. (1994). Local density evaluation and tracking multiple objects from complex image sequences. 20th International Conference on

- *Industrial Electronics, Control and Instrumentation (IECON).5-9 Sep 1994.*Bologna, 744-748.
- Rosten, E. a. (2006). Machine Learning for highspeed corner detection . *lecture Notes in Computer Science 3591*, 430.
- Sirmacek, B., & Reinartz, P. (2011). Automatic crowd analysis from airborne images. *Recent Advances in Space Technologies (RAST), 2011 9-11 June 2011. Istanbul.*, 116-120.
- Sirmacek, B., & Reinartz, P. (2011). Automatic crowd analysis from very high resolution satellite images. *PIA* 2011. 5-7 Oct 2011. Munich, Germany, pp.1-6.
- Sirmacek, B., & Reinartz, P. (2011). Kalman filter based feature analysis for tracking people from airborne images. *ISPRS Workshop High-Resolution Earth Imaging for Geospatial Information*. Volume XXXVIII-4/W19, 2011, pp.303-30
- Sirmacek, B., & Unsalan, C. (2010). A probabilistic framework to detect buildings in aerial and satellite images. . *IEEE Transactions on Geoscience and Remote Sensing*. Vol.49, pp.211-221.
- Srinivasan, V., Eswaran, C., & Sriraam, N. (2005). Artificial Neural Network Based Epileptic Detection Using Time-Domain and Frequency-Domain Features. *Journal Medicine System*, 29(6), 647-660.
- Wei Hsu, C., C. C., & ChihJen, L. (2010). A Practical Guide to Support Vector Classification. *Bioinformatics*, *1*, 1-16.

- Xinyu, W. G., Ka, K. L., & Yangsheng, X. (2009). Crowd Density Estimation Using Texture Analysis and Learning. *Buletin of Advanced Technology Research Vol* 3, 35-41.
- Zhan, B., Monekosso, D. N., Remagnino, P., Velastin, S. A., & Xu, Q. L. (2008).

  Crowd Analysis: A Survey. *Machine Vision and Application*. Vol.19, pp.345–357