PREDATOR-PREY MODEL WITH CONSTANT RATE OF HARVESTING

NURUL AINA BINTI ARIFIN

A thesis submitted in fulfillment of the requirements for the awards of the degree of Master of Science (Mathematics)

Faculty of Science

Universiti Teknologi Malaysia

JANUARY 2014

Special dedicate to my beloved family

Arifin Bin Abdullah Rohani Binti Dali Mohd Fakharuddin Bin Arifin Nurulain Hanis Binti Shahruni Mohamad Amirudin Bin Arifin and

Nurul Atiqah Arifin

Thanks for all the supports, sacrifices, patients and willingness to share my dreams with me...

To my honoured supervisor, Dr Faridah Mustapha, my friends (Mira, Hidayah, Yana, Azira, Amiza and Aisya) and all UTM lecturers Thank you for everything you taught me. Giving me inspiration to be knowledge person.

ACKNOWLEDGMENT

All praise belongs to Allah (SWT), The Lord of the Universe, without the health, strength and perseverance he gave, I would not be able to complete this thesis.

First and foremost, I would like to express my gratefulness and appreciation to my supervisor Dr. Faridah Mustapha for her guidance and support that she had given me along the completion of this project.

I also feel grateful to PSZ for providing me the information for my research study.

Finally, I also would like to thank all my beloved persons in my life that inspire and motivate me a lot throughout all the hard works while carrying out this research, especially to my beloved parents, Arifin Abdullah and Rohani Dali, my brother, Fakharudin, my little brother and sister, Amirudin and Atiqah. Last but not least, thanks to all my friends for sharing ideas and giving encouragement.

ABSTRACT

Predator-prey model is the first model to illustrate the interaction between predators and prey. It is a topic of great interest for many ecologists and mathematicians. This model assumes that the predator populations have negative effects on the prey populations. The generalized equation of this model is the response of the populations would be proportional to the product of their population densities. Prey population grows with limited by carrying capacity, K and it is called the logistic equation. Thus, in this research, there are four different cases are analyzed which are predator-prey model, predator-prey model with harvesting in prey, predator-prey model with harvesting in predator and predator-prey model with harvesting in both populations. Systems of ordinary differential equation are used for all models. The objectives of this research are i) to study the concept of Lotka-Volterra predator-prey model, ii) to analyze the predator-prey model with constant rate of harvesting in prey, iii) to analyze the predator-prey model with constant rate of harvesting in predator, iv) to analyze the predator-prey model with constant rate of harvesting in both populations. In analyzing all four models, equilibrium points will be obtained and analyzed for the stability by using Routh-Hurwitz Criteria. Lastly, some numerical examples and graphical analysis are shown to illustrate the stability of the stable equilibrium points and the effects of harvesting to the systems.

ABSTRAK

Pemangsa-Mangsa merupakan model yang pertama Model untuk menggambarkan interaksi antara pemangsa dan mangsa. Ia adalah satu topik yang menarik minat besar bagi semua ahli ekologi dan ahli matematik. Model ini mengandaikan populasi pemangsa memberi kesan negatif kepada populasi mangsa. Persamaan umum model ini adalah tindak balas sesuatu populasi yang berkadar dengan hasil kepadatan sesuatu populasi. Populasi mangsa membesar dengan dihadkan oleh keupayaan membawa, K dan ia dipanggil sebagai persamaan logistik. Oleh itu, dalam kajian ini, terdapat empat kes berbeza yang dianalisis iaitu model pemangsa-mangsa, model pemangsa-mangsa dengan penangkapan dalam mangsa, model pemangsa-mangsa dengan penangkapan dalam pemangsa dan model pemangsa-mangsa dengan penangkapan dalam kedua-dua populasi. Sistem persamaan pembezaan biasa digunakan untuk keseluruhan model. Objektif kajian ini adalah i) untuk mengkaji konsep model Lotka-Volterra Pemangsa-mangsa, ii) untuk menganalisis pemangsa-mangsa model dengan kadar tetap penangkapan dalam mangsa, iii) untuk menganalisis pemangsa-mangsa model dengan kadar tetap penangkapan dalam pemangsa, iv) untuk menganalisis pemangsa-mangsa model dengan kadar tetap penangkapan dalam kedua-dua populasi. Dalam menganalisis keempat-empat model tersebut, titik keseimbangan akan diperolehi dan kestabilannya akan dianalisis dengan menggunakan Kriteria Routh-Hurwitz. Akhir sekali, beberapa contoh berangka dan analisis graf ditunjukkan untuk memperlihatkan kestabilan titik keseimbangan dan kesan penangkapan dalam sistem.

TABLE OF CONTENTS

CHAPTER	TITLE	PAGE
	DECLARATION	ii
	DEDICATION	iii
	ACKNOWLEDGEMENT	iv
	ABSTRACT	V
	ABSTRAK	vi
	TABLE OF CONTENTS	vii
	LIST OF SYMBOLS	xi
	LIST OF FIGURES	xii
	LIST OF TABLES	XV
	LIST OF APPENDICES	xvi

1 INTRODUCTION

1.1	Background of Research	1
1.2	Problem Statement	3
1.3	Objectives of Research	3
1.4	Scope of Research	4
1.5	Significant of Research	4

2 LITERATURE REVIEW

2.1	Introduction	5
2.2	Mathematical Modeling	6

2.3	Preda	tor-Prey Interaction	7
2.4	Lotka	-Volterra Predator-Prey Model	8
2.5	Predator-Prey Model with Constant Rate of Harvesting		9
	2.5.1	Definition of Harvesting in Population Dynamics	10
	2.5.2	Stability with Harvesting	11

3 RESEARCH METHODOLOGY

3.1	Introduction	14
3.2	Nullclines	15
3.3	Equilibrium Analysis	16
3.4	Eigenvalues	17
	3.4.1 Asymptotically Stability	19
3.5	Routh – Hurwitz Criteria	20
3.6	Numerical Method to Solve Ordinary Differential	21
	Equation	

4 **PREDATOR-PREY MODEL**

4.1	Introduction	23
4.2	The Model	24
4.3	Equilibrium Points of Predator-Prey Model	26
4.4	Analyzing the Model	28
4.5	Numerical Examples	33

5 PREDATOR-PREY MODEL WITH CONSTANT RATE OF PREY HARVESTING

5.1	Introduction	38
5.2	The Model	39
5.3	Equilibrium Points of Predator-Prey Model with Harvesting in Prey	42
5.4	Analyzing the Model	45
5.5	Numerical Examples	51
PRE RAT	DATOR-PREY MODEL WITH CONSTANT TE OF PREDATOR HARVESTING	
6.1	Introduction	58
6.2	The Model	59
6.3	Equilibrium Points of Predator-Prey Model with Harvesting in Predator	62
6.4	Analyzing the Model	65
6.5	Numerical Examples	69
PRE RAT	DATOR-PREY MODEL WITH CONSTANT TE OF BOTH POPULATION HARVESTING	
7.1	Introduction	73
7.2	The Model	74
7.3	Equilibrium Points of Predator-Prey Model with Harvesting in Both Populations	77
7.4	Analyzing the Model	79
7.5	Numerical Examples	83

8 CONCLUSION AND RECOMMENDATIONS

APPENDICES		94
REFERENCES		91
8.3	Recommendations	90
8.2	Research Conclusion	88
8.1	Introduction	87

LIST OF SYMBOLS

x(t)	-	Prey population
y(t)	-	Predator population
H_x	-	Prey harvesting
H_y	-	Predator harvesting
$\lambda_{1,2}$	-	Eigenvalues of equilibrium point
r	-	Growth rate of prey
K	-	Carrying capacity of the prey.
α	-	Rate of consumption of prey by predator.

- β Conversion of prey consumed into predator reproduction rate.
- *c* Death rate of predator

LIST OF FIGURES

FIGURE NO.	TITLE	PAGE
Figure 3.1	Phase portraits for real or distinct eigenvalues	18
Figure 3.2	Phase portraits for complex eigenvalues	19
Figure 4.1	The death rate of predator, $K\beta$ versus the conversion of prey into predator reproduction rate, <i>c</i> with fixed values for $r = 1$ and $\alpha = 1$.	32
Figure 4.2	Phase portraits for a nonlinear system (4.10)	34
Figure 4.3	The graph show population densities of prey and predator versus time, $r = 1$, $\alpha = 1$, $K = 2$, $\beta = 0.05$ and $c = 0.3$	35
Figure 4.4	Phase portraits for a nonlinear system (4.11)	36
Figure 4.5	The graph show population densities of prey and predator versus time, $r = 1$, $\alpha = 1$, $K = 10$, $\beta = 0.05$ and $c = 0.3$	37
Figure 5.1	Constant rate of prey harvesting, H_x versus growth rate of prey and carrying capacity, rK	43
Figure 5.2	Constant rate of prey harvesting, H_x versus death rate of predator, <i>c</i> with $r = 1$, $K = 2$, $\alpha = 1$ and $\beta = 0.05$.	50
Figure 5.3	Phase portraits for a nonlinear system (5.23)	52

Figure 5.4	Phase portraits for a nonlinear system with $c = 0.07$ and $H_x = 0.45$	53
Figure 5.5	The graphs show the population densities of prey and predator versus time, $r = 1$, $K = 2$, $\alpha = 1$, $\beta = 0.05$. a) $c = 0.09$, $H_x = 0.4$ b) $c = 0.07$, $H_x = 0.45$	53
Figure 5.6	Phase portraits for a nonlinear system (5.24)	55
Figure 5.7	Phase portraits for a nonlinear system with $c = 0.07$ and $H_x = 0.3$	56
Figure 5.8	The graphs show the population densities of prey and predator versus time, $r = 1$, $K = 2$, $\alpha = 1$, $\beta = 0.05$. a) $c = 0.08$, $H_x = 0.2$ b) $c = 0.07$, $H_x = 0.3$	56
Figure 6.1	Constant rate of predator harvesting, H_y versus growth rate of prey, <i>r</i> with $K = 10$, $\alpha = 1$, $\beta = 0.05$ and $c = 0.3$	64
Figure 6.2	Phase portraits of nonlinear system (6.20) with $r = 1$ and $H_y = 0.01$	70
Figure 6.3	Phase portraits with $r = 2$ and $H_y = 0.02$	71
Figure 6.4	The graph show the population densities of prey and predator versus time $K = 10$, $\alpha = 1$, $\beta = 0.05$, $c = 0.3$ a) $r = 1$ and $H_y = 0.01$ b) $r = 2$ and $H_y = 0.02$	71
Figure 7.1	Constant rate of prey harvesting, H_x versus growth rate of prey and carrying capacity, rK	78

 $(\alpha = 1, \beta = 0.05, c = 0.3 \text{ and } H_y = 0.02)$

- **Figure 7.2** Constant rate of prey harvesting, H_x versus the conversion of prey consumed into predator reproduction rate, β with ($r = 1, K = 20, \alpha = 1, c = 0.3$ and $H_y = 0.02$).
- **Figure 7.3** The graph show the population densities of prey and predator versus time, r = 1, K = 100, $\alpha = 1$, $\beta = 0.05$, c = 0.3, $H_x = 0.01$ and $H_y = 0.02$

LIST OF TABLES

TABLE NO.	TITLE	PAGE
5.1	Parameters used in predator-prey model with constant rate of harvesting in prey	41
8.1	Summarization on the stability of equilibrium points with the conditions for predator-prey model without harvesting, predator-prey model with harvesting in prey, predator-prey model with harvesting in both populations.	89

LIST OF APPENDICES

APPENDIX	TITLE	PAGE
Α	Calculation of Eigenvalues for Each Equilibrium Points and Calculation of Fourth Order Runge Kutta Using Maple Software.	94
В	Phase Portraits of the Predator-Prey Model with Constant Rate of Prey Harvesting using Matlab Software.	96

CHAPTER 1

INTRODUCTION

1.1 Background of Research

In the ecology system, the predator-prey model is amongst the oldest studies and also the first model to illustrate the interaction between predators and prey. This model assume that the predator populations have negative effects on the prey populations and this system was formulated by Vito Volterra, an Italian mathematician and Alfred Lotka, an American mathematical biologist in 1925 (Boyce and DiPrima, 2010).

There are several known predator-prey models such as Lotka-Volterra model, Logistic equation, Holling Tanner Type 2 and Type 3 models, Yodzis model and so on. This study only focuses on the most well known Lotka-Volterra model. This model has been analyzed by various text books in dynamical systems, mathematical biology, ecology, differential equations etc. The generalized equation of this model is the response of the populations would be proportional to the product of their population densities. The prey population grows infinitely in the absence of predators. Therefore, the logistic equation or often called as carrying capacity of the environment was added to the prey equation given,

$$\frac{dx}{dt} = rx(t) \left(1 - \frac{x(t)}{K} \right) - \alpha x(t) y(t),$$

$$\frac{dy}{dt} = \beta x(t) y(t) - cy(t),$$
(1.1)

where

- x(t) denotes prey population.
- y(t) denotes predator population.
- *r* denotes the growth rate of prey.
- *K* denotes carrying capacity.
- α denotes the rate of consumption of prey by predator.
- β denotes the conversion of prey consumed into predator reproduction rate.
- *c* denotes death rate of the predator.

Our study also continues by adding constant rate of harvesting to the model. In the previous research, Brauer (1977), Dai and Tang (1998), Martin and Ruan (2001), Kar and Pahari (2006), Syamsuddin and Malik (2008), Xia et al. (2009) and Agarwal and Pathak (2012) had analyzed the constant rate of harvesting either prey or predator population. According to Kar and Pahari (2006), many of interesting dynamical behaviors such as the stability of the equilibrium points, existence of Hopf bifurcation and limit cycles have been observed. Therefore, this study concern on analyze the stability of the model by adding the harvesting to both populations by using the method of differential equation.

Lotka-Volterra predator-prey model plays a crucial role in the population dynamics and also one of the major advanced theories introduced by Lotka and Volterra. They assumed the response of the population would be proportional to the product of their population densities without any delayed and constant rate of harvesting. The model formulation is in the equation (1.1). Some of the studies found that the rate of harvesting has been used to control the increasing of population and as a controller of the population density (Ouncharoen et al., 2010). This means that harvesting can make whether the population increases or decreases for a continuity yields but it will limited by a carrying capacity in equation (1.1).

In this project, the constant rate of harvesting will be added to either preys, predators or both populations and we will analyze the stability of the equilibrium points of the predator-prey model.

1.2 Problem Statement

This study is focused on how constant rate of harvesting affect the dynamics of the predator-prey system.

1.3 Objectives of Research

The objectives of this research are:

- 1. To study the concept of Lotka-Volterra predator-prey model.
- 2. To analyze the predator-prey model with constant rate of harvesting in prey.
- 3. To analyze the predator-prey model with constant rate of harvesting in predator.
- 4. To analyze the predator-prey model with constant rate of harvesting in both populations.

1.4 Scope of Research

The main scope of this research is to analyze the predator-prey model by with the constant rate of harvesting. In this research, we shall only focus on two populations which are prey and predator. We will formulate the model by adding the constant rate of harvesting prey, predator or both population and also find how this factor affects to the stability of equilibrium points in predator-prey model.

1.5 Significant of Research

The findings of this research is useful for the mathematicians who are interested in the ecology fields because this research will give us more understanding in predator-prey model with or without harvesting and the effects on the stability of the population. The result obtained can be a guide by applying to another predation model in population field.

REFERENCES

- Agarwal, M. and Pathak, R. (2012). Harvesting and Hopf Bifurcation in a preypredator model with Holling Type IV Functional Response. International Journal of Mathematics and Soft Computing. Vol.2, No.1 (2012), 83 – 92.
- Barnes, B. and Fulford, G. R. (2009). Mathematical Modelling with Case Studies: A Differential Approach Using Maple nad Matlab. 2nd edition. New York: CRC Press, Taylor & Francis Group, A Chapman & Hall Book.
- Boyce, W. E. and DiPrima, R. C. (2010). Elementary Differential Equations and Boundary Value Problems. 9th edition. New York: John Wiley & Sons (Asia) Pte Ltd.
- Brauer ,F. (1977). Stability of some population models with delay. Math. Biosci., 33, 345-358.
- Brauer, F. and Soudack, A. C. (1979). Stability Regions and transition phenomena for harvested predator-prey systems. Journal of Mathematical Biology 7, 319–337.
- Burghes, D., Galbraith, P., Price, N. and Sherlock, A. (1996). Mathematical Modeling. UK: Prentice Hall.
- Dai, G and Tang, M. (1998). Coexistence region and global dynamics of a harvested predator-prey system. Siam Journal of Applied Mathematics (1998), 58, 193-210.
- Farlow, J., Hall, J. E., Mc Dill, J. E., and West, B. H. (2007). Differential Equations with Dynamical System. New Jersey: Princeton University Press.
- Giardano, F. R., Weir, M. D. and Fox, W. P. (2003). A First Course in Mathematical Modeling. 3rd edition. US: Thomson BRooks/Cole.

- Hennig, C.(2009). Mathematical Models and Reality- a Constructivist Perspective.Research Report No. 304, Department of Statistical Science, UniversityCollege London.
- Jessie, S. (2004). Population Dynamics Beyond Classic Lotka-Volterra Models. Thesis: Degree of Bachelor of Arts in Liberal Arts and Sciences with a Concentration in Mathematics. Harriet L. Wilkes Honors College of Florida Atlantic University
- Jones, D. S., Plank, M, J. and Sleeman, B, D. (2010). Differential Equations and Mathematical Biology. Second Edition. UK: CRC Press Taylor & Francis Group.
- Kar, T. K. and Pahari, U. K. (2006). Non-selective harvesting in prey-predator models with delay. Communications in Nonlinear Science and Numerical Simulation 11 (2006) 499–509.
- Kar, T. K. and Chakraborty, K. (2010). *Effort Dynamics in a Prey-Predator Model with Harvesting*. International Journal Of Information And Systems Sciences Volume 6, Number 3, Pages 318-332.
- Keshet, L. E. (1988). *Mathematical Models in Biology*. New York: Random House, Inc.
- Mahony, J. J. and Fowkes, N. D. (1994). *An Introduction to Mathematical Modeling*. New York: John Wiley & Sons, Inc.
- Martin, A. and Ruan, S. (2001). *Predator-prey models with delay and prey harvesting*. J. Mathematical Biology, 43 (2001), 247-267.
- May, R. M. (1972). *Limit cycles in predator–prey communities*. Science 177, 900–902.
- Murray, J. D. (2002). Mathematical Biology 1. An Introduction. Third edition. US: Springer Science+Business Media, Inc.
- Narayan, K. L. and Ramacharyulu, N.C.P. (2008). A prey-predator model with an alternative food for the predator, harvesting of both the species and with a

gestation period for interaction. Int. J. Opne Problems Compt. Math., 1, No. 1.

- Ouncharoen R., Pinjai, S., Dumrongpokaphan, Th. and Lenbury, Y. (2010). Global Stability Analysis of Predator-Prey Model with Harvesting and Delay. Thai Journal of Mathematics Volume 8 (2010) Number 3: 589–605.
- Salleh, K.. (2013). Dynamics of Modified Leslie-Gower Predator-Prey Model with Predator Harvesting. International Journal of Basic & Applied Sciences IJBAS-IJENS Vol:13 No:05.
- Saputra, K. V. I. (2008). Semi-global analysis of Lotka-Volterra systems with constant terms. Thesis: Degree of Doctor of Philosophy. School of Engineering and Mathematical Sciences Faculty of Science, Technology and Engineering La Trobe University.
- Syamsuddin and Malik (2008). Stability Analysis of Predator-Prey Population Model with Time Delay and Constant Rate of Harvesting. Punjab University Journal of Mathematics (ISSN 1016-2526). Vol. 40 (2008) pp. 37-48.
- Strogatz, S.H. (1994). Nonlinear dynamics and chaos. Addison-Wesley, Reading, MA.
- Xia ,J., Liu, Z., Yuan, R. and Ruan, S. (2009). The effects of harvesting and time delay on predator-prey systems with Holling type II functional response. SIAM J. App. Math, Vol. 70, No. 4, pp. 1178–1200.

"Harvesting a Prey Population",

http://amrita.vlab.co.in/?sub=3&brch=67&sim=774&cnt=1