EFFICIENT TIME SIMULATION REGRESSION PROCEDURE FOR PREDICTING OFFSHORE STRUCTURAL RESPONSES

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DEDICATION

To my beloved family especially walid, ummi and siblings, including my friends for their wits, intelligence and guidance in life

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ABSTRACT

The assessment of accurate hydrodynamic loads on structures due to the extreme environmental loadings is the primary concern in the design of offshore platforms. The wind-induced waves are normally the most potential loadings with nonlinear behaviour, contributing to a complicated solution. The conventional Monte Carlo Time Simulation (MCTS) method is required for an accurate analysis of wave loads without offering any approximation error. The MCTS technique is considered a realistic and versatile approach because it can cover all sorts of nonlinearities to evaluate the offshore structural responses. However, this conventional technique is very computationally demanding, as reliable results require a large number of simulations due to unavoidable excessive sampling variability. Past studies showed that an Efficient Time Simulation (ETS) method offered a more effective result without scarifying accuracy. Nevertheless, the ETS method is limited to specific sea state conditions, in which the level of accuracy decreased with the presence of the wave current. Therefore, this study aims to improve the ETS method by taking advantage of their excellent correlation between extreme surface elevation and corresponding structural responses. Hence, an extended version of the ETS method is introduced. A novel model is developed based on regression algorithms and known as an ETS-Regression (ETS-Reg) procedure contributing a simplified method for the direct calculation of the wave-induced loads. Two ETS-Reg models were developed based on different input variables with similar output variables. In model development, the first relationship-based model was developed based on the surface elevation (input) and nonlinear responses (output), defined as the ETS-Reg_{SE} model. The second model was an improved version of the ETS-Reg_{SE} model, the linearised responses (input) with their corresponding nonlinear responses, known as the ETS-Reg_{LR} model. In short-term analysis, these models will be tested by three sea state conditions and three different wave-induced currents. The probability distribution of the 100-year extreme response values from the ETS-Reg models have been compared with corresponding distributions of 100-year response values from the MCTS procedure to examine the accuracy and the efficiency of the developed technique. As a result, for the short-term analysis, the ETS-Reg_{LR} model delivered an excellent accuracy in the range of 93% to 99% in predicting 100-year responses compared with the benchmark value using the MCTS method for all cases of wave conditions. Meanwhile, the ETS-Reg_{SE} model varies between 20% and 96%. Remarkably, the efficiency level achieved by the ETS-Reg_{LR} model was in the range of 43 to 51 times more efficient than the MCTS method in terms of variance ratio of sampling variability, whereas, the ETS-Reg_{SE} model was in the range of 22 to 42 times. The same inference appeared for long-term analysis since both the ETS-Reg models' accuracies were closely matched to the previous shortterm analysis. The ETS-Reg_{LR} model's accuracy was 95% to 99%, whereas, 89% to 96% by the ETS-Reg_{SE} model. Overall, the ETS-Reg models can lead to better performance without extensive simulations, which the models require less computationally demanding processes and time. Thus, these innovative models are proposed as an alternative technique for frequency domain in the probabilistic assessment in the oil and gas industry.

ABSTRAK

Penilaian beban hidrodinamik yang tepat pada struktur disebabkan oleh beban persekitaran yang melampau adalah perhatian utama dalam reka bentuk platform luar pesisir. Gelombang yang disebabkan oleh angin merupakan beban yang biasanya paling berpotensi dengan tingkah laku ketaklelurusan, menyumbang kepada penyelesaian yang rumit. Kaedah simulasi masa Monte Carlo (MCTS) konvensional diperlukan untuk analisis tepat mengenai beban gelombang tanpa menawarkan ralat penghampiran. Teknik MCTS dianggap sebagai pendekatan yang realistik dan serba boleh kerana ia dapat merangkumi pelbagai jenis ketaklelurusan untuk menilai tindak balas struktur luar pesisir. Walau bagaimanapun, teknik konvensional ini sangat memerlukan pengiraan kerana keputusan yang tepat memerlukan sebilangan jumlah simulasi yang sangat besar kerana kepelbagaian pensampelan berlebihan yang tidak dapat dielakkan. Kajian lepas menunjukkan bahawa kaedah Simulasi Masa Cekap (ETS) menawarkan keputusan yang lebih berkesan tanpa menjelaskan ketepatan. Namun begitu, kaedah ETS terhad pada keadaan laut tertentu di mana aras ketepatannya menurun dengan kehadiran arus gelombang. Oleh itu, kajian ini bertujuan untuk meningkatkan kaedah ETS dengan mengambil kira korelasi yang sangat baik antara ketinggian permukaan air dan tindak balas struktur yang sepadan. Oleh itu, versi lanjutan kaedah ETS diperkenalkan. Model baru dibentuk berdasarkan algoritma regresi dan dikenali sebagai prosedur ETS-Regresi (ETS-Reg) yang menyumbang kaedah yang dipermudah untuk pengiraan terus beban yang disebabkan oleh gelombang. Dua model ETS-Reg dibentuk berdasarkan pemboleh ubah input yang berbeza dengan pemboleh ubah output yang sama. Dalam pembangunan model, perhubungan pertama berasaskan model dibentuk berdasarkan ketinggian permukaan air (input) dan tindak balas tak-lelurus (output), yang dinamakan sebagai model ETS-Reg_{SE}. Model kedua adalah versi yang lebih baik dari model ETS-Reg_{SE}, tindak balas terlinear (input) dengan tindak balas tak-linear (output) yang sesuai, yang dikenali model ETS-Reg_{LR}. Dalam analisis jangka pendek, model-model ini akan diuji dengan tiga keadaan laut dan tiga arus gelombang yang berbeza. Taburan kebarangkalian nilai tindak balas ekstrim 100 tahun dari model ETS-Reg dibandingkan dengan taburan nilai tindak balas 100 tahun yang sepadan dari prosedur MCTS untuk memeriksa ketepatan dan kecekapan teknik yang dibentuk. Hasilnya, untuk analisis jangka pendek, model ETS-Reg_{LR} memberikan ketepatan yang sangat baik dalam lingkungan 93% hingga 99% dalam meramalkan tindak balas 100 tahun berbanding dengan nilai penanda aras menggunakan kaedah MCTS untuk semua kes keadaan gelombang. Sementara itu, model ETS-Reg_{SE} berbeza antara 20% dan 96%. Tahap kecekapan yang dicapai oleh model ETS-Reg_{LR} berada dalam lingkungan 43 hingga 51 kali lebih efisien daripada kaedah MCTS dari segi nisbah varians pemboleh ubah sampel, sedangkan, model ETS-RegSE berada dalam lingkungan 22 hingga 42 kali. Kesimpulan yang sama muncul untuk analisis jangka panjang kerana ketepatan kedua-dua model ETS-Reg sangat berkaitan dengan analisis jangka pendek sebelumnya. Ketepatan model ETS-Reg_{LR} adalah 95% hingga 99%, manakala, 89% hingga 96% oleh model ETS-Reg_{SE}. Secara keseluruhannya, model ETS-Reg memberi prestasi yang lebih baik tanpa simulasi tambahan, yang mana model memerlukan pengurangan proses dan masa pengiraan. Oleh itu, model inovatif ini dicadangkan sebagai teknik alternatif untuk frekuensi domain dalam penilaian probabilistik dalam industri minyak dan gas.

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LIST OF ABBREVIATIONS

API	-	American Petroleum Institute
API RP	-	American Petroleum Institute Recommended Practice
BS	-	Base Shear
BV	-	Bureau Veritas
C++	-	C with Classess (Programming Language)
CDF		Cumulative Distribution Function
CPU	-	Central Processing Unit
DFT	-	Discrete Fourier Transform
DNV	-	Det Norske Veritas
DSA	-	Deterministic Spectrum Amplitude
ETS	-	Efficient Time Simulation
ETS-R	-	Efficient Time Simulation Relationship
ETS-Reg	-	Efficient Time Simulation Regression
ETS-Reg _{SE}	-	Efficient Time Simulation Regression-based Surface
		Elevation
ETS-Reg _{LR}	-	Efficient Time Simulation Regression-based Linearised
		Responses
ETS-RTS	-	Efficient Time Simulation-Relationship Time Simulation
ETU	-	Efficient Threshold Up-crossing
EVA	-	Extreme Value Analysis
FFT	-	Fast Fourier Transform
FMNS	-	Finite-Memory Nonlinear System
IDFT	-	Inverse Discrete Fourier Transform
IFFT	-	Inverse Fast Fourier Transform
ITTC	-	International Towing Tank Conference
ISSC	-	International Ship Security Certificate
JONSWAP	-	Joint North Sea Wave Project Spectrum
LRWT	-	Linear Random Wave Theory
MATLAB	-	Matrix Laboratory (Programming Language)
MCTS	-	Monte Carlo Time Simulation

MFMNS	-	Modified Finite-Memory Nonlinear System
MN	-	Mega Newton
MNm	-	Mega Newton meter
MOM	-	Method of Moment
NARX	-	Non-linear Autoregressive with Exogenous Input
NLFD	-	Nonlinear frequency-domain
NSA	-	Non-deterministic Spectrum Amplitude
NWT	-	New Wave theory
OTM	-	Overturning Moment
P-M	-	Pierson Moskowitz
PCT	-	Principal Component Technique
PDF	-	Probability Density Function
POF	-	Probability of Failure
QRA	-	Quantitative Risk Analysis
RTS	-	Relationship Time Simulation
SDOF	-	Single Degree of Freedom
SE	-	Surface Elevation
SFSM	-	Second - Fourth Statistical Moment
SRA	-	Strcutural Reliability Analysis
SST	-	Simple Sampling Technique
SWL	-	Still Water Level
UK	-	United Kingdom

LIST OF SYMBOLS

a,b,c,d	-	regression model coefficients
Α	-	wave amplitude
A_u and B_u	-	complex (Fourier series) coefficients of u
A	-	Phillip's constant of 0.0081
â	-	factors for the equivalent linear form (drag-induced)
\overline{lpha}	-	mode of the extreme value distribution (Gumbel parameters)
β	-	factors for the equivalent linear form (inertia-induced)
$ar{eta}$	-	dispersion coefficients (Gumbel parameters)
cl	-	celerity
С	-	damping
C_d	-	drag coefficient
C_m	-	inertia coefficient
Δf	-	frequency interval
Δl	-	length interval of the structure element
d	-	water depth
D	-	diameter of cylindrical structures
Ε	-	residual error
З	-	random wave phase angle
е	-	error
$E[e^2]$	-	residual error (drag-induced)
$E[e'^2]$	-	residual error (inertia-induced)
EV_{R100}	-	100-year extreme responses
exp	-	exponent
$ ilde\eta$	-	sum of sinusoids of sample sea surfaces
η_{ev}	-	surface elevation extreme value
f	-	wave frequency
f_p	-	peak frequency
f^l	-	function of linear regression model
f^p	-	function of polynomial regression model
f ^c	-	function of cubic regression model

F	-	Morison's force (wave-induced loads)
8	-	gravitational acceleration of 9.81 m/s ²
gg_i and hh_i	-	standardised Gaussian random variables
G_f	-	function of failure
<i>g</i> _{cdf}	-	Gumbel cumulative distribution function
G_{pdf}	-	Gumbel probability density function
g_{x_n}	-	extreme values of cumulative distribution function
$\Gamma_{u,i}$	-	TF of particle velocity related drag-induced responses
$\Gamma_{\dot{u},i}$	-	TF of particle acceleration related inertia-induced responses
γ	-	Euler–Mascheroni constant (≈0.5772)
γ_p	-	peak enhancement factor
h or H	-	wave height
Hs	-	significant wave height
Κ	-	stiffness
k	-	wave number
М	-	mass
Mz	-	number of wave cycle during period T (dimensionless)
μ_η	-	mean of the sea surface elevation
μ_H	-	mean of the sea wave height
Ν	-	total number of simulation records (simulated responses)
NL	-	numbers of nodal loads
NW	-	number of wavelet components
Na	-	annual average number of sample data
L	-	load
λ	-	wavelength
log	-	logarithm
ln	-	natural logarithm
lr _{ev}	-	linearised responses extreme value
ω	-	angular wave frequency
П	-	mathematical constant of 3.142
Р	-	probability distribution
P_{η}	-	probability density function of surface elevation

p_{H_s,T_z}	-	joint occurrence probability density function of H_s and T_z
P_H	-	probability density function of wave height
p_H	-	cumulative distribution function of wave height
P _i	-	probability of occurrence of Group <i>i</i>
p_k	-	equivalent point loads acting on node k of wave forces
p_{X_n}	-	cumulative probability of return periods
$P_{\eta_{ev}}$	-	probability surface elevation extreme value
P _{rev}	-	probability response extreme value
$P_{r_{max} h,t}$	-	short-term probability distribution by <i>Hsi</i> and <i>Tzj</i>
$P_{LT,r_{max}}(q_n)$	-	long-term probability distribution (entire sea states)
q	-	nodal point displacements
q_n	-	<i>n</i> -th smallest simulated extreme value
r	-	correlation coefficients / correlation-r values
r^2	-	determination coefficients / r-squared values
R	-	resistance
$\tilde{R} \text{ or } \tilde{R}_{QS}$	-	quasi-static offshore structural nonlinear response
$\hat{R} \ or \ \hat{R}_{DYN}$	-	dynamic offshore structural nonlinear response
r_{drag}	-	drag forces
r _{inertia}	-	inertia forces
r _{L,drag}	-	linearised drag forces
r _{L,inertia}	-	linearised inertia forces
r _{ev}	-	predicted extreme response values
r_{ev}^l	-	predicted extreme responses based on first-order linear
r_{ev}^p	-	predicted extreme responses based on second-order linear
r_{ev}^c	-	predicted extreme responses based on third-order linear
r _{max}	-	simulated extreme response value
ρ	-	seawater density
S_{η}	-	wave energy spectrum
σ	-	standard deviation
σ^2	-	variance
σ_a	-	standard deviation to the left
σ_b	-	standard deviation to the right

σ_η	-	standard deviation of the sea surface elevation
σ_η^2	-	variance of the sea surface elevation
σ_{H}	-	standard deviation of the sea wave height
σ_{H}^{2}	-	variance of the sea wave height
σ_{x_n}	-	standard deviation of random variables
S_k	-	flexibility coefficients
SS _{res}	-	residual sum of squares
SS _{tot}	-	total sum of squares
t	-	time
Т	-	wave period
TF	-	transfer function
$TF_{\tilde{R}_L}$	-	transfer function of linearised responses
T _r	-	specific return periods
T_z	-	mean zero up-crossing period
и	-	water particle velocity
<i>ù</i>	-	water particle acceleration
U	-	current velocity
U'	-	DFT of horizontal water particle velocity
$U^{\prime\prime}$	-	DFT of horizontal water particle acceleration
W	-	the total number of sea states
W_{ij}	-	the number of occurrences of the sea states represented by
		Hsi and Tzj in the scatter diagram
x	-	horizontal direction displacement
x_n	-	random variable of extreme values
<i>X</i> ₀	-	mean surface elevation
X_n and X_{-n}	-	complex Fourier coefficients of $\tilde{\eta}$
X_n^*	-	complex conjugate of X_n
\overline{x}	-	stationary random processes (time domain)
\overline{X}	-	stationary random processes (frequency domain)
\bar{x}_r	-	amplitude of the <i>r</i> -th complex component
\overline{X}_k	-	discrete Fourier Transform of k^{th} complex component
у	-	probability y-axis
Z.	-	vertical direction for the seabed

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CHAPTER 1

INTRODUCTION

1.1 Research Background

Crude oil is currently the most abundant energy sources, accounting for an estimated 39 percent of fossil energy, followed by coal and natural gas at 33 and 28 percent, respectively (Ritchie and Roser, 2019). With the arrival of passenger vehicles, aviation, road freight, chemical feedstock, industry, shipping and the extensive use of electricity (buildings/power), oil has become the dominant fuel during the twentieth century (Garside, 2018). Due to high demand, oil and other petroleum commodities have been rapidly rising over the years (Cooper *et al.*, 2018).

High demand has motivated petroleum companies to explore the ocean floor to extract oil and other resources, and to deliver the oil onto land for marketing purpose. Many oil and gas partnerships have made great efforts to take this opportunity to invest in the marine industry (Bennaceur, 2019). To meet this goal, many companies require essential equipment and access to thousands of facilities for the exploration and production of oil and natural gas with a variety of categories and sizes around the world (Laik, 2018).

Offshore oil and gas production has evolved in line with technological progress to remain relevant in different circumstances (Schmidt *et al.*, 2017). The development of oil platforms offers varying capabilities in security, technical, economic and national needs that depend on the depth of the ocean as well (Nouban *et al.*, 2016). The success of a platform and to the success of the entire operation must take into account the most basic offshore drilling in the seabed. Most drilling operations either can be accomplished by a fixed or floating offshore platform (Swamidas and Reddy, 2016).

The main focus of this thesis is on fixed platforms because this is the majority of platforms installed around the world (Goswami *et al.*, 2019). Recently, this kind of fixed offshore structure has played a primary role in oil and gas activity for the past decade (Reddy and Swamidas, 2016). The fixed-based structures account for around 95% of the jacket platforms currently found in different bays, gulf and oceans of the world, a percentage that is growing year by year (Limited, 2017). As reported by O'Connor *et al.* (2007); OECD (2016), more than 9000 offshore platform installations are in service around the world. These installations are employed for drilling, providing water or gas for inoculation into the storage tank for processing crude oil, refining the produced water for dumping into the sea and also serve as staff housing (Bleasdale, 2018).



Figure 1.1 Main sections of the jacket offshore platform Source: (Bücker *et al.*, 2014)

Shallow water fixed offshore structure is very low-cost and more practicable to provide operators and tools on structural platforms (Yu *et al.*, 2015). Under this type, the study would concentrate on piled structures, mainly known as the jacket offshore platforms. "Jackets" refers to fixed steel offshore structures, which are fundamental in support the deck and topsides to ensure the stability of the platforms

and piling process (El-Reedy, 2019). They are the most commonly located structure for shallow and intermediate water depths reaching up to 400 metres. Jackets had been designed to assist topside weights about 50000 tonnes, although it is possible to formulate jackets for even larger topside weights as illustrated in Figure 1.1.

Offshore platforms positioned in the ocean environments are more vulnerable to hazardous risks compared to onshore oil rig platforms. Some common dangers that can affect the structural integrity are extreme waves, which can exceed 30m or more such as an incident in the northern North Sea, as reported by (Bruserud and Haver, 2019). In this study, the environmental load (e.g. wind-induced wave) is a main consideration in the design of offshore structures. For acceptable structural integrity, offshore structures should be designed with the capability of withstanding extreme wave loads (Henry *et al.*, 2017).

According to Board (2011), the wave loads from an environmental perspective contribute as a dominant load was around 70% affecting the durability of jacket structures. Large waves represent a danger to offshore platforms and marine installations if the design of marine structures is not followed by the right development criteria (Szalewski *et al.*, 2017). Since the harsh environmental loads represent a significant role in leading the design of offshore structures, the precise prediction of environmental wave loads acting on the structure is indispensable.

A study revealed that the risks associated with extreme waves, which have a tremendous effect on offshore structures, have increased in recent years (ATEX, 2016; Slunyaev, 2017). As stated by Demirbilek (2010), a number of platform accidents related to extreme waves had been reported, and this is the lessons learned how the impact of intense waves hits into the platform structures if the design of offshore platform does not follow the predefined guidelines. As demonstrated in Figure 1.2, a massive wave had hit the marine structures such as the Hurricane Lilli in the Gulf of Mexico.



Figure 1.2 EI-322 'A' platform structures damaged by Hurricane Lilli Source: (DeFranco *et al.*, 2004)

Pursuant to (Cruz and Krausmann, 2008), Hurricane Katrina is another example that caused damage to more than 30 oil platforms and rigs, the closure of nine onshore refineries, and destruction of transport facilities and oil production in the Gulf of Mexico region. The damage could be the occurrence of a particular wave phenomenon, such as an abnormal wave crest. These strange wave phenomena are often referred to as rogue, freak, giant, episodic and extreme waves (Kettle, 2018). The abnormal waves are unexpected and unpredictable phenomena that surface waves immediately reach without warning and can influence (strike) large force.

Incidents of "unprecedented" wave phenomena have occurred in different locations, for example, Model of Ocean Ranger, Draupner oil rig in the North Sea, Jacket platform in the Gulf of Mexico and other offshore platforms related to wave cases (Cavaleri *et al.*, 2017). Such incidents have been highlighted because extreme waves can lead to dominant failures. Figure 1.3 displays an example of the failure mode with an intact structure exposed to a massive wave. An accident on offshore jacket structures reveals that leaning installations with huge deformations are the most expected results as well as a toppled topside and total collapses (Kajuputra *et al.*, 2016).



Figure 1.3 Excessive environmental load failure mode Source: (Ersdal, 2005)

Based on previous accidents, a risk assessment has been carried out on waverelated incidents in order to classify the possible hazards. Hazards can pose a danger to the structural integrity of offshore structures due to insufficient strength of structures (Thapa, 2016). There are two possibilities of risks associated with the inadequate strength, which are fatigue failure (cyclic loading) and first excursion failure (Taylor *et al.*, 2006). Fatigue failure may occur when a response spends too much of its time out of a limit. For instance, degradation of the offshore structure because of fatigue coupled with corrosion might reduce the capability of structures to confront excessive waves and current loadings.

Another mode is the first excursion failure, which arise once the structural responses exceed a designated safety domain for the first time in a certain year (e.g. 50-year or 100-year) (Najafian, 2005; Mohd Zaki *et al.*, 2016b; Mukhlas *et al.*, 2016a; Santo *et al.*, 2016). Hence, structural integrity requires to be sustained by environmental loads during the lifetime of the installation (Nayak and Pandian, 2018). Knowledge of how risky ocean conditions interface with fixed structures is required to assure the safety of employees and avoid property loss (Procedures, 2017). The

safety aspect of the offshore structures should be addressed carefully and consciously (Nizamani, 2015).

The main concern in this view is that obligations about safety should not be negotiated. For achieving the safety level, it is essential to emphasise in the design phase and construction of an offshore platform at the initial scope of work (Bea, 1992; Coccon *et al.*, 2017). The design stage of offshore developments is the first step before continuing the next phase of fabrication, installation and operation activities (El-Reedy, 2019). That is why the calculation of the design wave load in the design stage is a crucial task for the construction of offshore structures. The need for design analysis is required in order to guarantee safety in design and operation from extreme wave loads (Sandhya, 2018).

To assure structure design is adequately safe, the initial implementation is to follow the rules and offshore standards. The standards were established by a competent organisation such as the American Petroleum Institute (API), Bureau Veritas (BV), Det Norske Veritas (DNV), International Standards Organization (ISO) etc. (DNV, 1974; BV, 1975; API, 1977; ISO, 2007). Thus, designers should obey all guidelines related to the design and construction of fixed offshore structures. For example, an API RP 2A standard is a well-recognised rule in the offshore fields (Mangiavacchi *et al.*, 2005). This standard is practised for specific perspectives of the offshore structure design around the world.

Referring to API RP 2A manual, the guideline declares that the extreme loads are generated from a combination of wind, wave and current, in which the wave is the most influential load (Goswami *et al.*, 2019). The wave-induced loads acting on offshore platforms are necessary for performing the structural analysis in order to obtain the offshore responses. Thus, offshore structures were designed to meet a standard that would be employed in the context of the level of risk and structural reliability (Onoufriou and Forbes, 2001). Historically, the reliability-based design for offshore structures is practised on the basis of the calculation of the load-induced motion responses (Chandrasekaran, 2017).
Prior to evaluating the data magnitude from these wave load-responses, a statistical and probabilistic description is required (Vanem *et al.*, 2019). Numerical analysis and computational procedures are applied to simulate such wave loads and its corresponding structural responses (Şen, 2018). With the numerical simulation, a Fourier Transform analysis based on the wave spectrum is used (Yu, 2018). In order to determine the design of extreme responses of the structures, the statistical approach via extreme value analysis (EVA) method is used (Coles, 2001). EVA is a conventional approach used to predict the structural response values that have to fit the data into the probability distribution.

EVA has been presented by a number of researchers (Thas *et al.*, 1997; Cooley, 2013; Chaves and Melchers, 2014; Horn and Winterstein, 2018). In brief, the result from the EVA approach is used as design conditions for the offshore structural reliability analysis. Designing the offshore structure is safe when its capability to resist the wave loads exceeds the maximum loads that may be applied once in a given time period (100-year) (Mat Soom *et al.*, 2019). Thus, the wave-induced loads imposed on the marine structures is commonly determined by the 100-year return period (Azman *et al.*, 2017; Mat Soom *et al.*, 2018). Also, calculating wave loading on the structures could be reached using either the deterministic or probabilistic method (Bjerager, 1990; Najafian *et al.*, 1995; Golafshani *et al.*, 2011).

According to Klein *et al.* (2020), the deterministic method is more suitable with the regular waves to forecast structural responses on wave loading. In real life, the ocean surface is always changing in time, which are also considerable uncertainties of the wind-generated random waves (Qiu *et al.*, 2014). Due to the uncertainty perspective (caused by wind, wave and current conditions), the main barrier in applying deterministic approach is about the random nature of the ocean that it does not consider while calculating the nonlinear properties in the design practice (Gao *et al.*, 2016). Due to the nonlinearity excitation, the deterministic-based analytical procedures for assessing irregular waves and its corresponding extreme responses are less accurate (Osborne, 2001; Clauss and Schmittner, 2005; Helder and Bunnik, 2016).

Therefore, the most promising method to estimate random wave-induced forces in the ocean conditions is a probabilistic method (Oumeraci *et al.*, 2001). The probabilistic approach is more consistent because uncertainties are admitted in the calculations (Bruserud and Haver, 2017), which can count random wave-induced loads and responses in the ocean environment. Under the probabilistic method, as stated in (Najafian *et al.*, 1995; Soares, 2012), there are three main approaches; probability, frequency and time domains. Each domain has its own process of evaluating structural responses.

1.2 Problem Statement

In targeting the early design phase, the structural analysis is utilised to determine the extreme structural responses of the structures. The probabilistic approach based on the time-domain simulation has been adopted, which is considered the best method to establish the short-term and long-term probability distribution of extreme offshore structural responses (Cassidy *et al.*, 2003; Abu Husain *et al.*, 2016a; Mohd Zaki *et al.*, 2016d; Mukhlas *et al.*, 2016a). A Monte Carlo Time Simulation (MCTS) method is practised to produce accurate values from the stochastic events of random waves (Norouzi, 2012). The stochastic analysis is feasible to be carried out by a robust MCTS technique, although numerous simulated data must be assessed in order to achieve the desired level of accuracy (Catelani *et al.*, 2014; Chai *et al.*, 2016).

Moreover, time-domain is capable of counting all sorts of nonlinearities without bringing in any approximations (Abu Husain *et al.*, 2016a). Due to its ability, this MCTS method had been applied for evaluation of the extreme responses affected by random excitations (Naess and Gaidai, 2008). It is the most precise, realistic and multifaceted approach for forecasting the statistical features of extreme offshore structural responses opened to irregular wave loads (Metcalfe *et al.*, 2003; Najafian, 2007c; Saha and Naess, 2010; Abu Husain *et al.*, 2016a; Mohd Zaki *et al.*, 2018a; Mukhlas *et al.*, 2018b). At the same time, MCTS method attempted to make less computational cost because it is simple to be applied while maintaining the benefits of conventional tools and computational simulations.

Due to the complex procedure of MCTS (Mukhlas *et al.*, 2016a), the length of the simulations depends on the number of response records varied with the computational time (completed simulations). Likewise, the numerous stages based on each process in wave hydromechanics modelling became more complicated. Also, the impact of nonlinearities will burden the process of calculations in analysing the ocean wave and its corresponding hydrodynamic loadings (Abu Husain *et al.*, 2016a; Mukhlas *et al.*, 2018a). Hence, the MCTS procedure involves a long run of simulations which requires more effort to reduce its sampling variability in order to reach satisfactory results in the calculation.

As shown in Figure 1.4, the sampling variability is very computationally demanding, and this is the main shortcoming of MCTS procedure because the precision required a large number of simulation records (Mohd Zaki *et al.*, 2018a; Abu Husain *et al.*, 2019; Mukhlas *et al.*, 2019). The method was repeated 100 times to display the impact of sampling variability. As observed, it proves that the MCTS method needs a large number of simulations (10,000 records) to reach better accuracy equal to 4 percentage error. It indicates that the sampling variability achieves 95 percent confidence level, which is an acceptable result complied below than 5 percent of the sampling variation (API, 2013). This technique's implementation is very complicated when considering 10,000 simulated records for each stage of the calculation process of schematic wave hydromechanics (Mukhlas, 2020). That is the reason the conventional MCTS method is very time-consuming.



Figure 1.4 Sampling variability of Monte carlo time simulation method

Hence, many studies have been conducted to understand the MCTS method problems and to make an improvement in terms of efficiency, as shown in Figure 1.5. An improved MCTS technique has been extended by many researchers (Najafian and Zaki, 2008; Mohd Zaki *et al.*, 2016b; Mukhlas *et al.*, 2018a). On the other hand, in order to capture this inefficiency, one of the favourable method was studied by (Abu Husain and Najafian, 2011), who presented an Efficient Time Simulation (ETS) method. Currently, the ETS method offers excellent efficiency and has proven in the full-wave investigation to be a very effective method in the development stages for quasi-static responses, dynamic responses and varying sea-state intensity ranging from low to high (Abu Husain *et al.*, 2013b; Johari *et al.*, 2016).



Figure 1.5 Design development of the proposed method and their limitations from previous methods

However, the limitation of the ETS method is that it does not perform well for low sea state (i.e., Hs = 5 m), especially the existence of the current effect, which will reduce the level of accuracy. As stated by Abu Husain *et al.* (2013b), this can be seen as the worst relationship between surface elevation and responses is at low Hs value. Some researchers put more effort to tackle this issue by introducing several methods such as Efficient Threshold Up-crossing, ETS-Relationship and Optimisation of ETS method. In 2013, Lambert *et al.* (2013) introduced the proficient calculation of probability distribution of the offshore structural responses. The fundamental ETU method was developed based on the information of threshold up-crossings connected with the speed of the ETS method. However, the comprehensive study was made on the aircraft gust loadings.

Mallahzadeh *et al.* (2014a); Mallahzadeh *et al.* (2014b) extended the ETS method with related initiatives of the relationship of input and output considerations. This improved ETS technique was named the ETS-Relationship (ETS-R) method, also known as ETS-Relationship Time Simulation (ETS-RTS) model. A conceptual study was carried out to develop an empirical model by introducing the relationships' extreme values between and surface elevations and responses. This initial investigation was promising, but to date has not dealt with a comprehensive study. Mallahzadeh *et al.* (2013) reviews were limited to a single-legged structure, single high sea state (*Hs* = 15 m) and did not consider certain other wave possibility conditions.

In order to improve this ETS-RTS procedure, Johari (2016) optimises the number of simulation records which will enhance the selection number of groups. Although it makes an enhancement in accuracy and efficiency, it still has the same problems in the low *Hs* value. To this end, referring to Mallahzadeh *et al.* (2013) as a conceptual study, a fully comprehensive examination will be extended in determining the 100-year extreme responses. Applying an advantage of ETS method, the proposed method is developed from the relationship (scattered distribution data) between two variables of extreme surface elevation (input) and its extreme responses (output). Thus, a systematic regression analysis is performed in order to obtain the appropriate model development based on the excellent relationship, which is also known as the ETS-Regression (ETS-Reg) model.

The model would be tested for the real structures. In this study, the examination will also be considered according to different sea state conditions, a four-legged structure platform, quasi-static jacket platforms, wave structures of nonlinearities kinematics loading, intermittent (cyclic) loading and the effect of current wave propagation. The improvement of the relationship between extreme values would also be conducted. As a result, a new method is likely to solve the complicated issue, particularly for the low *Hs* alongside the current impact.

Also, the proposed method is expected to be more efficient than MCTS and ETS methods because of simplifying another complicated calculation procedure without sacrificing accuracy. As a regression model preferred, there is no need to run extensive simulations or to pass through several processes of calculations. The models would be a great technique to calculate the responses while at the same time, raising its efficiency.

1.3 Aims and Research Objectives

The study aim is to develop an efficient procedure for evaluating the 100-year fixed offshore structure responses using Efficient Time Simulation (ETS) method by taking advantage of their excellent correlation between extreme values of surface elevation and linearised responses (input) with their equivalent extreme values of nonlinear response (output).

The study objectives can be further detailed as follows:

- 1. To investigate the hydrodynamical relationships between extreme values of surface elevation and linearised responses with their corresponding nonlinear responses.
- 2. To develop a regression model for the prediction of extreme responses by the utilisation of relationships.
- 3. To validate the accuracy and efficiency of the regression models for both shortterm and long-term probability distribution in predicting extreme offshore responses.

1.4 Scope of the Study

This study will focus on the four-legged fixed offshore platform without internal bracings for a water depth (*d*) up to 110 m. The application of numerical simulation analysis based on the mathematical models is preferred to simulate ocean wave hydrodynamic into the real world with the aid of computer ability. The linear random wave theory (LRWT) is used to simulate the water kinematics in hydrodynamic wave loadings. The forecast for structural responses has been extensively used based on probabilistic modelling due to its ability to calculate the random nature of loading. The probabilistic-based time domain was selected to evaluate 100-year extreme responses in short-term and long-term probability distribution. The derivation of the probability distribution of extreme structural responses are based on the API RP 2A standard (API, 2014).

This study only considered the system structure in quasi-static responses. Two primary responses would be counted, namely; base shear (BS) and overturning moment (OTM) of structural responses, which relies on three hydrodynamic components; drag-induced, inertia-induced and total responses. Ensuring the platform complies with standards, the structure was tested under various wave conditions, including without and with the presence of currents; U = 0 m/s, +0.9 m/s and -0.9 m/s, respectively. For a short-term analysis, it considers a single sea state characteristic in the calculation. The three cases of sea states are taken into account accordant with low, mid and high significant wave heights; Hs = 5 m, 10 m and 15 m associated with its zero up-crossing wave period; Tz = 7.94 sec, 11.23 sec and 13.75 sec, respectively. All terms related to low, mid and high Hs are also known as the low, mid and high sea state, which considers the category of sea state intensity.

By completing the short-term analysis on fulfilling a good agreement, the study continues with a long-term analysis that considers the entire sea states based on the scatter diagram alongside their wave frequency of occurrences. These input wave parameters (*Hs*, Tz and d) are used to find the extreme values that correspond to irregular wave analysis that correlate strongly to the structural responses (design responses) for any specific year of return periods.

1.5 Significance of the Study

This study's primary finding is to provide a simple technique for derivation of the probability distribution of extreme structural responses with reference to a specified period. Applying the relationship-based model development, the proposed model not only reduces the computational demand (time-cost), but it proved to be at least equivalent to the MCTS method used in the probability distribution of extreme responses. The offered regression model delivers a simplified approach to the numerical procedure. There is no need to pass through several calculation stages, and it does not need extensive simulations. For example, this simple model is expected to be an effective technique to determine design responses. As observed, there is too much calculation effort needed in completing the whole process for the long-term analysis.

On the other side, the frequency domain is widely applied in estimating the 100-year extreme responses. In industry practice, the calculation based on the frequency domain is preferred because of its efficiency. However, the frequency-based approach always yields inconsistent results. This inconsistency is related to the issue of underprediction or overprediction values. That is why the presence of the regression model based on the time domain are suggested to be more reliable and competent. By using this simplified model, the sustainable and competitive choice for analysing the fixed offshore structures in the oil and gas sector can be provided. Apart from the application, the potential of model development is a generic model that could be applied in any random discipline related to excitation forces (e.g. waves, vibration, wind turbine, aircraft, renewable energy equipment).

1.6 Thesis Overview

This thesis consists of five chapters. The content of each chapter is briefly described below.

Chapter 1 includes the subject of the specific issue generally addressed; following the current problems faced in ocean engineering and the inspiration of the newest approach on how to solve it. Once the problem statement is identified, the proposed method comes up with the new solution, which is to fulfil the limitation from previous studies that had been done up to now. The chapter concludes with the aims and objectives, the scope of the study and the significance of the study. In summary, this chapter accustoms the reader to what is the focused path in this study.

Chapter 2 deals with the reliability analysis in offshore structures in compliance with the rules and regulations. The study finding is related to the safety practices that will be utilised in the design phase and analysis process in order to sustain the structural integrity imposed by the wave loadings. Details of the probabilistic modelling have been discussed comprehensively, either in the probability, frequency and time domains from the previous research achievement. The most relevant parts will be reviewed on the fundamental of ocean wave hydromechanics and the offshore structural assessment. Under the probabilistic analysis, this study will narrowly focus on the new method used in predicting the structural responses in the research gap.

Chapter 3 involves three main simulation procedures in calculating the structural responses. An MCTS method is used for benchmark purpose; meanwhile, an ETS method is a predecessor method, which is used for a proposed model of ETS-Reg model. Due to the limitation on specific (certain) wave conditions, the improvisation of ETS-Reg model is also introduced. Eventually, the proposed method becomes an alternative approach in deriving the short-term and long-term probability distribution for the offshore structures. Each procedure is provided as a comprehensive workflow.

Chapter 4 provides two forms of analysis, namely the short-term and the longterm response analysis. In this chapter, the proposed model would be compared and validated with the benchmark method of MCTS. By initially focusing on the shortterm, the model is assessed in relation to low, medium and high sea state and its corresponding current impact. This initial analysis is to identify the performance of ETS-Reg model regarding observation of accuracy level and efficiency. Having produced a satisfactory result, the study performed a long-term analysis for the cases of without and with current imposed, in which the prediction would be conducted based on Met-Ocean data (entire wave distribution diagram). Besides, for a more detailed analysis, both analyses were examined on the separate hydrodynamic basis, which is drag-induced, inertia-induced and total responses.

Chapter 5, which is the final chapter, explains the accomplishment of the study objectives, and summarises the conclusions that are made throughout this study. A claim of contribution, whether in academic and practical aspects correlated to the theoretical and knowledge, and how this proposed model could compose an impact in the offshore oil and gas industry also are mentioned and further study recommendations are noted. The published conference paper proceedings and award achievements are also recorded.

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Appendix A Structural Data

%basic_hse_structural_data_2004

%'EXPLANATION : All the units are metric, except mass and force ' %'which are in terms of tonnes (1000Kg) and KN, respectively.' %Note that the lower frequency limit must be greater than zero

%basic_hse_structural_data
global_global_gravitational

0.0 a 0 ± 0	
global	global_gravitational_constant global_water_depth global_WLW global_WUW
global	global segment length global frequency interpolation interval
	global_upper_frequency_limit_for_frequency_spectrum_plot

<pre>global_upper_frequency_ global_frequency_interp global_gravitational_cos global_segment_length wave_kinematics_factor</pre>	limit_for_frequency_spectrum_plot olation_interval nstant	= 0.50; = 0.005; = 9.806; = 2^0*1024; = 0.95;	%Hz %Hz %m/s^2
<pre>gnrlsd_stiffness_2 gnrlsd_stiffness_5 gnrlsd_stiffness_8</pre>	= [98.60 105.56 1210.25 4446.75 = [23.81 33.86 96.80 1326.71 489 = [10.02 15.78 29.09 1105.56 77.	3382.74 3070.13 .09 813.09 247.20 43 206.18 135.93	2510.56 20061.60 2489.89 4728.80]; 6 457.23 369.68 694.73]; 179.16 153.46 235.70];
<pre>natural_frequency_2 natural_frequency_5 natural_frequency_8</pre>	= [0.39571 0.41085 1.4202 2.6819 = [0.19188 0.2301 0.40378 1.4328 = [0.12311 0.15506 0.22128 1.307	4.7498 5.2018 10 2.1338 2.2316 3 5 1.6478 1.8101 2	D.358 10.5 11.067 11.83]; .4498 3.783 4.2302 6.4227]; 2.1169 2.1187 2.487 3.7176];
damping_ratio	= [0.05 0.05 0.05 0.05 0.05 0.05	0.05 0.05 0.05 (0.05];
%coeffs of generalized	responses to derive particular re	sponses	

%MN/m %MN/m %MN/m

%(Hz) %(Hz) %(Hz)

generation	copponeed to define pareteatat reepeneed	
<pre>%coef_modal_amp</pre>	= [1 0.012 1 1 1 1 1 1 1 1 %first particular response	
~~~	1 0.012 1 1 1 1 1 1 1]; %second particular response	Э
impulse method	= 'definition'; %choose between 'definition' and 'DFT'	

cylinder_surface	<pre>= 'Rough';</pre>	<pre>%Choose 'Smooth', 'Rough', 'Drag'(Cd=.7&amp;Cm=0.0) or 'Inertia' (cm=1.7)</pre>
simulation_type	= 'NSA';	%'DSA' or 'NSA' for deterministic or non-deterministic amplitude type
x surface elevation	= 0.1;	<pre>%simulate surface elevation at this reference point (meter)</pre>
twosided fr spctrm lngth	n= 2^11;	%No. of data points of the two-sided frequency spectra
<pre>impulse_response_length</pre>	= 2^10;	%No. of impulse response function data points
global_water_depth	= 110.0;	%meter
NM	= 120;	%No. of members (nodal forces) which receive wave load
NRV	= 2;	%No. of reponse variables
NMD	= 10;	%No. of modal responses
RHOW	= 1.025;	%(1000 kgs/cubic meter)
global_WLW	= 0.100;	<pre>%Lower frequency limit ratio; take 0.1 for Pierson-Moskowitz spectrum</pre>
global WUW	= 8.00;	<pre>%Upper frequency limit ratio; take 8.0 for Pierson-Moskowitz spectrum</pre>
COEF	= 1.00;	%Horizontal coordinate scaling coefficient

predominat_wave_direction	on = 0;	%predominant wave direction in degrees
number_of_angle_interval	ls = 2*16;	%Number of angle intervals for directional seas; must be an even number
coef_n	= 4;	%the spreading function coeficient for directional seas; normally equal to 4

%Z: vertical elevation of nodal points is measured from seabed and is positive upwards

8 (1)	(2)	(3)	(4)	(5)	(6)	(7)	(8)	(9)
% Node	NO X	Y	Z	node_below	node_above	DIAMETER	CD	CM
MATRIX_	A =							
[1	-19.0	-17.5	0.0	1	2	1.5	1.05	1.20
2	-19.0	-17.5	8.0	1	9	1.5	1.05	1.20
3	19.0	-17.5	0.0	3	4	1.5	1.05	1.20
4	19.0	-17.5	8.0	3	10	1.5	1.05	1.20
5	19.0	17.5	0.0	5	6	1.5	1.05	1.20
6	19.0	17.5	8.0	5	11	1.5	1.05	1.20
7	-19.0	17.5	0.0	7	8	1.5	1.05	1.20
8	-19.0	17.5	8.0	7	12	1.5	1.05	1.20
9	-19.0	-17.5	16.0	2	13	1.5	1.05	1.20
10	19.0	-17.5	16.0	4	14	1.5	1.05	1.20
11	19.0	17.5	16.0	6	15	1.5	1.05	1.20
12	-19.0	17.5	16.0	8	16	1.5	1.05	1.20

13	-19.0	-17.5	24.0	9	17	1.5	1.05	1.20
14	19.0	-17.5	24.0	10	18	1.5	1.05	1.20
15	19.0	17.5	24.0	11	19	1.5	1.05	1.20
16	-19.0	17.5	24.0	12	20	1.5	1.05	1.20
17	-19.0	-17.5	32.0	13	21	1.5	1.05	1.20
18	19.0	-17.5	32.0	14	22	1.5	1.05	1.20
19	19.0	17.5	32.0	15	23	1.5	1.05	1.20
20	-19.0	17.5	32.0	16	24	1.5	1.05	1.20
21	-19.0	-17.5	39.0	17	25	1.5	1.05	1.20
22	19.0	-17.5	39.0	18	26	1.5	1.05	1.20
23	19.0	17.5	39.0	19	27	1.5	1.05	1.20
24	-19.0	17.5	39.0	20	28	1.5	1.05	1.20
25	-19.0	-17.5	46.0	21	29	1.5	1.05	1.20
26	19.0	-17.5	46.0	22	30	1.5	1.05	1.20
27	19.0	17.5	46.0	23	31	1.5	1.05	1.20
28	-19.0	17.5	46.0	24	32	1.5	1.05	1.20
29	-19.0	-17.5	53.0	25	33	1.5	1.05	1.20
30	19.0	-17.5	53.0	26	34	1.5	1.05	1.20
31	19.0	17.5	53.0	27	35	1.5	1.05	1.20
32	-19.0	17.5	53.0	28	36	1.5	1.05	1.20
33	-19.0	-17.5	60.0	29	37	1.5	1.05	1.20
34	19.0	-17.5	60.0	30	38	1.5	1.05	1.20
35	19.0	17.5	60.0	31	39	1.5	1.05	1.20
36	-19.0	17.5	60.0	32	40	1.5	1.05	1.20
37	-19.0	-17.5	67.0	33	41	1.5	1.05	1.20
38	19.0	-17.5	67.0	34	42	1.5	1.05	1.20
39	19.0	17.5	67.0	35	43	1.5	1.05	1.20
40	-19.0	17.5	67.0	36	44	1.5	1.05	1.20
41	-19.0	-17.5	74.0	37	45	1.5	1.05	1.20
42	19.0	-17.5	74.0	38	46	1.5	1.05	1.20
43	19.0	17.5	74.0	39	47	1.5	1.05	1.20
44	-19.0	17.5	74.0	40	48	1.5	1.05	1.20
45	-19.0	-17.5	79.0	41	49	1.5	1.05	1.20
46	19.0	-17.5	79.0	42	50	1.5	1.05	1.20
47	19.0	17.5	79.0	43	51	1.5	1.05	1.20
48	-19.0	17.5	79.0	44	52	1.5	1.05	1.20

49	-19.0	-17.5	84.0	45	53	1.5	1.05	1.20
50	19.0	-17.5	84.0	46	54	1.5	1.05	1.20
51	19.0	17.5	84.0	47	55	1.5	1.05	1.20
52	-19.0	17.5	84.0	48	56	1.5	1.05	1.20
53	-19.0	-17.5	88.0	49	57	1.5	1.05	1.20
54	19.0	-17.5	88.0	50	58	1.5	1.05	1.20
55	19.0	17.5	88.0	51	59	1.5	1.05	1.20
56	-19.0	17.5	88.0	52	60	1.5	1.05	1.20
57	-19.0	-17.5	93.0	53	61	1.5	1.05	1.20
58	19.0	-17.5	93.0	54	62	1.5	1.05	1.20
59	19.0	17.5	93.0	55	63	1.5	1.05	1.20
60	-19.0	17.5	93.0	56	64	1.5	1.05	1.20
61	-19.0	-17.5	98.0	57	65	1.5	1.05	1.20
62	19.0	-17.5	98.0	58	66	1.5	1.05	1.20
63	19.0	17.5	98.0	59	67	1.5	1.05	1.20
64	-19.0	17.5	98.0	60	68	1.5	1.05	1.20
65	-19.0	-17.5	102.0	61	69	1.5	1.05	1.20
66	19.0	-17.5	102.0	62	70	1.5	1.05	1.20
67	19.0	17.5	102.0	63	71	1.5	1.05	1.20
68	-19.0	17.5	102.0	64	72	1.5	1.05	1.20
69	-19.0	-17.5	105.0	65	73	1.5	1.05	1.20
70	19.0	-17.5	105.0	66	74	1.5	1.05	1.20
71	19.0	17.5	105.0	67	75	1.5	1.05	1.20
72	-19.0	17.5	105.0	68	76	1.5	1.05	1.20
73	-19.0	-17.5	108.0	69	77	1.5	1.05	1.20
74	19.0	-17.5	108.0	70	78	1.5	1.05	1.20
75	19.0	17.5	108.0	71	79	1.5	1.05	1.20
76	-19.0	17.5	108.0	72	80	1.5	1.05	1.20
77	-19.0	-17.5	110.0	73	81	1.5	1.05	1.20
78	19.0	-17.5	110.0	74	82	1.5	1.05	1.20
79	19.0	17.5	110.0	75	83	1.5	1.05	1.20
80	-19.0	17.5	110.0	76	84	1.5	1.05	1.20
81	-19.0	-17.5	112.0	77	85	1.5	1.05	1.20
82	19.0	-17.5	112.0	78	86	1.5	1.05	1.20
83	19.0	17.5	112.0	79	87	1.5	1.05	1.20
84	-19.0	17.5	112.0	80	88	1.5	1.05	1.20

85	-19.0	-17.5	114.0	81	89	1.5	1.05	1.20
86	19.0	-17.5	114.0	82	90	1.5	1.05	1.20
87	19.0	17.5	114.0	83	91	1.5	1.05	1.20
88	-19.0	17.5	114.0	84	92	1.5	1.05	1.20
89	-19.0	-17.5	116.0	85	93	1.5	1.05	1.20
90	19.0	-17.5	116.0	86	94	1.5	1.05	1.20
91	19.0	17.5	116.0	87	95	1.5	1.05	1.20
92	-19.0	17.5	116.0	88	96	1.5	1.05	1.20
93	-19.0	-17.5	118.0	89	97	1.5	1.05	1.20
94	19.0	-17.5	118.0	90	98	1.5	1.05	1.20
95	19.0	17.5	118.0	91	99	1.5	1.05	1.20
96	-19.0	17.5	118.0	92	100	1.5	1.05	1.20
97	-19.0	-17.5	120.0	93	101	1.5	1.05	1.20
98	19.0	-17.5	120.0	94	102	1.5	1.05	1.20
99	19.0	17.5	120.0	95	103	1.5	1.05	1.20
100	-19.0	17.5	120.0	96	104	1.5	1.05	1.20
101	-19.0	-17.5	122.0	97	105	1.5	1.05	1.20
102	19.0	-17.5	122.0	98	106	1.5	1.05	1.20
103	19.0	17.5	122.0	99	107	1.5	1.05	1.20
104	-19.0	17.5	122.0	100	108	1.5	1.05	1.20
105	-19.0	-17.5	124.0	101	109	1.5	1.05	1.20
106	19.0	-17.5	124.0	102	110	1.5	1.05	1.20
107	19.0	17.5	124.0	103	111	1.5	1.05	1.20
108	-19.0	17.5	124.0	104	112	1.5	1.05	1.20
109	-19.0	-17.5	126.0	105	113	1.5	1.05	1.20
110	19.0	-17.5	126.0	106	114	1.5	1.05	1.20
111	19.0	17.5	126.0	107	115	1.5	1.05	1.20
112	-19.0	17.5	126.0	108	116	1.5	1.05	1.20
113	-19.0	-17.5	128.0	109	117	1.5	1.05	1.20
114	19.0	-17.5	128.0	110	118	1.5	1.05	1.20
115	19.0	17.5	128.0	111	119	1.5	1.05	1.20
116	-19.0	17.5	128.0	112	120	1.5	1.05	1.20
117	-19.0	-17.5	130.0	113	117	1.5	1.05	1.20
118	19.0	-17.5	130.0	114	118	1.5	1.05	1.20
119	19.0	17.5	130.0	115	119	1.5	1.05	1.20
120	-19.0	17.5	130.0	116	120	1.5	1.05	1.20

121	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
122	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
123	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
124	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
125	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
126	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
127	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
128	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
129	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
130	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
131	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
132	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
133	-19.0	-17.5	135.0	132.5	67.5	1.5	1.05	1.20
134	19.0	-17.5	135.0	132.5	67.5	1.5	1.05	1.20
135	-19.0	17.5	135.0	132.5	67.5	1.5	1.05	1.20
136	19.0	17.5	135.0	132.5	0.0	1.5	1.05	1.20
137	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
138	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
139	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
140	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
141	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
142	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
143	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
144	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
145	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20
146	0.0	0.0	0.0	0.0	0.0	1.5	1.05	1.20];

#### % NODAL FLEXIBILITY COEFFICIENTS FOR THE FOLLOWING RESPONSES

% NODE No. %	BASE SHEAR	OVERTURNING MOMENT
MATRIX B =		
[1	1.0	0.0
2	1.0	8.0
3	1.0	0.0

4	1.0	8.0
5	1.0	0.0
6	1.0	8.0
7	1.0	0.0
8	1.0	8.0
9	1.0	16.0
10	1.0	16.0
11	1.0	16.0
12	1.0	16.0
13	1.0	24.0
14	1.0	24.0
15	1.0	24.0
16 17	1.0	24.0
1 / 1 0	1.0	32.0
10	1.0	32.0
20	1.0	32.0
21	1 0	39 0
22	1.0	39.0
23	1.0	39.0
24	1.0	39.0
25	1.0	46.0
26	1.0	46.0
27	1.0	46.0
28	1.0	46.0
29	1.0	53.0
30	1.0	53.0
31	1.0	53.0
3∠ 22	1.0	53.0
37	1.0	60.0
34 35	1 0	60.0
36	1.0	60.0
37	1.0	67.0
38	1.0	67.0
39	1.0	67.0

40	1.0	67.0
41	1.0	74.0
42	1.0	74.0
43	1.0	74.0
44	1.0	74.0
45	1.0	79.0
46	1.0	79.0
47	1.0	79.0
48	1.0	79.0
49	1.0	84.0
50	1.0	84.0
51	1.0	84.0
52	1.0	84.0
53	1.0	88.0
54	1.0	88.0
55	1.0	88.0
56	1.0	88.0
57	1.0	93.0
58	1.0	93.0
59	1.0	93.0
60	1.0	93.0
61	1.0	98.0
62	1.0	98.0
63	1.0	98.0
64	1.0	98.0
65	1.0	102.0
66	1.0	102.0
67	1.0	102.0
68	1.0	102.0
69	1.0	105.0
70	1.0	105.0
71	1.0	105.0
72	1.0	105.0
73	1.0	108.0
74	1.0	108.0
75	1.0	108.0

76	1.0	108.0
77	1.0	110.0
78	1.0	110.0
79	1.0	110.0
80	1.0	110.0
81	1.0	112.0
82	1.0	112.0
83	1.0	112.0
84	1.0	112.0
85	1.0	114.0
86	1.0	114.0
87	1.0	114.0
88	1.0	114.0
89	1.0	116.0
90	1.0	116.0
91	1.0	116.0
92	1.0	116.0
93	1.0	118.0
94	1.0	118.0
95	1.0	118.0
96	1.0	118.0
97	1.0	120.0
98	1.0	120.0
99	1.0	120.0
100	1.0	120.0
101	1.0	122.0
102	1.0	122.0
103	1.0	122.0
104	1 0	122 0
105	1 0	124 0
106	1 0	124 0
107	1.0	124.0
108	1.0	124.0
109	1.0	126.0
110	1.0	126.0
111	1.0	126.0
	- • v	± = • • •

112	1.0	126.0
113	1.0	128.0
114	1.0	128.0
115	1.0	128.0
116	1.0	128.0
117	1.0	130.0
118	1.0	130.0
119	1.0	130.0
120	1.0	130.0
121	1.0	0.0
122	1.0	0.0
123	1.0	0.0
124	1.0	0.0
125	1.0	0.0
126	1.0	0.0
127	1.0	0.0
120	1.0	0.0
130	1.0	0.0
131	1.0	0.0
132	1 0	0.0
133	1 0	135 0
1.34	1.0	135.0
135	1.0	135.0
136	1.0	135.0
137	1.0	0.0
138	1.0	0.0
139	1.0	0.0
140	1.0	0.0
141	1.0	0.0
142	1.0	0.0
143	1.0	0.0
144	1.0	0.0
145	1.0	0.0
146	1.0	0.0];

### Appendix B Correlation-*r* and *r*-squared Values for the Short-term Analysis

Table B-1 The coefficient of extreme surface elevation and their corresponding extreme responses between MCTS, ETS-R_{SE} and ETS-R_{LR} methods based on model development of ETS-Reg_{SE} and ETS-Reg_{LR} regression models for base shear quasistatic responses with Hs = 5 m, Tz = 7.95 sec and T = 128sec

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE}	ETS-Reg _{LR}	
Models	Coeffi	cient of correlat	ion ( <i>r</i> )	Coefficient of de	etermination $(r^2)$	
Current ( $U = -0.9 \text{ m/s}$ )						
Linear	0.5157	0.6241	0.9268	0.3895	0.8590	
Polynomial	-	-	-	0.4250	0.8798	
Cubic	-	-	-	0.4597	0.8844	
		Current (U	U = 0.0  m/s	•		
Linear	0.7689	0.8837	0.9343	0.7809	0.8729	
Polynomial	-	-	-	0.8179	0.8743	
Cubic	-	-	-	0.8279	0.8746	
Current ( $U = +0.9 \text{ m/s}$ )						
Linear	0.7182	0.8534	0.9678	0.7283	0.9366	
Polynomial	-	-	-	0.7384	0.9367	
Cubic	-	-	-	0.7443	0.9368	

### a) Drag-induced responses

### b) Inertia-induced responses

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE}	ETS-Reg _{LR}		
Models	Coeffi	cient of correlat	ion ( <i>r</i> )	Coefficient of de	etermination $(r^2)$		
Current ( $U = -0.9 \text{ m/s}$ )							
Linear	0.5800	0.7353	0.9885	0.5407	0.9772		
Polynomial	-	-	-	0.5472	0.9773		
Cubic	-	-	-	0.5629	0.9775		
	Current ( $U = 0.0 \text{ m/s}$ )						
Linear	0.6607	0.8089	0.9902	0.6543	0.9805		
Polynomial	-	-	-	0.6546	0.9807		
Cubic	-	-	-	0.6546	0.9809		
Current ( $U = +0.9 \text{ m/s}$ )							
Linear	0.7366	0.8673	0.9930	0.7523	0.9861		
Polynomial	-	-	-	0.7525	0.9862		
Cubic	-	-	-	0.7534	0.9863		

### c) Total responses

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE}	ETS-Reg _{LR}		
Models	Coeffi	cient of correlat	ion ( <i>r</i> )	Coefficient of de	etermination $(r^2)$		
	Current ( $U = -0.9 \text{ m/s}$ )						
Linear	0.4430	0.5851	0.9598	0.3424	0.9213		
Polynomial	-	-	-	0.3708	0.9378		
Cubic	-	-	-	0.3997	0.9409		
	Current ( $U = 0.0 \text{ m/s}$ )						
Linear	0.7240	0.8444	0.9626	0.7131	0.9265		
Polynomial	-	-	-	0.7360	0.9291		
Cubic	-	-	-	0.7377	0.9292		
Current ( $U = +0.9 \text{ m/s}$ )							
Linear	0.7377	0.8659	0.9719	0.7497	0.9446		
Polynomial	-	-	-	0.7635	0.9448		
Cubic	-	-	-	0.7661	0.9455		

Table B-2 The coefficient of extreme surface elevation and their corresponding extreme responses between MCTS, ETS-R_{SE} and ETS-R_{LR} methods based on model development of ETS-Reg_{SE} and ETS-Reg_{LR} regression models for base shear quasistatic responses with Hs = 10 m, Tz = 11.23 sec and T = 128sec

	-						
Methods	MCTS	ETS-R _{SE}	$ETS-R_{LR}$	ETS-Reg _{SE}	ETS-Reg _{LR}		
Models	Coeffi	cient of correlat	ion ( <i>r</i> )	Coefficient of de	etermination $(r^2)$		
	Current ( $U = -0.9 \text{ m/s}$ )						
Linear	0.8214	0.8925	0.9462	0.7966	0.8953		
Polynomial	-	-	-	0.8438	0.9011		
Cubic	-	-	-	0.8461	0.9011		
	Current ( $U = 0.0 \text{ m/s}$ )						
Linear	0.8605	0.9291	0.9884	0.8632	0.9770		
Polynomial	-	-	-	0.8946	0.9772		
Cubic	-	-	-	0.8946	0.9773		
Current ( $U = +0.9 \text{ m/s}$ )							
Linear	0.8763	0.9433	0.9898	0.8895	0.9797		
Polynomial	-	-	-	0.9129	0.9799		
Cubic	-	-	-	0.9132	0.9801		

a) Drag-induced responses

### b) Inertia-induced responses

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE}	ETS-Reg _{LR}		
Models	Coeffi	cient of correlat	ion ( <i>r</i> )	Coefficient of de	etermination $(r^2)$		
	Current ( $U = -0.9 \text{ m/s}$ )						
Linear	0.8058	0.9187	0.9936	0.8440	0.9873		
Polynomial	-	-	-	0.8475	0.9875		
Cubic	-	-	-	0.8477	0.9877		
		Current (l	U = 0.0  m/s				
Linear	0.8347	0.9287	0.9951	0.8625	0.9903		
Polynomial	-	-	-	0.8652	0.9905		
Cubic	-	-	-	0.8662	0.9909		
Current ( $U = +0.9 \text{ m/s}$ )							
Linear	0.8445	0.9329	0.9965	0.8704	0.9931		
Polynomial	-	-	-	0.8719	0.9934		
Cubic	-	-	-	0.8728	0.9935		

# c) Total responses

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE}	ETS-Reg _{LR}		
Models	Coeffi	cient of correlat	ion ( <i>r</i> )	Coefficient of de	etermination $(r^2)$		
Current ( $U = -0.9 \text{ m/s}$ )							
Linear	0.8319	0.9043	0.9649	0.8178	0.9311		
Polynomial	-	-	-	0.8518	0.9423		
Cubic	-	-	-	0.8524	0.9435		
	Current ( $U = 0.0 \text{ m/s}$ )						
Linear	0.8799	0.9322	0.9891	0.9013	0.9783		
Polynomial	-	-	-	0.9026	0.9786		
Cubic	-	-	-	0.9178	0.9788		
Current ( $U = +0.9 \text{ m/s}$ )							
Linear	0.8822	0.9444	0.9914	0.8919	0.9829		
Polynomial	-	-	-	0.9108	0.9830		
Cubic	-	-	-	0.9111	0.9835		

Table B-3 The coefficient of extreme surface elevation and their corresponding extreme responses between MCTS, ETS-R_{SE} and ETS-R_{LR} methods based on model development of ETS-Reg_{SE} and ETS-Reg_{LR} regression models for base shear quasistatic responses with Hs = 15 m,  $T_Z = 13.75$  sec, T = 128sec

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE}	ETS-Reg _{LR}			
Models	Coeffi	cient of correlat	ion (r)	Coefficient of de	etermination $(r^2)$			
	Current ( $U = -0.9 \text{ m/s}$ )							
Linear	0.8761	0.9145	0.9819	0.8364	0.9642			
Polynomial	-	-	-	0.9119	0.9707			
Cubic	-	-	-	0.9146	0.9719			
	Current ( $U = 0.0 \text{ m/s}$ )							
Linear	0.9127	0.9393	0.9926	0.8824	0.9852			
Polynomial	-	-	-	0.9252	0.9852			
Cubic	-	-	-	0.9263	0.9853			
Current ( $U = +0.9 \text{ m/s}$ )								
Linear	0.9302	0.9553	0.9894	0.9126	0.9788			
Polynomial	-	-	-	0.9392	0.9788			
Cubic	-	-	-	0.9397	0.9788			

a) Drag-induced responses

### b) Inertia-induced responses

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE}	ETS-Reg _{LR}	
Models	Coeffi	cient of correlat	ion ( <i>r</i> )	Coefficient of de	etermination $(r^2)$	
Current ( $U = -0.9 \text{ m/s}$ )						
Linear	0.8475	0.9194	0.9938	0.8452	0.9876	
Polynomial	-	-	-	0.8471	0.9876	
Cubic	-	-	-	0.8479	0.9877	
		Current (l	U = 0.0  m/s	•		
Linear	0.8507	0.9334	0.9945	0.8713	0.9890	
Polynomial	-	-	-	0.8722	0.9890	
Cubic	-	-	-	0.8724	0.9890	
Current ( $U = +0.9 \text{ m/s}$ )						
Linear	0.8448	0.9296	0.9951	0.8642	0.9902	
Polynomial	-	-	-	0.8653	0.9902	
Cubic	-	-	-	0.8655	0.9903	

### c) Total responses

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE}	ETS-Reg _{LR}		
Models	Coeffi	cient of correlat	ion ( <i>r</i> )	Coefficient of de	etermination $(r^2)$		
	Current ( $U = -0.9 \text{ m/s}$ )						
Linear	0.8873	0.9151	0.9820	0.8375	0.9644		
Polynomial	-	-	-	0.9173	0.9723		
Cubic	-	-	-	0.9212	0.9741		
	Current ( $U = 0.0 \text{ m/s}$ )						
Linear	0.9164	0.9408	0.9931	0.8851	0.9862		
Polynomial	-	-	-	0.9284	0.9863		
Cubic	-	-	-	0.9296	0.9864		
Current ( $U = +0.9 \text{ m/s}$ )							
Linear	0.9319	0.9555	0.9903	0.9131	0.9801		
Polynomial	-	-	-	0.9393	0.9806		
Cubic	-	-	-	0.9399	0.9806		

Table B-4 The coefficient of extreme surface elevation and their corresponding extreme responses between MCTS, ETS-R_{SE} and ETS-R_{LR} methods based on model development of ETS-Reg_{SE} and ETS-Reg_{LR} regression models for overturning moment quasi-static responses with Hs = 5 m,  $T_Z = 7.95$  sec, T = 128sec

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE}	ETS-Reg _{LR}	
Models	Coefficient of correlation ( <i>r</i> )			Coefficient of determination $(r^2)$		
		Current (U	r = -0.9  m/s	•		
Linear	0.5283	0.6298	0.9083	0.3966	0.8249	
Polynomial	-	-	-	0.4551	0.8572	
Cubic	-	-	-	0.4943	0.8592	
Current ( $U = 0.0 \text{ m/s}$ )						
Linear	0.7674	0.8838	0.9324	0.7811	0.8695	
Polynomial	-	-	-	0.8201	0.8707	
Cubic	-	-	-	0.8306	0.8707	
Current ( $U = +0.9 \text{ m/s}$ )						
Linear	0.7439	0.8775	0.9570	0.7701	0.9159	
Polynomial	-	-	-	0.7837	0.9161	
Cubic	-	-	-	0.7891	0.9161	

a) Drag-induced responses

## b) Inertia-induced responses

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE}	ETS-Reg _{LR}			
Models	Coefficient of correlation ( <i>r</i> )			Coefficient of determination $(r^2)$				
	Current ( $U = -0.9 \text{ m/s}$ )							
Linear	0.5580	0.7113	0.9839	0.5060	0.9681			
Polynomial	-	-	-	0.5187	0.9682			
Cubic	-	-	-	0.5397	0.9683			
Current ( $U = 0.0 \text{ m/s}$ )								
Linear	0.6437	0.7918	0.9854	0.6270	0.9711			
Polynomial	-	-	-	0.6293	0.9711			
Cubic	-	-	-	0.6293	0.9713			
Current ( $U = +0.9 \text{ m/s}$ )								
Linear	0.7310	0.8667	0.9875	0.7512	0.9751			
Polynomial	-	-	-	0.7513	0.9751			
Cubic	-	-	-	0.7521	0.9755			

# c) Total responses

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE}	ETS-Reg _{LR}	
Models	Coefficient of correlation ( <i>r</i> )			Coefficient of determination $(r^2)$		
~		Current (U	t = -0.9  m/s			
Linear	0.4346	0.5826	0.9470	0.3394	0.8968	
Polynomial	-	-	-	0.3815	0.9212	
Cubic	-	-	-	0.4189	0.9238	
Current ( $U = 0.0 \text{ m/s}$ )						
Linear	0.7126	0.8360	0.9528	0.6988	0.9078	
Polynomial	-	-	-	0.7345	0.9103	
Cubic	-	-	-	0.7386	0.9105	
Current ( $U = +0.9 \text{ m/s}$ )						
Linear	0.7509	0.8770	0.9644	0.7692	0.9300	
Polynomial	-	-	-	0.7881	0.9301	
Cubic	-	-	-	0.7914	0.9310	

Table B-5 The coefficient of extreme surface elevation and their corresponding extreme responses between MCTS, ETS-R_{SE} and ETS-R_{LR} methods based on model development of ETS-Reg_{SE} and ETS-Reg_{LR} regression models for overturning moment quasi-static responses with Hs = 10 m,  $T_z = 11.23$  sec, T = 128sec

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE}	ETS-Reg _{LR}	
Models	Coefficient of correlation ( <i>r</i> )			Coefficient of determination $(r^2)$		
		Current (U	V = -0.9  m/s			
Linear	0.8120	0.8831	0.9462	0.7799	0.8953	
Polynomial	-	-	-	0.8344	0.9011	
Cubic	-	-	-	0.8368	0.9011	
Current ( $U = 0.0 \text{ m/s}$ )						
Linear	0.8621	0.9272	0.9882	0.8597	0.9765	
Polynomial	-	-	-	0.8930	0.9765	
Cubic	-	-	-	0.8931	0.9770	
Current $(U = +0.9 \text{ m/s})$						
Linear	0.8866	0.9431	0.9884	0.8895	0.9769	
Polynomial	-	-	-	0.9129	0.9770	
Cubic	-	-	-	0.9132	0.9774	

a) Drag-induced responses

### b) Inertia-induced responses

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE}	ETS-Reg _{LR}	
Models	Coefficient of correlation ( <i>r</i> )			Coefficient of determination $(r^2)$		
		Current (U	r = -0.9  m/s	•		
Linear	0.7913	0.9048	0.9849	0.8186	0.9701	
Polynomial	-	-	-	0.8228	0.9704	
Cubic	-	-	-	0.8228	0.9704	
Current ( $U = 0.0 \text{ m/s}$ )						
Linear	0.8339	0.9239	0.9886	0.8808	0.9687	
Polynomial	-	-	-	0.8570	0.9777	
Cubic	-	-	-	0.8580	0.9778	
Current ( $U = +0.9 \text{ m/s}$ )						
Linear	0.8544	0.9352	0.9912	0.8820	0.9684	
Polynomial	-	-	-	0.8764	0.9825	
Cubic	-	-	-	0.8773	0.9827	
### c) Total responses

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE} ETS-Reg			
Models	Coefficient of correlation ( <i>r</i> )			Coefficient of determination $(r^2)$			
	Current ( $U = -0.9 \text{ m/s}$ )						
Linear	0.8091	0.8773	0.9697	0.7697	0.9403		
Polynomial	-	-	-	0.8146	0.9557		
Cubic	-	-	-	0.8156 0.9559			
Current ( $U = 0.0 \text{ m/s}$ )							
Linear	0.8688	0.9233	0.9878	0.8525 0.9758			
Polynomial	-	-	-	0.8819 0.975			
Cubic	-	-	-	0.8821	0.9764		
Current ( $U = +0.9 \text{ m/s}$ )							
Linear	0.8888	0.9420	0.9894	0.8873	0.9788		
Polynomial	-	-	-	0.9095	0.9789		
Cubic	-	-	-	0.9096	0.9796		

Table B-6 The coefficient of extreme surface elevation and their corresponding extreme responses between MCTS, ETS-R_{SE} and ETS-R_{LR} methods based on model development of ETS-Reg_{SE} and ETS-Reg_{LR} regression models for overturning moment quasi-static responses with Hs = 15 m, Tz = 13.75 sec, T = 128sec

~ <b>~</b>	I I				1		
Methods	MCTS	ETS-R _{SE}	$ETS-R_{LR}$	ETS-Reg _{SE}	ETS-Reg _{LR}		
Models	Coefficient of correlation ( <i>r</i> )			Coefficient of determination $(r^2)$			
Current ( $U = -0.9 \text{ m/s}$ )							
Linear	0.8708	0.9146	0.9885	0.9174	0.9772		
Polynomial	-	-	-	0.9146	0.9794		
Cubic	-	-	-	0.8365 0.981			
Current ( $U = 0.0 \text{ m/s}$ )							
Linear	0.9126	0.9372	0.9919	0.8783 0.9838			
Polynomial	-	-	-	0.9294	0.9838		
Cubic	-	-	-	0.9307	0.9841		
Current ( $U = +0.9 \text{ m/s}$ )							
Linear	0.9345	0.9548	0.9892	0.9116	0.9785		
Polynomial	-	-	-	0.9463	0.9785		
Cubic	-	-	-	0.9470	0.9785		

a) Drag-induced responses

# b) Inertia-induced responses

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE}	ETS-Reg _{LR}			
Models	Coefficient of correlation ( <i>r</i> )			Coefficient of determination $(r^2)$				
	Current ( $U = -0.9 \text{ m/s}$ )							
Linear	0.8414	0.9162	0.9851	0.8395	0.9703			
Polynomial	-	-	-	0.8442	0.9704			
Cubic	-	-	-	0.8449	0.9704			
Current ( $U = 0.0 \text{ m/s}$ )								
Linear	0.8555	0.9385	0.9842	0.8808 0.9687				
Polynomial	-	-	-	0.8835	0.9688			
Cubic	-	-	-	0.8835	0.9688			
Current ( $U = +0.9 \text{ m/s}$ )								
Linear	0.8568	0.9392	0.9841	0.8820	0.9684			
Polynomial	-	-	-	0.8851 0.9684				
Cubic	-	-	-	0.8853	0.9687			

# c) Total responses

Methods	MCTS	ETS-R _{SE}	ETS-R _{LR}	ETS-Reg _{SE} ETS-Reg			
Models	Coefficient of correlation ( <i>r</i> )			Coefficient of determination $(r^2)$			
Current ( $U = -0.9 \text{ m/s}$ )							
Linear	0.8727	0.9128	0.9889	0.8331 0.9780			
Polynomial	-	-	-	0.9161	0.9804		
Cubic	-	-	-	0.9193 0.9823			
Current ( $U = 0.0 \text{ m/s}$ )							
Linear	0.9129	0.9376	0.9922	0.8792 0.9844			
Polynomial	-	-	-	0.9304	0.9845		
Cubic	-	-	-	0.9317 0.9846			
Current ( $U = +0.9 \text{ m/s}$ )							
Linear	0.9347	0.9548	0.9898	0.9116 0.9794			
Polynomial	-	-	-	0.9461 0.9799			
Cubic	-	-	-	0.9467	0.9802		

#### Appendix C Verification Criteria of the ETS-Regression Model

In order to define the robustness of model development, the accuracy criterion was the main part of the measurements to be considered. Accuracy expresses how closely the estimated value corresponds to its actual value of the benchmark. The accuracy in the short-term perspective needs to identify as the first measurement. It is possible to avoid inaccurate readings, which will contribute to the worse results in the long-term analysis. The guideline, as in this appendix, included in this analysis is to avoid such unexpected happen. Also, they will clarify the sign of the proposed model in good condition.

#### i) Confidence Intervals for Pearson's Correlation Analysis

A hypothesis assessment implies that there is merely not enough depend on the relationship only without knowing how the good model was taken into account. In this section, the proper analysis which is the scientific technique can be derived via the confidence interval (Bewick *et al.*, 2003). In order to measure the confidence interval, the distributed sample data (scatterplot) must be converted into the Gaussian distribution so as to determine the standard error using the Fisher transformation (Kirkwood and Sterne, 2010).

By this technique, the estimation on the lower and upper limits of the confidence interval could be reached by the level of 95 percentiles for the correlation coefficient. Thus, the range between these limits is used to calculate any size of sample data for obtaining a specified level of accuracy (Whitley and Ball, 2002). Once the correlation was analysed, regression analysis would be employed to determine the function for this regression line. Normally, such line is responded to as the regression model.

For this pilot test, the analysis was considered for the cases of low and high sea states without current impact based on the difference of relationship. With reference to Figure 3.19, the pattern of ETS- $R_{SE}$  was chosen due to this relationship was the weak relationship and lowest of *r*-squared among the ETS's relationship from *Sub*- *Subsections 3.6.1.1* and *3.6.1.2*. Below is the more description in Table C-1 for the correlation and its relating regression analysis.

Table C-1 ETS-Reg_{SE} standard error estimates and confidence intervals for the cases of total base shear; quasi-static, Hs = 5 m, Tz = 7.94 sec and U = 0 m/s

ANOVA						
	df	SS	MS	F	Significance F	
Regression	1	169.4906	169.4906	641.1766	0.0000	
Residual	258	68.2005	0.2643			
Total	259	237.6912				
	Coefficients	Standard Error	t Stat	P-value	Lower 95%	Upper 95%
Intercept	1.4569	0.0915	15.9197	0.0000	1.2767	1.6371
Variable SE	8.1673	0.3225	25.3215	0.0000	7.5321	8.8024

Following this findings, an ETS- $\text{Reg}_{SE}$  model was applied to these two variables, which analysed based on the confident interval producing 0.3225 standard error, as shown in Figure C-1.



Figure C-1 The ETS-Reg_{SE} model fit scatterplot related to the confidence interval

Based on the previous relationship in Figure 3.20, it demonstrate that the ETS- $R_{LR}$  was the strong relationship and the highest value of *r*-squared from the relationship based on the ETS method. Consequently, the outcome show that the smallest standard error obtained was 0.0043, as shown in Figure 2. The small error will help the model

to predict the values accurately. This investigation has proven that is why the input parameter of linearised responses could reduce the minimal error, as revealed in Table C-2.

Table C-2 ETS-Reg_{LR} standard error estimates and confidence intervals for the cases of total base shear; quasi-static, Hs = 15 m, Tz = 13.75 sec and U = 0 m/s

ANOVA						
	df	SS	MS	F	Significance F	
Regression	1	185.1992	185.1992	18486.7181	0.0000	
Residual	258	2.5846	0.0100			
Total	259	187.7839				
	Coefficients	Standard Error	t Stat	P-value	Lower 95%	Upper 95%
Intercept	0.2077	0.0118	17.6096	0.0000	0.1845	0.2309
Variable SE	0.5872	0.0043	135.9659	0.0000	0.5787	0.595



Figure C-2 The ETS-Reg_{LR} model fit scatterplot related to the confidence interval

Regarding these comparison of results, the pattern of ETS- $R_{SE}$  relationship produced the wide form of scatterplot, whereas the ETS- $R_{LR}$  relationship formed the narrow (like linear) relationship. Since the ETS- $R_{LR}$  relationship possesses strong relationships, this can be viewed in residuals how the less error affected the high model accuracy. As discussed in *Chapter 2*, the improvement of the ETS- $Reg_{SE}$  model has generated a huge improvement of relationship intensity where the error in scatterplot could be minimised as much as possible. As shown in Figure C-3, the residual comparison can be seen between the ETS-Reg_{SE} model and the ETS-Reg_{LR} models.



Figure C-3 Comparison the residual between ETS-Reg_{SE} and ETS-Reg_{LR} models related to its relationship

Regarding this preliminary analysis, the prediction of 100-year responses by ETS-Reg_{LR} are better accuracy compared to ETS-Reg_{SE}. As expected, the improved relationship gave major impact into the model accuracy of ETS-Reg_{LR} which is the most accurate result achieved due to its strength in relationship-based model development. In accordance to Table 3.6, the ETS-Reg_{LR} based on cubic model is chosen for the permanent model for further studies used in completing the remaining short-term and long-term probability distribution of 100-year structural responses.

#### ii) Sampling Variability and Confidence Intervals



Figure C-4 The bell-shaped curve by reduction of standard deviation from (a) to (b) seeing the improvement in accuracy

The sampling variability is referred to as the variability deriving from the sampling process. The intervals at which the sampling variability is measured are called confidence intervals. Smaller sample size or higher variability corresponds to a wider confidence interval with a larger error margin, as seen in as seen in Figure C-4(a). The confidence level also influences the width of the interval. This interval won't be as narrow if a higher level of confidence is reached. A close 95% or more confidence interval is optimal (preferable as acceptable results), as observed in Figure C-4(b).



Appendix D Short-term Development of Relationship Patterns based on MCTS and ETS Procedures





## Appendix E Short-term ETS-Regression Model Developments





# Appendix F Short-term Analysis on Relationships and its Prediction of 100-year Responses Without Current Impacts

a) Relationship base shear responses

b) Relationship overturning moment responses



a) Prediction of 100-year base shear responses

# PREDICTION OF 100-YEAR RESPONSES U = 0.0 M/s



b) Prediction of 100-year overturning moment responses

#### LIST OF PUBLICATIONS

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# Innovation

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- MTE 2018 Gold Award entitled "Efficient Load Coefficient Method for Structural Reliability Assessment for Ageing Offshore Platform". PWTC, Kuala Lumpur. (22-24 February, 2018).
- ITEX 2018 Gold Award entitled "Efficient Load Coefficient Method for Structural Reliability Assessment for Ageing Offshore Platform". KLCC, Kuala Lumpur. (10-12 May, 2018).
- PECIPTA 2019 Gold Award entitled "Efficient Load Coefficient Method for Structural Reliability Assessment for Ageing Offshore Platform". UTHM, Batu Pahat, Johor. (22-23 Sept, 2019)
- INATEX 2019 Gold Award entitled "Efficient Load Coefficient Method for Structural Reliability Assessment for Ageing Offshore Platform". UTM, Skudai, Johor. (30 Sept-2 Oct, 2019)