



## Exact Analysis of Unsteady Solute Dispersion in Blood Flow: A Theoretical Study

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### Abstract

The diameter of an artery can narrow due to atherosclerosis or stenosis, making it challenging to resolve solute dispersion issues as blood flows via a stenosed artery. The stenosis occurrence restricted drug dispersion and blood flow. This research introduces the establishment of a mathematical model in examining the unsteady dispersion with respect to the solute in overlapping stenosis arteries depicting blood as a Herschel-Bulkley (H-B) fluid model. Note that fluid velocity was obtained by analytically solving the governing and constitutive equations. The transport equation has been solved by employing a generalised dispersion model (GDM), in which the dispersion process is described. Accordingly, yield stress, stenosis height, slug input of solute length, as well as a rise in the power-law index have improved the peak with regard to the mean concentration and solute concentration. The maximum mean concentration yielded the effective dose for therapeutic concentration. In conclusion, this study is relevant to disease arteries, coagulating hemodynamics and may help physiologists in furnishing a more refined understanding of diffusion processes in cardiovascular hydrodynamics. An interesting application related to the present study is the transportation of drugs in the arterial blood flow.

**Keywords:** blood flow; solute; dispersion; Herschel-Bulkley fluid; mean concentration.

## 1 Introduction

The World Health Organization (WHO) reports cardiovascular disease (CVD), which accounts for 17% of all fatalities in 2022, is the leading cause of death worldwide. Atherosclerosis, commonly referred to as stenosis, is the primary cause of CVD. Recently, Hepatitis B and Coronavirus (COVID-19) have been considered the most common factors which increase the risk factors for atherosclerosis or stenosis [13]. Low-density lipoproteins, cellular waste products, cholesterol, calcium, fibrin as well as other substances gradually accumulate on the artery wall to induce stenosis [9, 33]. Such accumulation in the artery might decrease its cross-sectional area, which makes it difficult for blood to pass through. This results in inadequate blood flow to the heart [22]. Death might result from artery stenosis if it continues to deteriorate over time [18]. Additionally, the flow behaviour in the stenosed artery differs from normal arteries. Furthermore, stresses as well as resistance to flow is much greater in stenosed arteries when compared to the normal ones [33]. Therefore, understanding circulatory disorders can be improved by examining blood flow in a restricted artery. Damaged and blocked arteries are severe illnesses that affect a large number of people worldwide. We take the issue into consideration because of its significance, negative effects on society, and the need for additional research to deepen our understanding of the issue. Hence, it is crucial to comprehend the behaviour of blood flow in a stenotic artery because it differs greatly from blood flow in a healthy artery [12].

The stenosis geometry affects the blood movement across the artery. The stenosed artery depends on the stenosis shape, length, and height. Hence, a mathematical study of such a situation is significant. Numerous research has been conducted concerning the onset of sclerosis, and the majority of them classified the shape of the stenosis as either symmetric or asymmetric [27]. However, it is recognized that the stenosis could be numerous in nature or develop irregularly. Hossain and Haque [17] stated that overlapping stenosis has caused more CVDs than the single stenosed artery. Prashantha and Anish [23] agreed with [17] by highlighting that around 70 to 80% of CVDs occur in geometries which are complex such as in an overlapping stenosed artery. According to Freidoonimehr *et al.* [14], the shape as well as the degree of stenosis of a stenotic coronary artery have crucial impacts on the arterial blockage. Uddin *et al.* [35] in their study stated that stenosis effect on blood flow might lead to severe arterial diseases and can be useful in medical science. Recently, Mehkheimer *et al.* [20], using an overlapped stenotic artery, studied the mixing of blood with synovial fluid application to nanoparticle drug delivery. Riahi and Origaza [24] investigated the solute transport in a constricted porous artery consisting of an overlapping stenosis. Apart from that, via an overlapping stenosed artery with a porous wall, Dada *et al.* [11] examined a double-layered blood flow. Here, an overlapped stenotic artery was extensively studied [30, 37].

Transportation of solute (drugs) in arterial blood flow with stenosis is an intriguing application of the current study. When a drug is being injected into an artery, it becomes crucial to determine the drug concentration at a later site in the field of arterial pharmacokinetics. Until a certain extent, the efficacy is effectively therapeutic; however, at that point, it starts to develop local or systemic toxicity, which can have catastrophic consequences. Specifically, as a result of diffusive as well as convective mechanisms in physiological systems, solutes such as nutrients, metabolic products, and drugs are carried by blood flow. The first significant study on dispersion was initiated by Taylor [32]. The author conducted experimental and theoretical studies of the solute's dispersion in a straight tube moving at a mean velocity. He was the first scientist to introduce the concept of axial dispersion. In the study, the author discovered that combining molecular diffusion as well as the mean velocity yields the diffusion of the solute at a molecular diffusivity given by  $D_{eff} = a^2 w_m^2 / 48 D_m$ , in which  $D_m$  represents the molecular diffusivity,  $a$  denotes the tube radius, while  $w_m$  depicts the mean axial velocity. Meanwhile, Aris [4] executed the moment method and reported that Taylor's dispersion theory could only be valid provided that

$D_{eff} \geq D_m$ . In order to improve Taylor's dispersion theory, Aris [4] included the axial molecular diffusion effect,  $D_{eff} = D_m + a^2 w_m^2 / 48 D_m$  and the combination of both findings were described as the Taylor-Aris's dispersion theory. Nevertheless, the proposed theory was inappropriate for short durations despite being valid for a prolonged period. Subsequently, Gill and Sankarasubramanian [16] offered an alternative method called the generalised dispersion model (GDM) to generate a consistent, accurate solution to the transport equation. This approach explains how a solute disperses throughout the bloodstream.

Solute transport has been achieved through a number of mechanisms which include convection as well as axial diffusion. According to Debnath *et al.* [7] the solute transport mechanism present in Newtonian blood flow was discussed using the GDM method, in which the solute is absorbed by the capillary wall with a linear irreversible reaction rate. In addition, Roy and Beg [25] and Roy and Shaw [26] imposed a GDM method to solve the convection-diffusion equation in a two-fluid model to get the transport coefficients and mean concentration of solute. Additionally, the latter is different from the former due to the permeability of the vessel wall as well as the type of fluid. Furthermore, the stenosis severity as well as geometry have an important influence on the distribution of mass concentration as stated by [3]. Numerous recent studies used GDM to govern solute transport in the blood flow [2, 6]. Not all fluids behave in advanced engineering in the same way as Newtonian fluids. Since their nonlinear shear rate as well as stress relationship, non-Newtonian fluids attract the attention of numerous researchers and have a big range of applications in industry and biology, including enhanced oil recovery, chemical processes like those found in distillation towers and fixed-bed reactors, and the use of pumping fluids like colloidal fluids, liquid crystals, synthetic lubricants, and biofluids (animal and human blood) [15, 1]. Despite the use of Newtonian and a number of non-Newtonian fluid models to explore blood motion, it is now understood that the Herschel-Bulkley (H-B) model best captures the behaviour of blood. Furthermore, a type of non-Newtonian fluid known as H-B fluids must experience finite critical stress, or yield stress, to deform. Additionally, these materials act as rigid solids when the local shear is less than the yield stress. Moreover, the material flows with a nonlinear stress-strain relationship once the yield stress is exceeded, either as a shear-thickening fluid or as a shear-thinning fluid. Paints, cement, food goods, polymers, slurries, blood flow, and pharmaceutical products are a few examples of fluids that behave in this manner [29].

Sankar *et al.* [28] used H-B fluid in poiseuille flow to study the effects of geometrical as well as fluid parameters in the medium which are porous. Wajihah and Sankar [36] emphasized that blood is a complex fluid with non-Newtonian properties, shear thinning behavior, viscoplasticity (yield stress), and a thixotropic nature in their review. Singh and Murthy [31] investigated pulsatile H-B fluid flow with unsteady solute dispersion in a tube to assess the impact of skewness and kurtosis on the distribution and its concentration. According to Tiwari *et al.* [34], variations in blood viscosity explained the unsteady solute dispersion using H-B fluid. They explained how an enhancement in the viscosity index impacts the diffusion coefficients and fluid flow velocity. In the following year, Chauhan and Tiwari [10] used Jeffrey fluid and H-B fluid to understand the solute dispersion through microvessels with absorbing walls under varying viscosity assumptions.

As a result, investigations on the issue of solute dispersion in blood flow with the inclusion of a mass transfer in an artery having stenosis are lacking, according to earlier publications in the literature. Therefore, it is essential to investigate solute dispersion in a non-Newtonian fluid in order to get accurate results that more accurately depict physical issues. To comprehend how non-Newtonian rheology affects solute dispersion, it is also vital to grasp the rheological parameters. This issue can be resolved by forecasting the mean concentration of solute and the transport coefficients in narrow arteries with low shear rates. For axisymmetric, incompressible, as well as fully developed flow of blood in a rigid, impermeable artery with constant axial pressure gradient and viscosity, a novel mathematical model is created in the present study. Hence, combining

many features that have only been examined separately in prior studies constitutes the novelty of the present research. Herein we amalgamate (i) a non-Newtonian fluid model consisting of overlapping stenosis as well as (ii) the GDM to solve the convection-diffusion equation. The current issue takes into account solute or drug distribution in stenosed arterial blood flow, in which a H-B fluid model has been taken into consideration. Knowing how a drug is capable of being distributed, how its amount varies along an artery, and, in particular, how atherosclerosis can affect the amount of drug that is needed in order to reach its target for the patient’s specific illness is important for understanding the problem faced when transporting the drug to a patient whose artery has been damaged resulting from the occurrence of atherosclerosis. We discover, in particular, that drug diffusivity has a significant impact on drug transport and that faster drug delivery is achieved with smaller values of the diffusivity coefficient when the initial drug value is not too small. The research findings will improve the existing knowledge of several physiological processes that involve introducing and transporting a known amount of solutes, such as drugs, into the bloodstream in the presence of stenosis. In the field of arterial pharmacokinetics, when a drug is injected into an artery, it is essential to assess the drug concentration at some downstream site. The injected drug has therapeutic efficacy up to a certain point, after which it develops systemic toxicity, which can have serious implications. The study has credible applications in medicine and biomedical engineering. In addition, the outcomes of the present work help in the treatment of many cardiovascular diseases. Therefore, this research may aid doctors in determining the extent of stenosis and its long-term effects or in the treatment of cardiovascular ailments including myocardial infarction, stroke, and heart attacks. In the event of more severe stenosis, this investigation may be furthered by the addition of other rheological and physical data.

## 2 Mathematical Formulation and Solution Methodology

The flow of a steady non-Newtonian fluid that is incompressible through a circular artery with overlapping stenosis, as depicted in Figure 1, is taken into consideration. It is unidirectional, laminar, and fully developed. Blood rheology is characterized using a H-B fluid model. The wall of the stenosed artery is assumed to be rigid and impermeable.

### 2.1 Governing equations

The cylindrical polar coordinates comprise three parameters, namely, the radial coordinate ( $\bar{r}$ ), axial coordinate ( $\bar{z}$ ) and the azimuthal angle,  $\bar{\theta}$ . Note that this study ignores the velocity of the fluid in  $\bar{r}$  direction since its magnitude is negligibly small and it only considers the direction of  $\bar{z}$ . Therefore,  $\bar{u}_{\bar{r}} = \bar{u}_{\bar{\theta}} = 0$ . Moreover, the velocity  $\bar{u}_{\bar{z}}$  refers to an independent and uniform in both  $\bar{z}$  and  $\bar{\theta}$  directions due to the axial symmetry, hence, the momentum equation of axial and radial components is reduced to the following [26, 28]:

$$\frac{d\bar{p}}{d\bar{z}} = -\frac{1}{\bar{r}} \frac{d}{d\bar{r}}(\bar{r}\bar{\tau}), \tag{1}$$

$$\frac{d\bar{p}}{d\bar{r}} = 0, \tag{2}$$

in which the constant pressure as well as shear stress, are represented as  $\bar{p}$  and  $\bar{\tau}$ , respectively. Equation (1) deploys that the pressure differs only in the axial direction. Here, the equation given

below displays the constitutive equation of H-B fluid [34, 10]:

$$\frac{d\bar{u}}{d\bar{r}} = \begin{cases} -\frac{1}{\eta_{HB}} (\bar{\tau} - \bar{\tau}_y)^n & \text{if } \bar{\tau} \geq \bar{\tau}_y, \\ 0 & \text{if } \bar{\tau} < \bar{\tau}_y, \end{cases} \tag{3}$$

in which  $\bar{\tau}_y$  and  $\bar{u}$  denote the yield stress and axial velocity, accordingly. The H-B fluid viscosity coefficient can be expressed by  $\eta_{HB}$  with a dimension of  $(ML^{-1}T^{-2})^n T$  whereas the power-law index is  $n$ . Equation (3) illustrates that normal shear flow takes place in the region provided that  $\bar{\tau} \geq \bar{\tau}_y$ . On the other hand, plug flow field or solid-like fluid occurs when  $\bar{\tau} < \bar{\tau}_y$ . Besides, Bessonov et al. [8] claimed that the fluid in the region would not flow if the yield stress were higher compared to the shear stress. Furthermore, in this area, fluid (blood) will not flow. As a solid mass is transported at a constant velocity, it is somehow transported by fluid particles found in the nearby shear flow region. The unknown parameters, shear stress  $\bar{\tau}$  and velocity  $\bar{u}$ , can be solved by utilizing equations (1) and (3) depending on the boundary conditions expressed as follows:

$$\bar{\tau} \text{ is finite at } \bar{r} = 0, \tag{4}$$

$$\bar{u} = 0 \quad \text{at } \bar{r} = \bar{R}(\bar{z}). \tag{5}$$

The finite yield stress effect, as seen in the boundary condition, equation (4), is that fluid exhibits a behaviour which is solid-like or plug flow (in which all velocity gradient can be negligible) in regions where the shear stress is less than the yield stress ( $\bar{\tau} < \bar{\tau}_y$ ) at  $\bar{r} = 0$ . However, since the fluid is viscous, it tends to sticks to the arterial wall, referred to as a no-slip condition as in equation (5) when  $\bar{r} = \bar{R}(\bar{z})$ .

### 2.2 Non-dimensionalisation

The dimensionless variables below are introduced:

$$\begin{aligned} C &= \frac{\bar{C}}{\bar{C}_0}, & u &= \frac{\bar{u}}{u_0}, & u_m &= \frac{\bar{u}_m}{u_0}, & r &= \frac{\bar{r}}{R_0}, & R(z) &= \frac{\bar{R}(\bar{z})}{R_0}, \\ \tau &= \frac{\bar{\tau}}{(p_0 R_0/2)}, & \tau_y &= \frac{\bar{\tau}_y}{(p_0 R_0/2)}, & l_0 &= \frac{\bar{l}_0}{R_0}, & \delta &= \frac{\bar{\delta}}{R_0}, \end{aligned} \tag{6}$$

where solute concentration =  $C$ , velocity =  $u$ , average velocity =  $u_m$ , stenosis height =  $\delta$ , centreline velocity:  $u_0 = \frac{R_0^{n+1} p_0^n}{2^n \eta_{HB}}$ , the stenotic artery radius =  $R(z)$ , radial distance =  $r$ , shear stress =  $\tau$ , yield stress =  $\tau_y$ , stenosis length =  $l_0$  and  $\eta_{HB} = \mu \left( \frac{p_0 R_0}{2} \right)^{n-1}$ , and  $\mu$  denotes the coefficient of viscosity with regard to a Newtonian fluid.

### 2.3 Geometry of stenosis

The artery geometry, which is in a dimensionless form, can be expressed as follows [19]:

$$R(z) = \begin{cases} 1 - \frac{3\delta}{2l_0^4} [11(z-d)l_0^3 - 47(z-d)^2 l_0^2 + 72(z-d)^3 l_0 - 36(z-d)^4], & d \leq z \leq d + l_0, \\ 1, & \text{Otherwise,} \end{cases} \tag{7}$$

where the maximum stenosis height appears at  $d + l_0/3$  as well as  $d + 2l_0/3$ , the distance with regard to the stenosis from the inlet =  $d$ , while the artery's length =  $L$ . Here, the geometry with regard to an artery with overlapping stenosis under consideration is displayed in Figure 1.

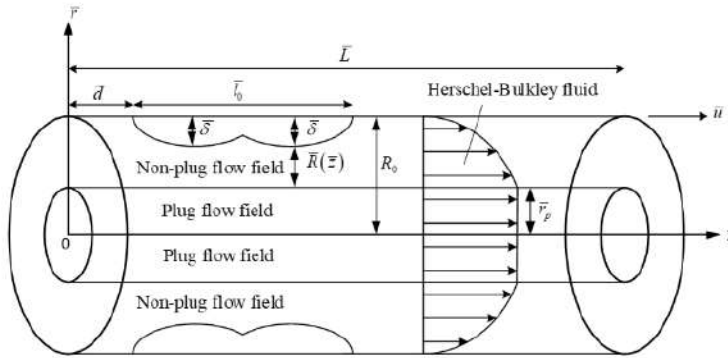


Figure 1: The geometry of an overlapping stenosed artery.

### 2.4 Mass transport

The convection-diffusion equation [7], which is represented in equation (8), governs the mass transport flow in the bloodstream in the dimensionless form given by

$$\frac{\partial C}{\partial t} + u \frac{\partial C}{\partial z} = \left( \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial}{\partial r} \right) + \frac{1}{Pe^2} \frac{\partial^2}{\partial z^2} \right) C, \tag{8}$$

where Peclet number =  $Pe$ , dispersion time =  $t$ , and coefficient of mass diffusion =  $D_m$ .

### 2.5 Method of solution

The equation measuring the shear stress is achieved by integrating equation (1) to  $r$  under boundary condition (4) and is written as follows:

$$\bar{\tau} = -\frac{\bar{r}}{2} \frac{d\bar{p}}{d\bar{z}}. \tag{9}$$

The velocity of the outer as well as plug flow fields with regard to non-dimensional forms in equation (6) is generated by substituting equation (9) into equation (3), followed by integrating the result to  $r$  with the boundary condition (5), as shown below:

$$u_+(r) = \left[ \frac{R(z)^{n+1}}{(n+1)} - \frac{r^{n+1}}{(n+1)} - r_p (R(z)^n - r^n) + \frac{n}{2} r_p^2 (R(z)^{n-1} - r^{n-1}) \right] 2^n, \tag{10}$$

if  $\tau \geq \tau_y$  and  $r_p \leq r \leq R(z)$ ,

$$u_-(r_p) = \left[ \frac{R(z)^{n+1}}{(n+1)} - r_p R(z)^n + \frac{n}{2} r_p^2 R(z)^{n-1} - \frac{n(n-1)}{2(n+1)} r_p^{n+1} \right] 2^n, \tag{11}$$

if  $\tau < \tau_y$  and  $0 \leq r < r_p$ .

As per Gill and Sankarasubramanian [16], the solution to equation (8) is measured as a series expansion and depicted as:

$$C(r, z, t) = C_m(z_1, t) + \sum_{i=R(z)}^{\infty} f_i(r, t) \frac{\partial^i C_m(z_1, t)}{\partial z_1^i}, \tag{12}$$

in which dispersion function =  $f_i$ , mean concentration =  $C_m$ , while a new axial coordinate moving with the average velocity is  $z_1 = z - u_m t$ . Additionally, as time starts,  $C_m$  distribution is diffusive. Hence, the GDM as appropriate functions of time  $t$  can be written as follows:

$$\frac{\partial C_m}{\partial t} = \sum_{i=1}^{\infty} K_i(t) \frac{\partial^i C_m}{\partial z_1^i}(z_1, t), \tag{13}$$

where  $K_i(t)$  resembles the dispersion coefficient. The series expansion is obtained by employing equation (13) and substituting equation (12) in equation (8). The function of  $f_1$  in Eq. (12) is the most essential to measure  $C$ . By equating the coefficients of  $\partial^i C_m / \partial z_1^i$  and let  $f_1(r, t) = f_{1s}(r) + f_{1t}(r, t)$ , in which  $f_{1s}$  refers to the steady-state while  $f_{1t}$  represents the state which is unsteady. Here, the variable separation method as well as the Bessel function is employed in solving the transient state,  $f_{1t}(r, t)$  of the dispersion function provided that  $f_{1t}(r, 0) = -f_{1s}(r)$  and  $\partial f_{1t} / \partial r = 0$ . The solution  $f_{1t}(r, t)$  is numerically computed by employing Simpson’s 3/8 rule expressed as:

$$f_{1t}(r, t) = \sum_{m=1}^{\infty} A_m e^{-\lambda_m^2 t} J_0(\lambda_m r), \tag{14}$$

where,

$$A_m = -\frac{\int_0^{R(z)} J_0(\lambda_m r) f_{1s}(r) r dr}{\int_0^{R(z)} J_0^2(\lambda_m r) r dr} = -\frac{2}{J_0^2(\lambda_m)} \int_0^{R(z)} J_0(\lambda_m r) f_{1s}(r) r dr. \tag{15}$$

Here, eigenvalues  $\lambda_m$  represent the roots of the equation  $J_1(r) = 0$ . Moreover,  $J_0$  and  $J_1$  represents Bessel functions of the first kind of order zero and one, accordingly. Additionally, the dispersion coefficient of the solute  $K_2(t)$  is obtained by substituting equations (10), (11), and the solution of  $f_1(r, t)$ , which is displayed as follows:

$$K_2(t) = \frac{1}{Pe^2} - 2 \int_0^{R(z)} f_1 u r dr. \tag{16}$$

The terms  $K_3(t)$  and higher-order terms are ignored since the value is negligibly small. Thus, equation (13) is simplified to:

$$\frac{\partial C_m}{\partial t} = K_2(t) \frac{\partial^2 C_m}{\partial z_1^2}(z_1, t). \tag{17}$$

The following equations show the boundary and initial conditions for  $C_m(z_1, t)$ :

$$C_m(z_1, 0) = \begin{cases} 1, & \text{if } |z_1| \leq \frac{z_s}{2}, \\ 0, & \text{if } |z_1| > \frac{z_s}{2}, \end{cases} \tag{18}$$

and

$$C_m(\infty, t) = 0. \tag{19}$$

The linear second-order partial differential equation of equation (17), with the help of conditions (18) and (19), is transformed into a linear ordinary differential equation analytically using the Fourier transform, the inverse Fourier transform, and the convolution theorem to obtain the  $C_m$  as presented below:

$$C_m(z_1, t) = \frac{1}{2} \left[ \operatorname{erf} \left( \frac{z_s/2 - z_1}{2\sqrt{\xi}} \right) + \operatorname{erf} \left( \frac{z_s/2 + z_1}{2\sqrt{\xi}} \right) \right], \tag{20}$$

where,

$$\xi(t) = \int_0^t K_2(s) ds. \tag{21}$$

By substituting  $C_m(z_1, t)$  and  $f_1(r, t)$  into equation (12) and ignoring the higher-order terms, the local concentration  $C(r, z_1, t)$  is obtained as shown below:

$$C(r, z_1, t) = C_m(z_1, t) + f_1(r, t) \frac{\partial C_m(z_1, t)}{\partial z_1}. \tag{22}$$

### 3 Results and Discussion

The aim of the study was to assess the blood flow behaviour in the presence of stenosis and also to examine the non-Newtonian rheological behaviour by varying the physical parameters. The effect of varying slug input lengths  $z_s$ , the power-law index  $n$ , the yield stress  $r_p$ , as well as stenosis height  $\delta$  with respect to the mean concentration of the solute  $C_m$  has been employed, with a range of parameters values:  $r_p : 0 - 0.3$ ,  $\delta : 0 - 0.04$ ,  $n : 0.5 - 1.5$ , and  $z_s : 0.004 - 0.019$  [7, 26]. Mathematica software was employed to create data and results for comparison and validation purposes. The results of Gill and Sankarasubramanian [16] were equivalent to the mean concentration of solute obtained in our investigation, according to Figures 2(a) and 2(b). For validation purposes, the value of  $r_p$  was set to zero while the geometry of the stenosed artery,  $R(z)$  as well as  $n$  was fixed to one to portray the Newtonian fluid without stenosis as presented in [16].

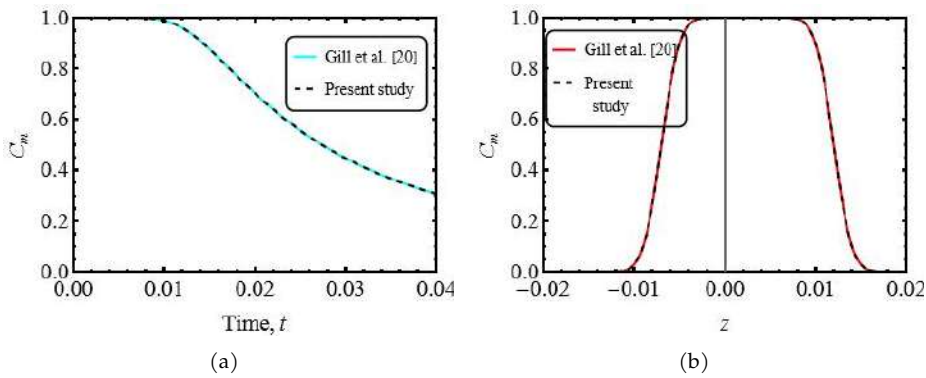


Figure 2: Validation of the mean concentration of solute (a) with time,  $t$  (b) with axial distance,  $z$ .

Figure 3(a) depicts the variation in the mean concentration of solute with time for the different slug inputs of solute length  $z_s$  when  $z = 0.5$ ,  $r_p = 0.1$ ,  $n = 0.95$ ,  $l_0 = 3$ ,  $d = 2$ ,  $\delta = 0.01$  and  $Pe = 1000$ . It can be seen that the peak of the mean concentration  $C_m$  occurs at  $t = 1.15$  for various slug input lengths. Moreover, the peak of  $C_m$  ascends with the raise of slug input length  $z_s$ . Furthermore, there is a two-fold increase when  $z_s$  increases from 0.004 to 0.008. A four-fold increase can be seen when  $z_s = 0.019$ . Here, the mean concentration of solute is seen to increase slowly with time which then reaches the peak position (higher concentration) in a natural way. The mean concentration of solute then decreases and finally disappears. The molecular diffusion caused by the concentration gradient from an area with high concentration to a region of low concentration increases the solute’s mean concentration.

The variation in mean solute concentration over time for various fluids is shown in Figure 3(b). Based on the blood’s rheology, it is noticed that the peak of mean concentration  $C_m$  is greater for the non-Newtonian nature ( $r_p > 0$ ) of the blood compared to the Newtonian nature ( $r_p = 0$ ). These results are in line with findings from Roy and Shaw’s [26]. The peak of  $C_m$  for Newtonian fluid occurs at  $t = 0.98$ , for Bingham fluid when  $r_p = 0.1$ ,  $n = 1$  is at  $t = 1.1$ . Additionally, in the case of Power-law fluid when  $r_p = 0$ ,  $n = 0.5$ , the peak of  $C_m$  is reached at  $t = 1.13$  and for H-B fluid when  $r_p = 0.1$ ,  $n = 0.5$  is at  $t = 1.25$ . More drug particles swiftly reach the disease site as the mean concentration rises by increasing the number of particles capable of getting there. It is generally known that the power-law index and yield stress boost the mean solute concentration, which improves the target disease recovery rate.

Figure 3(c) demonstrates how the mean solute concentration changes over time for different stenosis heights  $\delta$  when  $z_s = 0.019$ ,  $z = 0.5$ ,  $r_p = 0.1$ ,  $n = 0.95$ ,  $l_0 = 3$ ,  $d = 2$  and  $Pe = 1000$ . The peak of  $C_m$  escalates when there is a rise in the stenosis height at  $t = 1.12$ . These findings show that as the stenosis height increases considerably, the radius of the stenotic artery decreases from  $R(z) = 1, 0.99, 0.98, 0.97$  to  $0.96$ , making the arterial wall narrower because of the accumulation of fats, lipids, cholesterol, as well as other unwanted substances found at the arterial wall. As a result, the normal flow of blood in the artery wall



is disrupted. Both blood flow and the magnitude of the flow rely on the height of the stenosis [5]. Misra and Chakravarty [21] found that improvement in stenosis height will decrease the amount of blood hematocrit in the stenotic area, resulting in reduced blood viscosity.

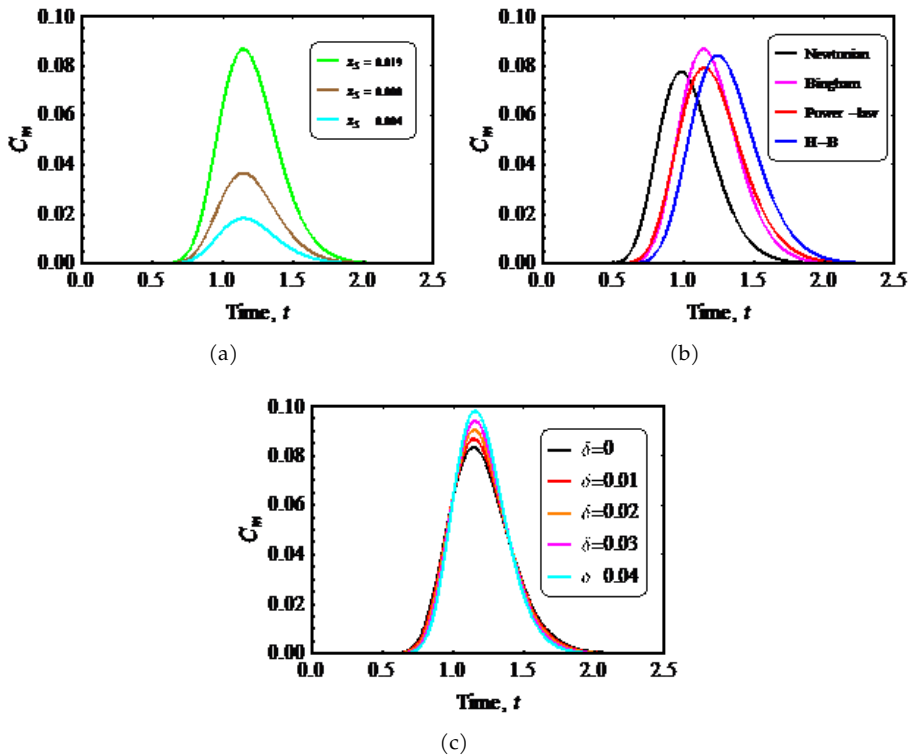


Figure 3: Variation of the mean concentration of the solute with time for various solute length  $z_s$  (a), type of fluids (b), and (c) stenosis height  $\delta$ .

Table 1 provides results of the difference in mean concentration as well as the concentration of solute with time for various yield stress. Yield stress relates to the non-Newtonian nature of the fluid, and when increasing the yield stress, the viscosity of the blood tends to increase as well. At the same moment, the yield stress is related to the radius of the plug region by the relation  $\tau_y = r_p/2$ , which illustrates that the radius of the plug region rises when there is an increase in the yield stress. It can be seen that with a rise in the plug core radius or yield stress, the flow velocity decreases, and hence the mean concentration and concentration of solute also increases. Moreover, the peak of the mean concentration  $C_m$  and concentration of solute  $C$  occurs at different  $t$  as  $r_p$  is varied.

Table 2 illustrates the results of the difference in mean concentration as well as the concentration of solute with axial distance for various power-law indexes. Power-law index is crucial in controlling the viscosity as well as the velocity of a fluid. When the power-law index escalates from  $n = 0.5, 1$  to  $1.5$ , the viscosity of fluid also rises, thus reducing the mean concentration and concentration of solute. Furthermore, the peak mean concentration  $C_m$  and concentration of solute  $C$  occurs at  $z = 0.04$  when  $n = 0.5$  and  $1$ , whereas when  $n = 1.5$ , it is at  $z = 0.05$ . As  $n$  increases, the shear thinning nature of the fluid reduces. Consequently, both flow velocity as well as dispersion coefficient decreases. Hence, the mean concentration  $C_m$  and concentration of solute  $C$  rises.

Table 1: Variation of mean concentration and concentration of solute with time for different plug core radius.

Time, $t$	$C_m$			$C$		
	$r_p = 0.1$	$r_p = 0.2$	$r_p = 0.3$	$r_p = 0.1$	$r_p = 0.2$	$r_p = 0.3$
1.3	0.06675	0.06797	0.07406	0.06680	0.06794	0.07399
1.4	0.04490	0.06810	0.08628	0.04498	0.06811	0.08623
1.5	0.02636	0.07808	0.09263	0.02645	0.07812	0.09259
1.6	0.01386	0.05353	0.11453	0.01396	0.05359	0.11452
1.7	0.00665	0.03191	0.11186	0.00675	0.03198	0.11187

Table 2: Variation of mean concentration and concentration of solute with axial distance for different power-law index.

$z$	$C_m$			$C$		
	$n = 0.5$	$n = 1$	$n = 1.5$	$n = 0.5$	$n = 1$	$n = 1.5$
0.00	0.07488	0.05878	0.05733	0.07494	0.05883	0.05739
0.01	0.14361	0.11809	0.11128	0.14366	0.11814	0.11133
0.02	0.22819	0.19764	0.18302	0.22823	0.19769	0.18306
0.03	0.30056	0.27564	0.25513	0.30058	0.27567	0.25516
0.04	0.32823	0.32040	0.30150	0.32822	0.32041	0.30151
0.05	0.29719	0.31046	0.30208	0.29717	0.31044	0.30207

### 4 Conclusions

The current research aimed to investigate how the height of the stenosis and non-Newtonian behaviour affected the solute dispersion in the cardiovascular system. Additionally, the following is an overview of the primary results:

1. Mean concentration and concentration of solute are improved with a rise in the slug input length, power-law index, yield stress, as well as stenosis height;
2. The peak  $C_m$  demonstrates the maximum concentration and effective concentration, whereas the maximum  $C_m$  is the effective dose for therapeutic concentration. The side effects of a specific drug can be predicted by determining the maximum concentration;
3. When the solute disperses in the H-B fluid model, the mean solute concentration is considerably greater. The H-B fluid’s yield stress as well as the power-law index make it possible to control the fluid’s viscosity. The H-B fluid model, therefore, provides a more precise model of blood rheology.

It is believed that this analysis would provide valuable insight into CVD and aid researchers in their knowledge of solute diffusion and solute dispersion in blood flow. Additionally, by determining the drug’s concentration in the arteries’ bloodstream, researchers can predict the appropriate dose for therapeutic concentration. Future study may applies and compares these research findings with the experimental results. From this research, scientists, pharmaceutical companies, and drug production companies (drug industries) can create more effective medications for medical use by observing the drug concentration and blood flow behaviour.

The primary focus of this study is on the solute concentration in the dispersion process in a steady flow. Further investigation into the effects of flow pulsatility on fluid dispersion in stenosis will be helpful, given that blood flow is highly pulsatile in nature. Additionally, this study is limited strictly to mathematical analysis. The results might be more significant and generously add to the experiment’s observations. In order to enhance the study, additional experimental findings related to the dispersion of a solute in blood flow with stenosis are advised for future research.

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