# MODEL PREDICTIVE CONTROL STRATEGY FOR PRECISION IRRIGATION TOWARDS WATER SAVING AGRICULTURE

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## MODEL PREDICTIVE CONTROL STRATEGY FOR PRECISION IRRIGATION TOWARDS WATER SAVING AGRICULTURE

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A thesis submitted in fulfilment of the requirements for the award of the degree of Doctor of Philosophy

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#### ACKNOWLEDGEMENT

I want to humbly thank the almighty God, the Kings of Kings and Lord of Lords for his faithfulness, grace and mercies from the beginning of this programme till now. Your faithfulness are new every morning, new every morning. Great is thy faithfulness o Lord, Great is they faithfulness Lord.

I equally express my profound gratitude to my supervisor, Assoc. Prof. Dr. Mohamad Shukri Zainal Abidin for his tutelage, advice, guidance, immense support towards the success of the programme. His entire family members are also appreciated for the relentless supports, especially on the countless get together which tremendously helped me to get used with Malaysian cuisines. Every of those special moments meant a lot and I do cherish them. I equally appreciate my Co Supervisors Assoc. Prof. Dr. Salinda Buyamin and Dr. Mohd Saiful Azimi Mahmud for their mentorship and guidiance. May God reward you abundantly.

I really appreciate entire staff of School of Electrical Engineering (SKE, UTM) is for organizing short courses and training and expert advice. My colleagues in Mobile Robot Laboratory, Khaire Idham, Azwan Ramli, Dr. Hammeda, Dr. Umar Zangina, Hassan Algabray, Balogun Wasiu Adebayo, Dr Hazriq, Dr Izudeeen & Dr Liyana are highly appreciated. Am always motivated by your words of encouragements and kind supports.

I equally appreciate my darling wife, Joy Taiye Bossa Esq and my Son, Abioye Alexander Oluwadarasimi, for their prayers, encouragement, and understanding. She and my lovely Son are great sources of my inspirations not to give up when my morals goes low and things seems uncertain. Alexander, will always say "Daddy weldone". God added another crown on my head, by blessing us with Abioye Anderson Oluwatimilehin towards the end of my PhD research. To God be the glory for his blessings. I cherish and adore them firmly in my heart. To my parents Daddy & Mummy Reuben Ajayi Abioye, for their efforts in bringing up in the way of the Lord. I also appreciate my mother inlaw, Madam C.Y. Bossa, I am grateful for your love and supports for the family. I have the best siblings and inlaws in the world Mayowa, Ayodele, Mary, Kemi, Kehinde, Emmanuel. I sincerely appreciate you all and your

entire family members for your love, prayers and supports. Special thanks Professor M. I. Ajibero, who has also been like a father. My academic journey from first degree to PhD will not be possible if not for God and your efforts. May God reward you abundantly.

My special appreciation also goes to Dr. A. O. Otuoze, Engr. Adeyeye Gbenga, Dr. Bulus Ibrahim, Dr. Obalowu Muhamed, Dr. Olakunle Elijah, who were with me throughout the PhD journey. Your love and kind supports are highly acknowledged.

The management of Akanu Ibiam Federal Polytechnic, Unwana (AIFPU) is duly acknowledged for their kind support for granting me the opportunity for study leave with pay. I also wish to acknowledge the entire staff of the School of Engineering and Technology, AIFPU and especially, those of the Department of Electrical and Electronics Engineering for their encouragements and supports.

#### **ABSTRACT**

The field of precision agriculture has widely utilized drip and capillary irrigations for water saving. However, most of the existing controllers for drip irrigation are not capable of adapting to the changing dynamics of soil, plant and weather effect in real-time. Also, investigations have revealed that capillary irrigation has potential for high water saving capability. Moreover, it suffers under-performance due to inaccurate determination and estimation of the water supply depth ( $\Delta h$ ) for wetting the root zone of plant. The advent and rapid successes of the internet of things (IoT) and advanced control theory are being integrated for improving monitoring system to achieve precision irrigation. In this thesis, two case studies namely a data-driven model predictive control (MPC) strategy for drip irrigated Cantaloupe plant and a Kalman filter based-PID controller for fibrous capillary irrigated Mustard leaf are proposed. An IoT based cultivation experiment on Cantaloupe plant and Mustard leaf was carried out for data collection on soil, plant, and weather parameters using the drip and capillary irrigations. The data collected are used to develop predictive models using system identification in MATLAB to obtain an accurate model representing the changing dynamics of the systems of both case studies. The predictive model for Cantaloupe cultivation was further used to design MPC and Laguerre network-based MPC for real-time drip irrigation management. To investigate the management of the capillary irrigation system, a Kalman filter based-PID control strategy was developed using the predictive model from Mustard leaf cultivation. The developed model based controllers were then integrated with network of sensor devices using IoT for real-time monitoring of the soil, plant and weather parameters to manipulate the  $\Delta h$  based on plant demand. The effectiveness of the model based controllers was simulated using Simulink and deployed on Raspberry Pi to validate their performance. Three greenhouses (GH1, GH2 and GH3) were used for cultivation experiments to test the performance of the developed control system. The data-driven modelling results for drip irrigation show that the ARX model has better accuracy in terms of MSE of 0.753 with an estimated fit of 91.31%, while a state-space model with an estimated fit of 92.3% was equally identified for the capillary irrigation dynamics. The experimental results show a better performance for the proposed controller deployed in GH2 with 30% savings in water and fertilizer, water productivity index of 23 g/L, and fruit sweetness of 13 Brix greater than existing evapotranspiration-based controller in GH1 for the cultivation of Cantaloupe plant. The Kalman filter based-PID controller for capillary irrigated Mustard leaf in GH3, was able to optimally estimate and control the water supply depth resulting to better water productivity index of 16% and improvement of yield when compared with the fuzzy logic controller deployed in GH3 for benchmarking purpose. Also, the investigation of the computation complexity of the MPC and its suitability for control of irrigation system shows that the Laguerre network-based MPC demonstrated a better computational efficiency when benchmarked with a discrete linear quadratic regulator method for drip irrigation control via simulation. This thesis has contributed to the enhancement of monitoring and advanced control strategies for precision irrigation scheduling towards the realization of improved yield, water saving, and efficient use of fertilizer in agriculture.

#### **ABSTRAK**

Bidang Pertanian Tepat (PA) banyak menggunakan teknik pengairan titisan dan teknik pengairan kapilari berserabut untuk penjimatan air tanaman. Walau bagaimanapun, sebahagian besar sistem kawalan yang digunakan untuk penjadualan sistem pengairan titisan ini tidak mampu mengadaptasi terhadap perubahan dinamik persekitaran seperti kelembapan tanah, tanaman dan cuaca dalam masa nyata. Penyelidikan telah menunjukkan bahawa pengairan kapilari berserabut berpotensi untuk mendapatkan penjimatan air yang tinggi. Walau bagaimanapun, prestasi system ini masih rendah kerana penentuan kawalan mengenai kedalaman air bekalan (Δh) yang tidak tepat kepada zon pembasahan akar tanaman. Kemunculan dan kejayaan 'Internet of Things' (IoT) dan teori kawalan termaju digabungkan untuk pemantauan sistem yang lebih baik untuk mencapai objektif pengairan yang tepat. Dalam tesis ini, dua kajian kes iaitu strategi pengawal Model Ramalan (MPC) berdasarkan data untuk sistem pengairan titisan tanaman tembikai dan pengawal berasaskan penapis Kalman-PID untuk tanaman sawi yang disiram kapilari berserat dicadangkan. Ujikaji penanaman berasaskan IoT pada tanaman tembikai dan sawi dilakukan untuk pengumpulan data berkaitan kelembapan tanah, tumbesaran tanaman, dan cuaca daripada sistem pengairan titisan dan kapilari. Data yang dikumpul digunakan untuk mengembangkan model ramalan menggunakan kaedah Pengenalpastian Sistem (SI) menggunakan MATLAB untuk mendapatkan model yang tepat yang mewakili perubahan dinamik sistem bagi kedua-dua model tersebut. Model ramalan yang dikembangkan selanjutnya bagi tanaman tembikai digunakan untuk merancang MPC berasaskan jaringan Laguerre untuk pengurusan pengairan titisan masa nyata. Untuk menyiasat pengurusan sistem pengairan kapilari berserabut, strategi kawalan PID berasaskan penapis Kalman dikembangkan menggunakan model ramalan dari penanaman sawi. Pengawal berdasarkan model yang dikembangkan ini kemudian digabungkan dengan rangkaian alatan sensor menggunakan IoT untuk pemantauan waktu nyata terhadap parameter tanah, tanaman dan cuaca. Keberkesanan sistem kawalan berdasarkan model yang dirancang disimulasikan menggunakan Simulink dan diuji pada Raspberry Pi untuk mengesahkan prestasi pengawal yang dikembangkan. Tiga rumah hijau (GH1, GH2 dan GH3) digunakan dalam ujikaji penanaman untuk menguji prestasi sistem kawalan yang dihasilkan. Hasil pemodelan berdasarkan data untuk pengairan titisan menunjukkan bahawa model ARX mempunyai ketepatan yang lebih baik dari segi MSE iaitu 0.773 dengan anggaran ketepatan 91.31%, sementara model ruang-keadaan dengan anggaran ketepatan 92.3% dikenal pasti serupa dengan dinamik pengairan kapilari. Hasil ujikaji yang diperolehi menunjukkan prestasi yang lebih baik untuk sistem kawalan yang dicadangkan yang digunakan dalam GH2 dengan penjimatan sebanyak 30% untuk air dan baja, indeks produktiviti air 23 g/L, dan kemanisan buah 13 Brix lebih tinggi daripada pengawal berasaskan evapotranspirasi di GH1 untuk penanaman tanaman tembikai. Pengawal berasaskan penapis Kalman-PID untuk tanaman sawi mengunakan sistem kapilari dalam GH3, dapat menganggarkan dan mengawal kedalaman air bekalan (Δh) secara optimum sehingga menghasilkan indeks produktiviti air yang lebih baik sehingga 16% dan peningkatan hasil jika dibandingkan dengan pengawal logik fuzzy yang digunakan di GH3 sebagai penanda aras. Juga, penyiasatan kerumitan pemprosesan MPC dan kesesuaiannya untuk mengendalikan sistem kawalan pengairan menunjukkan bahawa MPC berasaskan rangkaian Laguerre menghasilkan kecekapan pemprosesan yang lebih baik apabila dibandingkan dengan kaedah pengatur Linear Kuadratik Diskret untuk kawalan pengairan titisan melalui simulasi. Tesis ini telah menyumbang kepada peningkatan strategi pemantauan dan pengendalian lanjutan untuk penjadualan pengairan yang tepat ke arah meningkatkan hasil pertanian, penjimatan air dan penggunaan baja yang lebih baik.

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DLQR - Discrete Linear Quadratic Regulator

GH - Greenhouse

IAE - Integral Absolute Error

IASE - Integral Absolute Square Error

ANOVA - Analysis of Variance

UV - Ultra Violet

TWU - Total Water Use

WPI - Water Productivity Index

DMPC - Discrete Model Predictive Control

NDVI - Normalized Difference Vegetation Index

BP - Back Propagation

ES - Expert System

EC - Electro Conductivity

POR - Peak Overshoot Ratio

DR - Decay Ratio

TDR - Time Domain Reflectometry

VWC - Volumetric Water Content

GSM - Global System for Mobile Communication

ISFET - Ion-Sensitive Field-Effect Transistor

PH - Potential Hydrogen

UAV - Unmanned Aerial Vehicles

CMOS - Complementary Metal Oxide Semi Conductor

LAI - Leaf Area Index

PAR - Photosynthetically Active Radiation

PWM - Pulse-Width Modulated

RTC - Real-Time Clock

RFID - Radio Frequency Identification Device

SSID - Service Set Identifier

HTTP - Hypertext Transfer Protocol

RSSI - Received Signal Strength Indication

ICT - Information Communication Technology

DSS - Decision Support System

LWPA - Low Power Wide Area

LoRa - Long Range

TDR - Time Domain Reflectometry

FAO - Food Agriculture Organization

RTC - Real-Time Clock

DC - Direct Current

AC - Alternating Current

SVM - Support vector machines

TSDI-ES - Technical Specification of Drip Irrigation-Expert System

ELM - Extreme Machine Learning

IGA - Improved Genetic Algorithm

SMLA - Shark Machine Learning Algorithm

GAPSO - Genetic Algorithm Particle Swarm Optimization

ADSS - Adaptive Decision Support System

LEPA - Low Energy Precision Application

SS-VRI - Site-Specific Variable Rate Irrigation

WS - Weather Station

MIMO - Multi-Input Multi-Output

GPC - Generalized Predictive Control

KNN - K Nearest Neighbour

SVR - Support Vector Regression

TWU - Total Water Use

MV. Manipulated Variable

 $t_s$  - Settling time

d Delay

Ho - Null hypothesis

ET<sub>0</sub> - Reference evapotranspiration (mm day<sup>-1</sup>)

 $R_n$  - Soil surface solar radiation at the crop surface (MJ m<sup>-2</sup> day<sup>-1</sup>)

U<sub>2</sub> - Speed of the wind measured at 2m height (ms<sup>-1</sup>)

*T* - Daily mean temperature of the air

G - Soil heat flux density(MJ m<sup>-2</sup> day<sup>-1</sup>)

 $e_s - e_a$  - Saturation vapour pressure deficit (kPa)

γ - Psychrometric constant (kPa <sup>0</sup>C<sup>-1</sup>)

- Gradient of the pressure curve (kPa <sup>0</sup>C<sup>-1</sup>)

 $F_T$  - F Statistics

 $MS_E$  - Mean Square for Error

 $MS_T$  - Mean Square for Treatment

ESS - Error for sum of square

df(e) - Error for the degree of freedom

*TSS* - Total sum of square

TrSS - Treatment sum of square

 $Y_{ij}$  - Grand mean

- Water Supply Depth

R<sup>2</sup> - Regression Coefficient

- Confidence Level ∝

- Inverse *z*-transform

ζ - Reference Trajectory

 $R_f$  - Predicted Output  $Y_{Pr}$  - Predicted Output

Δ*U* - Optimal Control Signal

 $EI_{max}$  - Effective Irrigation Effort

δ - Dirac delta function

a - Scaling factor

*L*(*k* - Discrete-time Laguerre functions

*I(k)* - Impulse Response

χ - Chi

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In a conventional irrigation system, farmers apply uniform irrigation across every part of the farm without considering the variabilities on the field and the water need for the crop. Therefore, this method has a lesser water-saving capability and can cause over-irrigation in some parts of the farm while other parts are under irrigated which often leads to water stress on the plant (Al-Karadsheh *et al.*, 2002; Munoth *et al.*, 2016; Li *et al.*, 2018). Also, most of the commercial irrigation controllers available in the market are pre-programmed to supply water at predefined intervals which offer fixed irrigation scheduling based on empirical knowledge of dynamics of weather variables, as well as soil and plant characteristics (Lozoya, Mendoza, Mejía, *et al.*, 2014). Since conventional irrigation systems often result to insufficient water supply to plant which causes yield loss and plants wilting, while too much water supply will result in wasted water and root disease, there is need to adopt a precision irrigation concept with advanced control strategies for optimal irrigation scheduling, water-saving, and better crop yield.

Drip and capillary irrigation is often practiced irrigation methods, which has potential for high water saving, but suffers a lot of operational and environmental problems. Drip irrigation is one of the surface irrigation methods which supplies water slowly through narrow emitter tubes to provide water to the soil near the plant roots (Seyfi and Rashidi, 2007). While fibrous capillary is subsurface irrigation that works based on the action of gradually supplying water from source directly to the root area by through a capillary medium using a negative pressure. One of the major challenge to achieve precise management of both irrigation methods is the disturbance in terms of water loss associated with the process and the need to compensate for it. The disturbance may include change in irrigation water flow, air and canopy temperature, water loss for soil and plant etc., and may lead to undesirable consequences on plant performance. For example, an abrupt increase or decrease in temperature and water loss in a tropical environment may have severe implications on the yield, if there is no proper real time monitoring and control of water resources to effectively manage such environmental effect. There is therefore need to sense and monitor crop response to water deficit often caused by disturbance due to water loss, in order to precisely irrigate the plants cultivated using both irrigation methods.

Precision irrigation is the integration of information, communication, and control technologies in the irrigation process to obtain optimal usage of water resources while minimising environmental impact (Shibusawa, 2001; Zacepins et al., 2012). Precision irrigation takes into account the spatial and temporal soil variation, soil structure and hydraulic properties, plant responses to water deficit, changing weather variables through effective monitoring via internet of things (IoT), to make better irrigation decisions that has the potential to help achieve high water saving and improved yield (Bitella et al., 2014; Capraro et al., 2018). Precision irrigation is an excellent water-saving technique for maximising yield and providing water at the correct location based on the water needs of the plant (Evett et al., 2009; Smith and Baillie, 2009; Niu et al., 2015). Also implied is the idea that the system will be managed to achieve a specific target by aiding the delivery of nutrient and water directly to the roots of each plant and keeping the soil moisture at optimal levels to eliminate surface run-off and deep percolation as the design process is conducted based on the ability of the soil to absorb water and the amount of crop water demand (Daccache et al., 2015). Therefore, this method results in increased productivity and improved quality of yield while ensuring maximum water use efficiency (Tropea, 2014). However, to provide efficient precision irrigation, the integration of the internet of things (IoT) for data acquisition as well as monitoring, control theory, and decision support technologies ought to be considered in irrigation management (Smith et al., 2010; Pham and Stack, 2018; Zamora-izquierdo et al., 2018).

This research focuses on advance monitoring and predictive control strategies for precision irrigation with the integration of IoT based irrigation monitoring methods. Control theory is an aspect of engineering and mathematics which deals with the dynamical behaviour of systems. In the context of precision irrigation, control is the ability to reallocate inputs and adjustment of irrigation management according to the crop response deficit while ensuring optimal water-saving and mitigating the effects of disturbance and uncertainties (De Baerdemaeker, 2000; Smith and Baillie, 2009). Therefore, in most cases, there will be a need to sense the response of a plant to the applied water at a scale appropriate for management, decide for improved irrigation using both the real-time and historical information for subsequent irrigation applications at a proper spatial level (Shashi *et al.*, 2017). Therefore, in this thesis, an improved monitoring system for soil, plant, and weather variables is proposed for both

drip and fibrous capillary irrigation experiments. The data collected using the IoT framework is used for data driven modelling. Also, the models were further used to design more advanced controllers for optimal irrigation decisions and water saving.

#### 1.2 Problem Statement

The significant losses in agriculture are mostly due to low-efficiency irrigation control and inaccurate weather monitoring and prediction methods. It is desirable to irrigate to meet specific plant water demands at the right time and volume while avoiding over and under irrigation. Excessive irrigation often affects plants health, have negative environmental impact and often results in high water and energy usage. Most of the commercial automated irrigation systems for drip irrigation are preprogramed to water at specific time intervals and apply a fixed irrigation volume, hence this method cannot provide crop water need with the changing dynamics of soil, plant and weather conditions. A number of these systems are also programmed to irrigate after a predefined soil moisture threshold is reached. Due to their open-loop structure, these methods may not guarantee optimum irrigation scheduling decisions resulting in suboptimal plant health and low efficiency in water use. As a result, the overall system may not be robust to external disturbance in terms of actual evapotranspiration and other environmental factors.

Irrigation management for Cantaloupe plant cultivation are mostly based on empirical or heuristic knowledge. Typically, drip irrigation strategies for Cantaloupe cultivation are often carried out by farmers in total ignorance of the actual soil water content, weather, as well as plant consideration. Such strategies are called open-loop irrigation strategy. The main drawback of open-loop irrigation for Cantaloupe is the difficulty in delivering the precise irrigation amount, which could lead to either a waste of irrigation water or insufficient watering which can cause root asphyxiation leading to root rot, low yield and fruit quality or even plant death. Due to the inefficiency of open-loop irrigation and the emerging water crisis, there has been an increasing interest in the research of model based closed-loop irrigation strategy.

- To model the dynamics of the soil-plant-weather system through system identification using data from IoT-based experimental cultivations of Cantaloupe plant.
- To model the dynamics of the soil-plant-weather system through system identification using data from IoT-based experimental cultivations of capillary irrigated Mustard leaf.
- iii. To design a MPC and Laguerre network based MPC controller for drip irrigation and implement it experimentally on Raspberry Pi for Cantaloupe plant cultivation.
- iv. To design a Kalman filter-PID controller for water supply depth ( $\Delta h$ ) of fibrous capillary irrigation and deploy on Raspberry Pi for Mustard leaf cultivation experiment.

### 1.4 Scope

The main scopes in conducting this research which is stated as follows:

- i. Only three greenhouses are selected for the experimental work, namely GH1 and GH2 for drip irrigation, and GH3 for fibrous capillary irrigation.
- ii. Matlab/Simulink and Python software are used for modelling and simulation of all the algorithms.
- iii. The model structures use to fit the data are ARX, ARMX, SS, and BJ.
- iv. Vertical and horizontal interface are used for the capillary irrigation system.
- v. Cantaloupe plant and Mustard leaf plant are selected as test crops for this study.
- vi. Liquid fertilizer (AB) is used to aid the plant growth.

### 1.5 Contribution of the Research Work

In this thesis, a data-driven predictive model is used to design an optimal irrigation control for drip and fibrous capillary irrigation systems in achieving watersaving agriculture. The real-time implementation of the model predictive irrigation control algorithm on the target hardware and integration of IoT monitoring will be a

novel approach to improve water use efficiency and crop yield. Specifically, the contribution of this research are as follows:

## (a) Development of different predictive models to represent the changing dynamics soil, plant and weather

An open loop and improved IoT based cultivation experiment on drip irrigated Cantaloupe and fibrous capillary irrigated Mustard leaf was carried out for data collection of soil, plant and weather variables. Through system identification, a state space model structure was use to fit the experimental input and output data. This results to a state space model that captured the dynamics of the plant.

## (b) Formulation of control law based on MPC and Laguerre networks MPC for drip irrigation system.

Using the predictive model formulated, an MPC and Laguerre networks MPC for drip irrigations was formulated, simulated, and implemented on Raspberry Pi in a greenhouse experimental cultivation for high water saving and improved yield. The MPC controller was benchmarked experimentally with a model base automatic evapotranspiration (ET) controller.

# (c) Improved management of water supply depth for fibrous capillary irrigation using Kalman filter-PID controller

Toward ensuring an extreme water saving Agriculture, a Kalman filter-PID control strategy for determining optimal  $\Delta h$  to ensure enhanced wetting of the root zone of plant was tested through simulation and bench marked experimentally with a fuzzy logic controller.

### 1.6 Thesis Organization

This thesis is organized in six chapters. Chapter 1 gives the overview of the whole thesis. It contains a general background of the study, the problem statement with the existing research gaps, the set objectives, the scopes of the work and limitations, and contribution of the research.

Chapter 2 presents a comprehensive and critical literature review of the theoretical background on precision irrigation concept, different irrigation system, monitoring and advanced control strategies for precision irrigation. The existing monitoring approach, issues associated with different irrigation method were highlighted.

Chapter 3 proposes the methodology used to achieve the objectives of this thesis in phases. The adopted methodology for the modelling presented in each of the phases are comprehensively discussed. In the monitoring phase, the IoT implementation for data collection and processing were equally presented. This is followed by the explanation of dynamic modelling for soil moisture prediction. The experimental performance comparison between drip and capillary irrigation systems for Cantaloupe plant cultivation is also presented.

Chapter 4 presents more detailed methodology on the formulation of control law for controller design for both drip irrigation. It also discusses the proposed controller as well as the implementation of the developed models for the design of both data driven MPC in Simulink and Laguerre networks based MPC controller on Raspberry Pi for Cantaloupe plant cultivation.

Chapter 5 discusses the design and implementation of Kalman filter-PID controller for fibrous capillary irrigation management for the cultivation of Mustard leaf is carried out.

Chapter 6 contains the results of the predictive modelling and model predictive controller design as well as implementation for both drip and capillary irrigation experiments. Finally, the results of the experimental performance comparison between drip and capillary irrigation systems for Cantaloupe plant cultivation is also explained.

Chapter 7 draws the overall conclusions of the remarkable achievements of the research. In addition, recommendations for future studies is presented. This thesis is closed with list of references, appendices as well as list of publications during the period of the research.

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## **Appendix C** List of publications

## **List of Published Journals**

- Abioye, Abiodun Emmanuel, Mohammad Shukri Zainal Abidin, Muhammad Naveed Aman, Mohd Saiful Azimi Mahmud, Salinda Buyamin, (2020) 'A Model Predictive Controller for Precision Irrigation using Discrete Laguerre Networks' Elsevier B.V., 181, p. 105953. Computer and Electronics in Agriculture). (Published – IF: 3.858, Q1, ISI)
- Abioye, Abiodun Emmanuel, Mohammad Shukri Zainal Abidin, Mohd Saiful Azimi Mahmud, Muhammad Khairie Idham Abd R., Salinda Buyamin, Mohamad Hafis Izran Ishak, Abdulrahaman O., Onotu Patrick. (2020) 'A Review on Monitoring and Advanced Control Strategies for Precision Irrigation' Computer and Electronics in Agriculture, Elsevier, 173, p. 105441 (Published IF: 3.858, Q1, ISI)
- 3. Abioye, Abiodun Emmanuel, Mohammad Shukri Zainal Abidin, Mohd Saiful Azimi Mahmud, Muhammad Khairie Idham Abd R Abdulrahaman O. Ona Denis Ijike. (2020) 'IoT Monitoring and Data-Driven Modelling of Drip Irrigation System for Mustard Leaf Cultivation Experiment' Information Processing in Agriculture, Elsevier. (Indexed by Scopus)
- 4. Abioye Abiodun Emmanuel, Mohammad Shukri Zainal Abidin, Mohd Saiful Azimi Mahmud, Salinda Buyamin, Mohamad Hafis Izran Ishak, Muhammad Khairie Idham Abd Rahman, Umar Zangina. (2020) 'Performance Comparison of Experimental IoT Based Drip and Fibrous Capillary Irrigation Systems in the Cultivation of Cantaloupe Plant' Advances in Agricultural & Food Research, vol. 1, no. 2. (Non-Indexed Journal)

## **Presented Conference Papers:**

- Abioye Abiodun Emmanuel, Mohammad Shukri Zainal Abidin, Mohd Saiful Azimi Mahmud, Salinda Buyamin, Mohamad Hafis Izran Ishak, Muhammad Khairie Idham Abd Rahman, Umar Zangina. Performance Comparism of Experimental IoT Based Drip and Fibrous Capillary Irrigation Systems in the Cultivation of Cantaloupe Plant. Malaysia Society of Agricultural and Engineers Conference 2020. Kualar Lumpur, June 2020.
- Abioye Abiodun Emmanuel, Mohammad Shukri Zainal Abidin, Oborkhale
  L.I., Mohd Saiful Azimi Mahmud, Muhammad Khairie Idham Abd Rahman,
  Amadi Amadi O. Advance Monitoring and Control Strategy for Fibrous
  Capillary Irrigation System towards Water-Saving Agriculture- Second
  International Engineering Conference (IECON 2019) College of Engineering

and Engineering Technology, Michael Okpara University of Agriculture, Umudike. Nigeria. pp. 240-253.

## **Collaborative Research Papers**

- Muhammad Khairie Idham Abd Rahman, Mohammad Shukri Zainal Abidin, Mohd Saiful Azimi Mahmud, Salinda Buyamin, Mohamad Hafis Izran Ishak, Abioye Abiodun Emmanuel. Advancement of a smart fibrous capillary irrigation management system with an Internet of Things integration-International Conference on Electrical, Electronic, Communication and Control Engineering (ICEECC2018)
- Mohd Saiful Azimi Mahmud\*, Mohamad Shukri Zainal Abidin, Abioye Abiodun Emmanuel and Hameedah Sahib Hasan Robotics and Automation in Agriculture: Present and Future Applications, Applications of Modelling and Simulation pp130-140
- Mohd Saiful Azimi Mahmud, Mohamad Shukri Zainal Abidin, Salinda Buyamin, Abioye Abiodun Emmanuel & Hameedah Sahib Hasan; Multiobjective Route Planning for Underwater Cleaning Robot in Water Reservoir Tank, Journal of Intelligent & Robotic Systems.